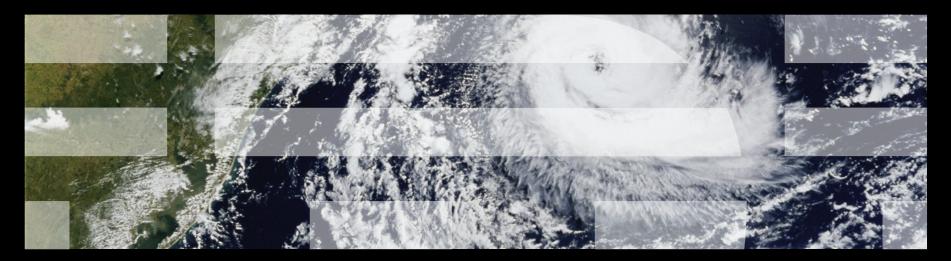
Paul E. McKenney, IBM Distinguished Engineer, Linux Technology Center 3 June 2013



# What Is RCU?

## Distributed OS Lecture, TU Dresden





#### Overview

- Mutual Exclusion
- Example Application
- Performance of Synchronization Mechanisms
- Making Software Live With Current (and Future) Hardware
- Implementing RCU
- RCU Grace Periods: Conceptual and Graphical Views
- Performance
- RCU Area of Applicability
- Summary



# **Mutual Exclusion**



#### **Mutual Exclusion**

"We simply do not have a synchronization mechanism that can enforce mutual exclusion"

True or false?



# **Example Application**



#### **Example Application**

- Schrödinger wants to construct an in-memory database for the animals in his zoo (example in upcoming ACM Queue)
  - -Births result in insertions, deaths in deletions
  - -Queries from those interested in Schrödinger's animals
  - -Lots of short-lived animals such as mice: High update rate
  - -Great interest in Schrödinger's cat (perhaps queries from mice?)



## **Example Application: Schrödinger's Cat**



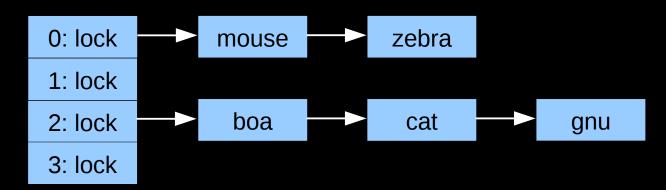
Author: ADA&Neagoe This file is licensed under the Creative Commons Attribution-ShareAlike license versions 3.0, 2.5, 2.0, and 1.0. © 2009 IBM Corporation



## **Example Application**

- Schrödinger wants to construct an in-memory database for the animals in his zoo (example in upcoming ACM Queue)
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Simple approach: chained hash table with per-bucket locking

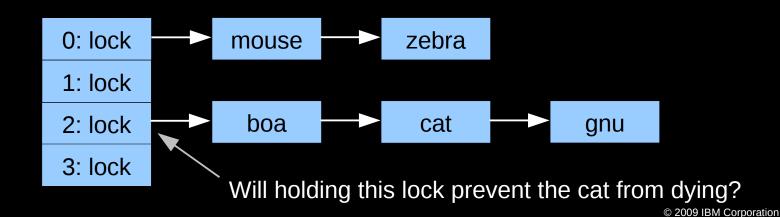




## **Example Application**

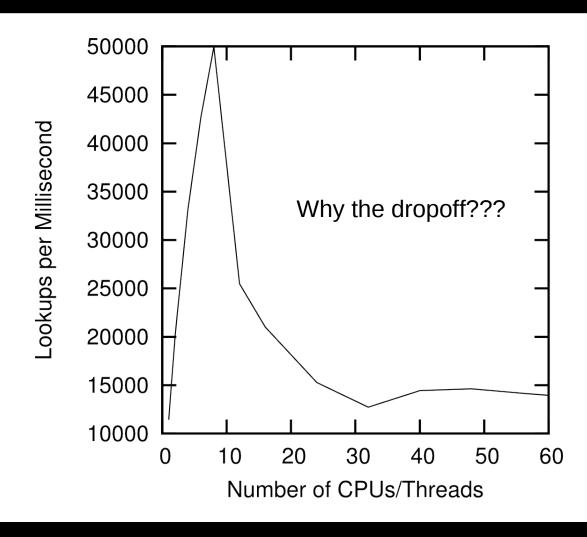
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Simple approach: chained hash table with per-bucket locking





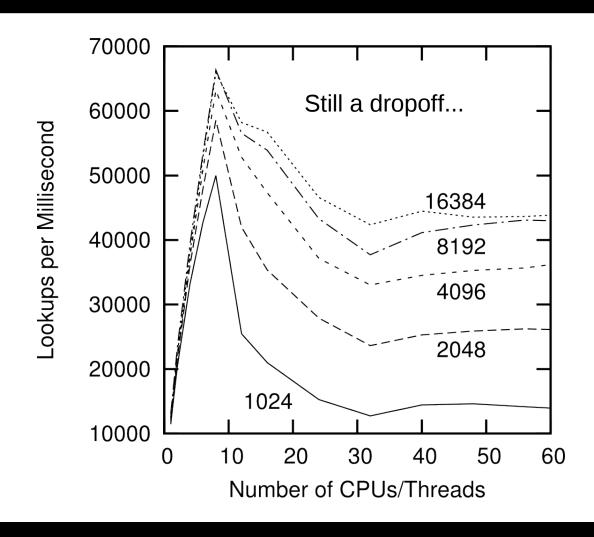
#### **Read-Only Bucket-Locked Hash Table Performance**



2GHz Intel Xeon Westmere-EX, 1024 hash buckets



## **Varying Number of Hash Buckets**



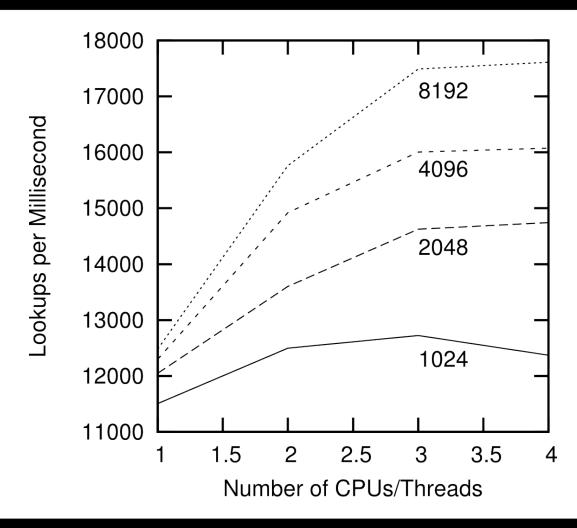


#### **NUMA Effects???**

- /sys/devices/system/cpu/cpu0/cache/index0/shared\_cpu\_list: -0,32
- /sys/devices/system/cpu/cpu0/cache/index1/shared\_cpu\_list: -0,32
- /sys/devices/system/cpu/cpu0/cache/index2/shared\_cpu\_list: -0,32
- /sys/devices/system/cpu/cpu0/cache/index3/shared\_cpu\_list: -0-7,32-39
- Two hardware threads per core, eight cores per socket
- Try using only one CPU per socket: CPUs 0, 8, 16, and 24



### **Bucket-Locked Hash Performance: 1 CPU/Socket**



2GHz Intel Xeon Westmere-EX: This is not the sort of scalability Schrödinger requires!!!

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## **Performance of Synchronization Mechanisms**



## **Performance of Synchronization Mechanisms**

16-CPU 2.8GHz Intel X5550 (Nehalem) System

Operation	Cost (ns)	Ratio
Clock period	0.4	1
"Best-case" CAS	12.2	33.8
Best-case lock	25.6	71.2
Single cache miss	12.9	35.8
CAS cache miss	7.0	19.4
Single cache miss (off-core)	31.2	86.6
CAS cache miss (off-core)	31.2	86.5
Single cache miss (off-socket)	92.4	256.7
CAS cache miss (off-socket)	95.9	266.4

And these are best-case values!!! (Why?)



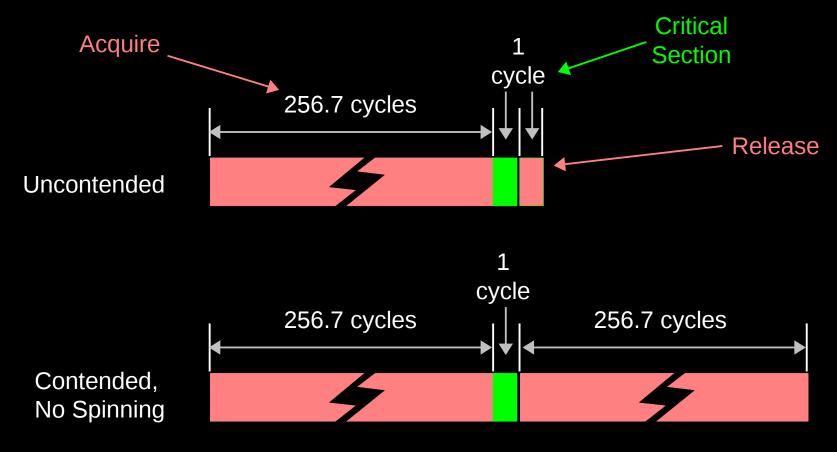
## Why All These Low-Level Details???

- Would you trust a bridge designed by someone who did not understand strengths of materials?
  - -Or a ship designed by someone who did not understand the steel-alloy transition temperatures?
  - -Or a house designed by someone who did not understand that unfinished wood rots when wet?
  - -Or a car designed by someone who did not understand the corrosion properties of the metals used in the exhaust system?
  - -Or a space shuttle designed by someone who did not understand the temperature limitations of O-rings?
- So why trust algorithms from someone ignorant of the properties of the underlying hardware???





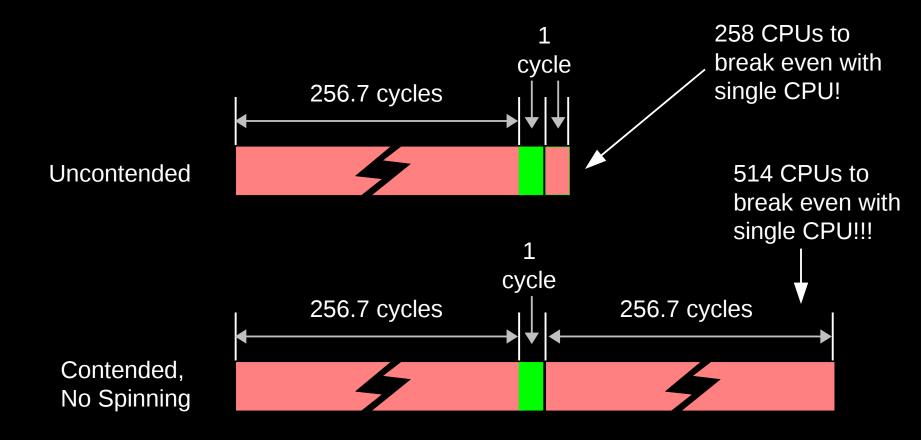
Single-instruction critical sections protected by multiple locks



So, what does this mean?

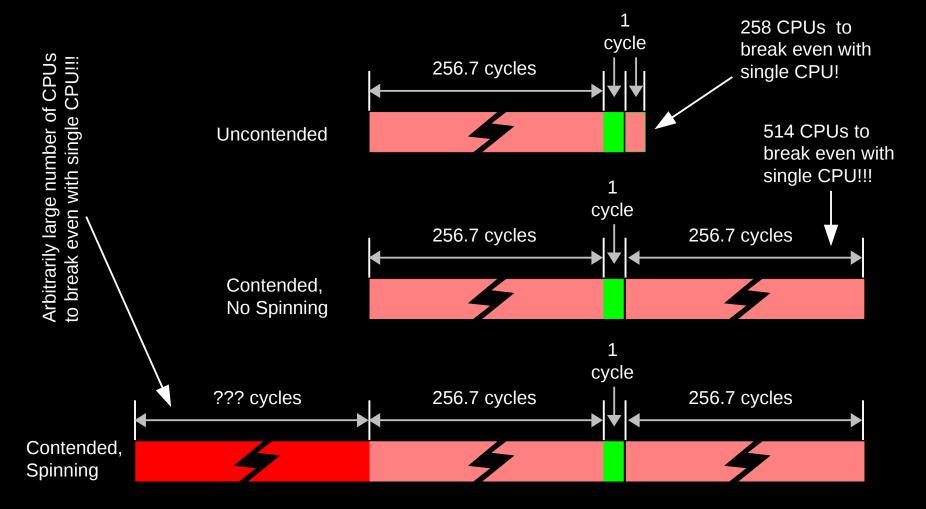


Single-instruction critical sections protected by multiple locks





Single-instruction critical sections protected by multiple locks

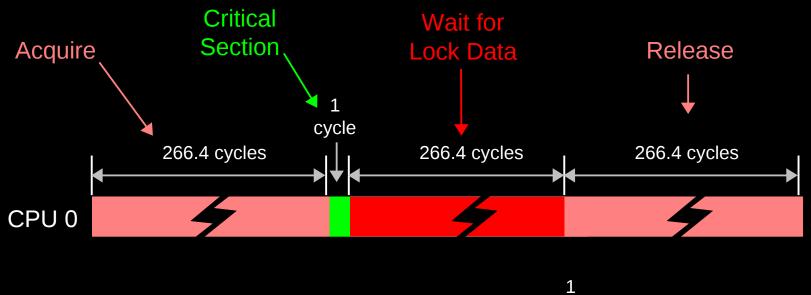


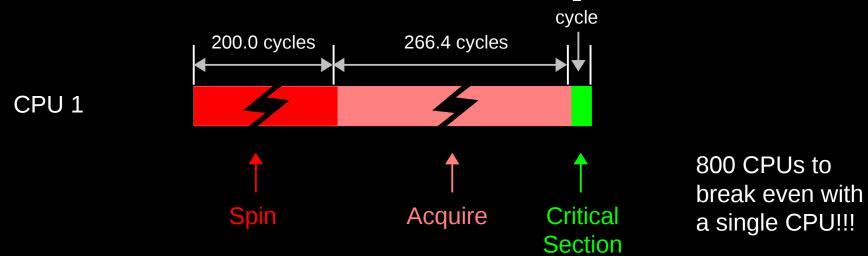


#### **Reader-Writer Locks Are Even Worse!**



#### **Reader-Writer Locks Are Even Worse!**



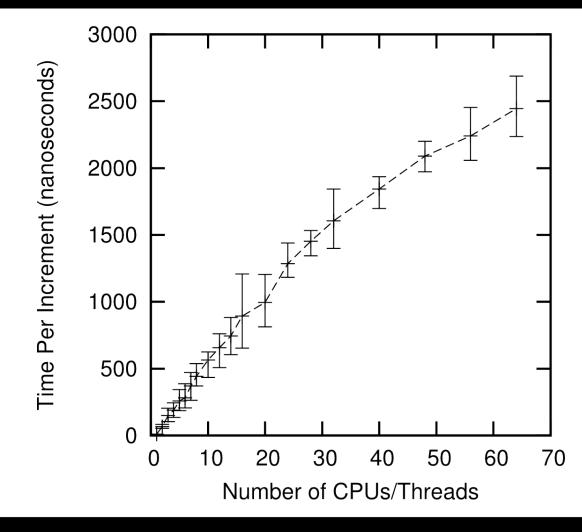




#### **But What About Scaling With Atomic Operations?**



## If You Think Single Atomic is Expensive, Try Lots!!!



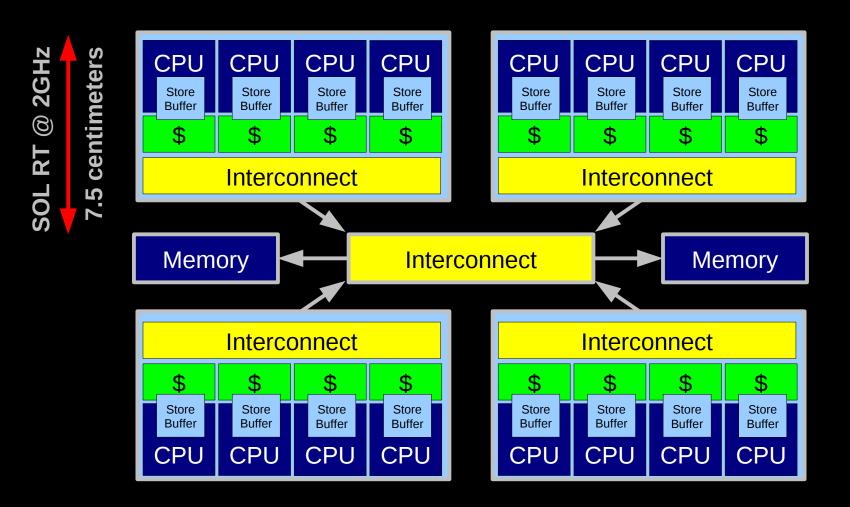
2GHz Intel Xeon Westmere-EX



# Why So Slow???



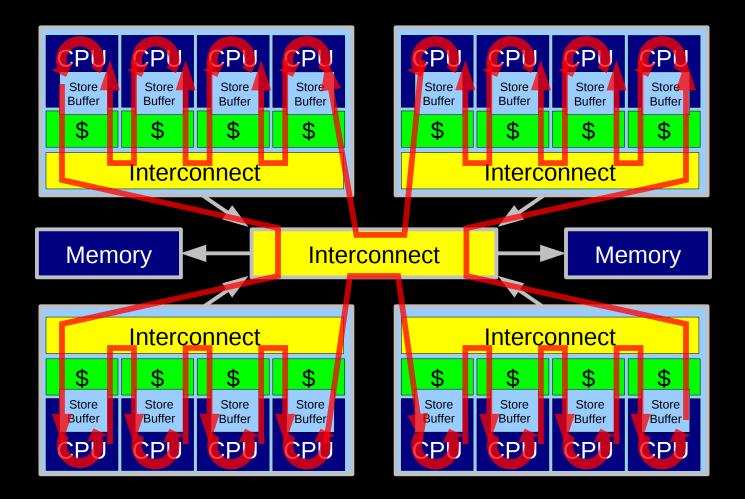
#### **System Hardware Structure and Laws of Physics**



Electrons move at 0.03C to 0.3C in transistors and, so lots of waiting. 3D???



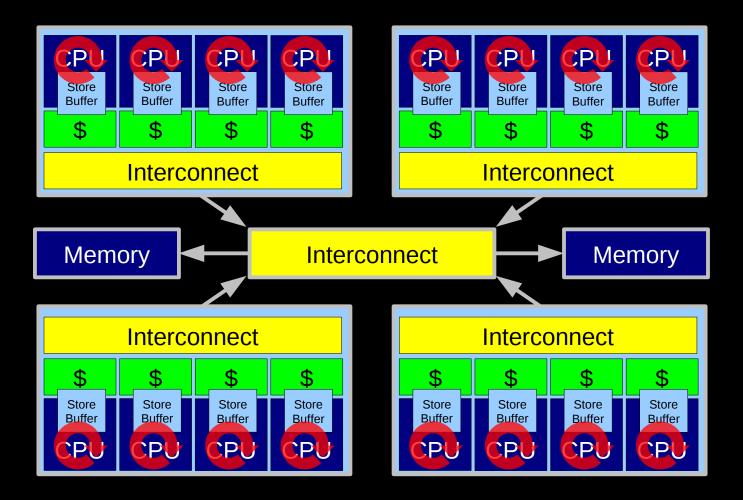
## **Atomic Increment of Global Variable**



Lots and Lots of Latency!!!



#### **Atomic Increment of Per-CPU Counter**



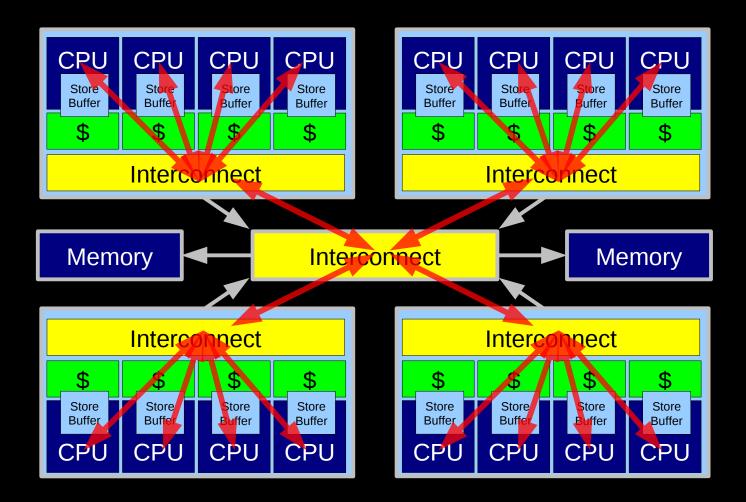
Little Latency, Lots of Increments at Core Clock Rate



#### **Can't The Hardware Do Better Than This???**



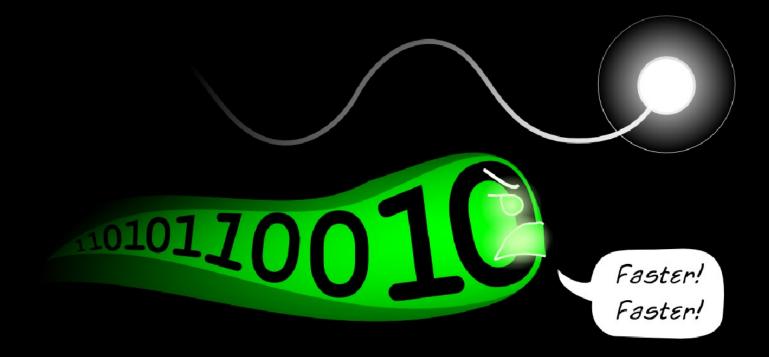
## **HW-Assist Atomic Increment of Global Variable**



SGI systems used this approach in the 1990s, expect modern micros to pick it up. Still not as good as per-CPU counters.

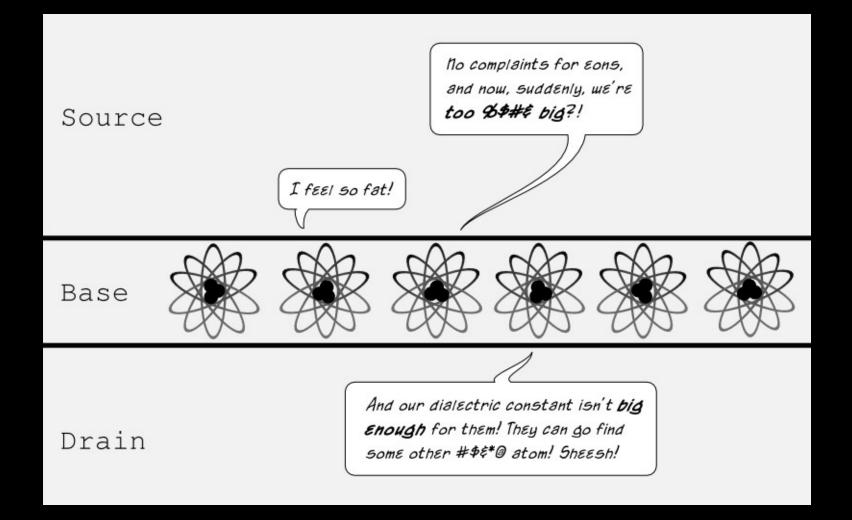


## **Problem With Physics #1: Finite Speed of Light**





#### **Problem With Physics #2: Atomic Nature of Matter**

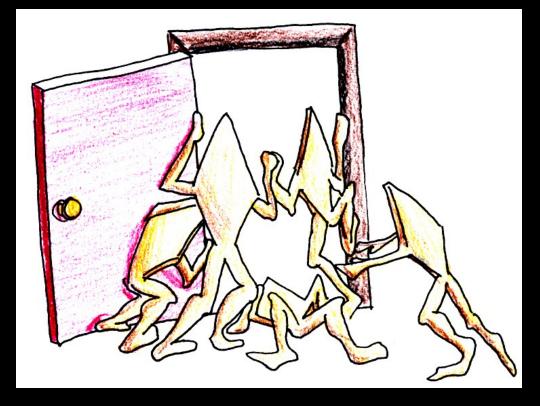




## How Can Software Live With This Hardware???



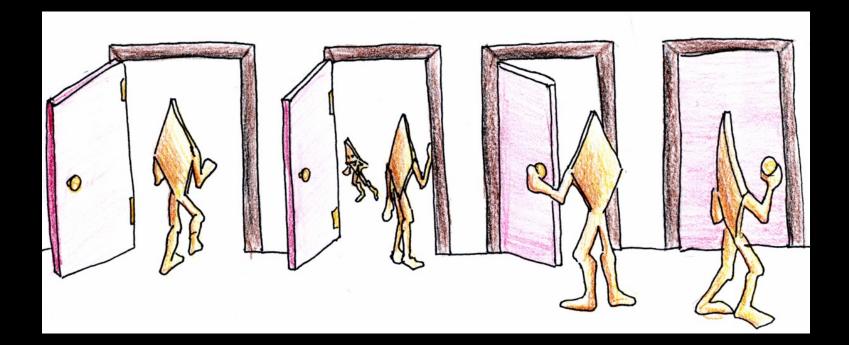
## **Design Principle: Avoid Bottlenecks**



Only one of something: bad for performance and scalability. Also typically results in high complexity.



## **Design Principle: Avoid Bottlenecks**



Many instances of something good! Avoiding tightly coupled interactions is an excellent way to avoid bugs. But NUMA effects defeated this for per-bucket locking!!!



# **Design Principle: Avoid Expensive Operations**

**Need to be here!** (Partitioning/RCU)

(but too bad about those poor writers...) 16-CPU 2.8GHz Intel X5550 (Nehalem) System

Operation	Cost (ns) Ratio
Clock period	0.4 1
"Best-case" CAS	<u>12.2</u> 33.8
Best-case lock	25.6 71.2
Single cache miss	12.9 35.8
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Heavily Single cache miss (off-	<b>core)</b> 31.2 86.6
optimized reader-writer CAS cache miss (off-co	ore) 31.2 86.5
lock might get Single cache miss (off-	socket) 92.4 256.7
here for readers (but too bad) CAS cache miss (off-so	ocket) 95.9 266.4

**Typical synchronization** mechanisms do this a lot



## **Design Principle: Get Your Money's Worth**

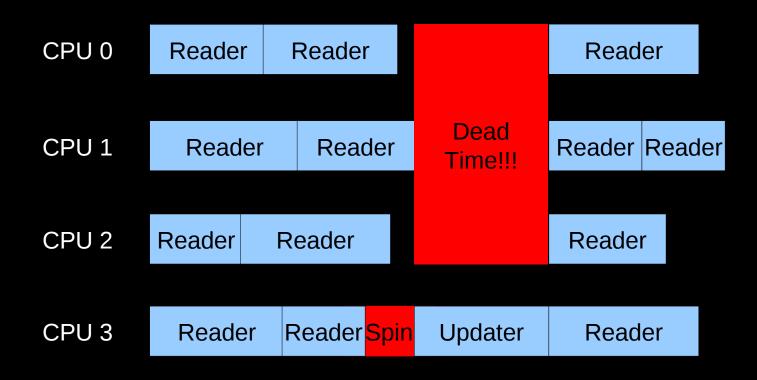
- If synchronization is expensive, use large critical sections
- On Nehalem, off-socket CAS costs about 260 cycles

   So instead of a single-cycle critical section, have a 26000-cycle critical section, reducing synchronization overhead to about 1%
- Of course, we also need to keep contention low, which usually means we want short critical sections

   Resolve this by applying parallelism at as high a level as possible
   Parallelize entire applications rather than low-level algorithms!

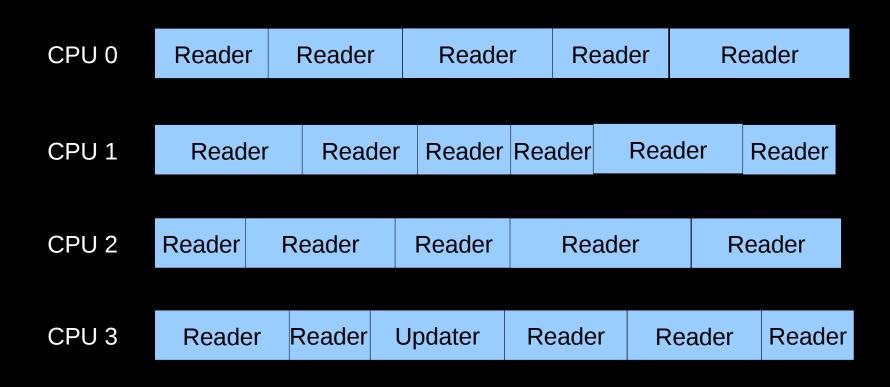


# **Design Principle: Avoid Mutual Exclusion!!!**





# **Design Principle: Avoiding Mutual Exclusion**



No Dead Time!



## **But How Can This Possibly Be Implemented???**



## Lightest-weight conceivable read-side primitives



# Lightest-weight conceivable read-side primitives -/\* Assume non-preemptible (run-to-block) environment. \*/ -#define rcu\_read\_lock() -#define rcu\_read\_unlock()



Lightest-weight conceivable read-side primitives

 -/\* Assume non-preemptible (run-to-block) environment. \*/
 -#define rcu\_read\_lock()
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 Best possible performance, scalability, real-time response, wait-freedom, and energy efficiency



Lightest-weight conceivable read-side primitives

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 -#define rcu\_read\_lock()
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- But how can these possibly be useful???



- Lightest-weight conceivable read-side primitives

   -/\* Assume non-preemptible (run-to-block) environment. \*/
   -#define rcu\_read\_lock()
   -#define rcu\_read\_unlock()
- Best possible performance, scalability, real-time response, wait-freedom, and energy efficiency
- But how can these possibly be useful???
- How can something that does not affect machine state be used as a synchronization primitive???



# What Is RCU?

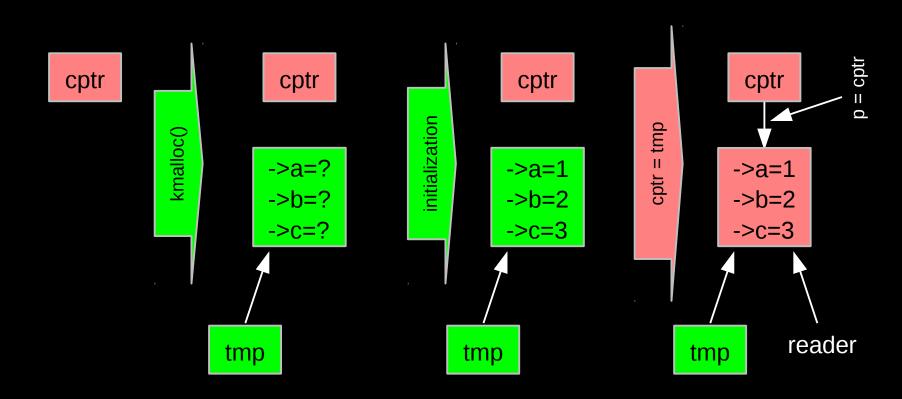
- Publishing of new data
- Subscribing to the current version of data
- Waiting for pre-existing RCU readers: Avoid disrupting readers by maintaining multiple versions of the data
  - -Each reader continues traversing its copy of the data while a new copy might be being created concurrently by each updater
    - Hence the name read-copy update, or RCU
  - Once all pre-existing RCU readers are done with them, old versions of the data may be discarded



# **Publication of And Subscription to New Data**

Key: 📕

Dangerous for updates: all readers can access Still dangerous for updates: pre-existing readers can access (next slide) Safe for updates: inaccessible to all readers





## Memory Ordering: Mischief From Compiler and CPU



## **Memory Ordering: Mischief From Compiler and CPU**

```
    Original updater code:

        p = malloc(sizeof(*p));

        p->a = 1;

        p->b = 2;

        p->c = 3;

        cptr = p;
    Original reader code:

        p = cptr;
```

```
foo(p->a, p->b, p->c);
```

Mischievous updater code: p = malloc(sizeof(\*p)); cptr = p; p->a = 1; p->b = 2; p->c = 3;

```
Mischievous reader code:
    retry:
    p = guess(cptr);
    foo(p->a, p->b, p->c);
    if (p != cptr)
        goto retry;
```



## Memory Ordering: Mischief From Compiler and CPU

```
Original updater code:
   p = malloc(sizeof(*p));
   p->a = 1;
   p - > b = 2;
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Original reader code:
   p = cptr;
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Mischievous updater code: p = malloc(sizeof(\*p)); cptr = p; p->a = 1; p->b = 2; p->c = 3;

```
retry:
p = guess(cptr);
foo(p->a, p->b, p->c);
if (p != cptr)
  goto retry;
```

But don't take *my* word for it on HW value speculation: http://www.openvms.compaq.com/wizard/wiz\_2637.html



## **Preventing Memory-Order Mischief**

```
•Updater uses rcu assign pointer() to publish pointer:
   #define rcu assign pointer(p, v) \
    ({ \
             smp wmb(); /* SMP Write Memory Barrier */ \
             (p) = (v); \setminus
   })
Reader uses rcu dereference() to subscribe to pointer:
   #define rcu dereference(p) \setminus
    ({ \
             typeof(p) p1 = (*(volatile typeof(p)*)\&(p)); \setminus
             smp read barrier depends(); \
             p1; \
   })
```

The Linux-kernel definitions are more ornate: Debugging code



## **Preventing Memory-Order Mischief**

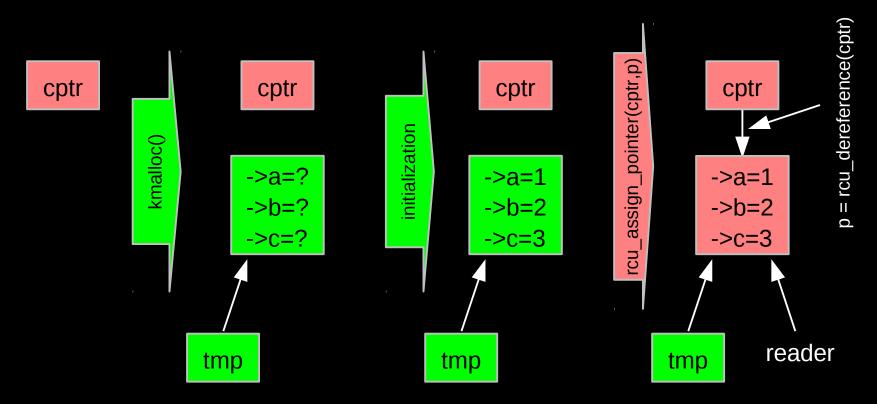
```
"Memory-order-mischief proof" updater code:
    p = malloc(sizeof(*p));
    p->a = 1;
    p->b = 2;
    p->c = 3;
    rcu_assign_pointer(cptr, p);
```

"Memory-order-mischief proof" reader code: p = rcu\_dereference(cptr); foo(p->a, p->b, p->c);



# **Publication of And Subscription to New Data**

Key: Dangerous for updates: all readers can access
 Still dangerous for updates: pre-existing readers can access (next slide)
 Safe for updates: inaccessible to all readers

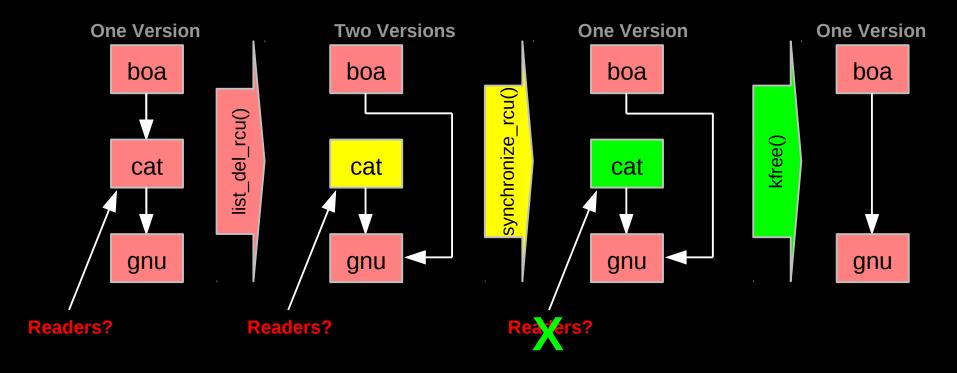


But if all we do is add, we have a big memory leak!!!



## **RCU Removal From Linked List**

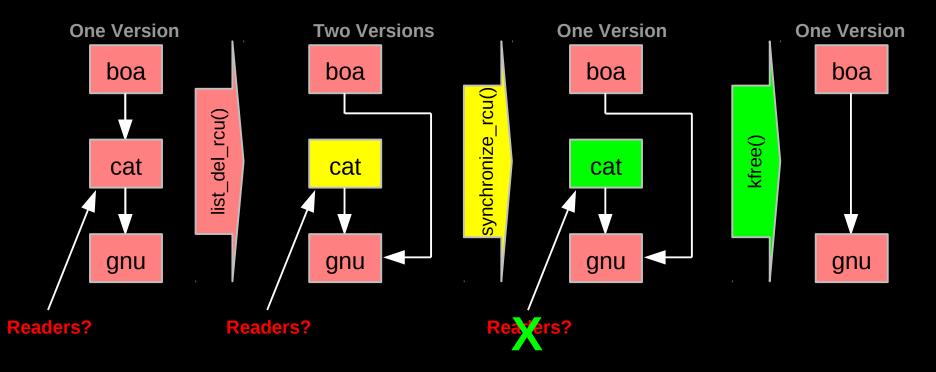
- Combines waiting for readers and multiple versions:
  - Writer removes the cat's element from the list (list\_del\_rcu())
  - Writer waits for all readers to finish (synchronize\_rcu())
  - Writer can then free the cat's element (kfree())





## **RCU Removal From Linked List**

- Combines waiting for readers and multiple versions:
  - Writer removes the cat's element from the list (list\_del\_rcu())
  - Writer waits for all readers to finish (synchronize\_rcu())
  - Writer can then free the cat's element (kfree())



But if readers leave no trace in memory, how can we possibly tell when they are done???



# How Can RCU Tell When Readers Are Done???



# How Can RCU Tell When Readers Are Done???

That is, without re-introducing all of the overhead and latency inherent to other synchronization mechanisms...



## **But First, Some RCU Nomenclature**

#### RCU read-side critical section

-Begins with rcu\_read\_lock(), ends with rcu\_read\_unlock(), and may contain rcu\_dereference()

#### Quiescent state

-Any code that is not in an RCU read-side critical section

#### Extended quiescent state

-Quiescent state that persists for a significant time period

#### RCU grace period

- Time period when every thread was in at least one quiescent state



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#### RCU grace period

- Time period when every thread was in at least one quiescent state

• OK, names are nice, but how can you possibly implement this???



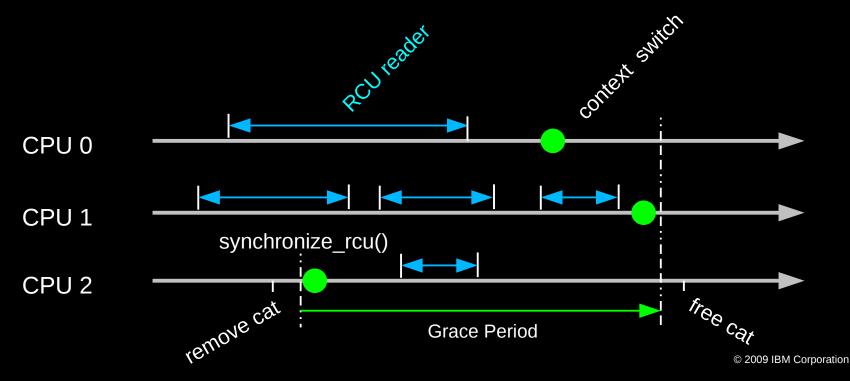
## Waiting for Pre-Existing Readers: QSBR

- Non-preemptive environment (CONFIG\_PREEMPT=n)
  - RCU readers are not permitted to block
  - Same rule as for tasks holding spinlocks



## Waiting for Pre-Existing Readers: QSBR

- Non-preemptive environment (CONFIG\_PREEMPT=n)
  - RCU readers are not permitted to block
  - Same rule as for tasks holding spinlocks
- CPU context switch means all that CPU's readers are done
- Grace period ends after all CPUs execute a context switch





# Synchronization Without Changing Machine State???

But rcu\_read\_lock() does not need to change machine state -Instead, it acts on the developer, who must avoid blocking within RCU read-side critical sections

 Or, more generally, avoid quiescent states within RCU read-side critical sections



# Synchronization Without Changing Machine State???

But rcu\_read\_lock() does not need to change machine state -Instead, it acts on the developer, who must avoid blocking within RCU read-side critical sections

- Or, more generally, avoid quiescent states within RCU read-side critical sections
- RCU is therefore synchronization via social engineering



# Synchronization Without Changing Machine State???

But rcu\_read\_lock() does not need to change machine state

- Instead, it acts on the developer, who must avoid blocking within RCU read-side critical sections
- Or, more generally, avoid quiescent states within RCU read-side critical sections
- RCU is therefore synchronization via social engineering
- Just as is the case for most synchronization mechanisms
  - -"Avoid data races"
  - "Protect specified variables with the corresponding lock"
  - "Access shared variables only within transactions"



# **Toy Implementation of RCU: 20 Lines of Code**

```
    Read-side primitives:
    #define rcu_read_lock()
    #define rcu_read_unlock()
    #define rcu_dereference(p) \
    ({ \
        typeof(p) _p1 = (*(volatile typeof(p)*)&(p)); \
        smp_read_barrier_depends(); \
        _p1; \
})
```

Update-side primitives

```
#define rcu_assign_pointer(p, v) \
    ({ \
            smp_wmb(); \
            (p) = (v); \
    })
void synchronize_rcu(void)
{
            int cpu;
            for_each_online_cpu(cpu)
                run_on(cpu);
}
```



# **Toy Implementation of RCU: 20 Lines of Code**

```
• Read-side primitives:
    #define rcu_read_lock()
    #define rcu_read_unlock()
    #define rcu_dereference(p) \
    ({ \
        typeof(p) _p1 = (*(volatile typeof(p)*)&(p)); \
        smp_read_barrier_depends(); \
        _p1; \
})
```

Update-side primitives

```
#define rcu_assign_pointer(p, v) \
    ({ \
            smp_wmb(); \
            (p) = (v); \
    })
void synchronize_rcu(void)
    {
            int cpu;
            for_each_online_cpu(cpu)
                run_on(cpu);
            }
}
```

}

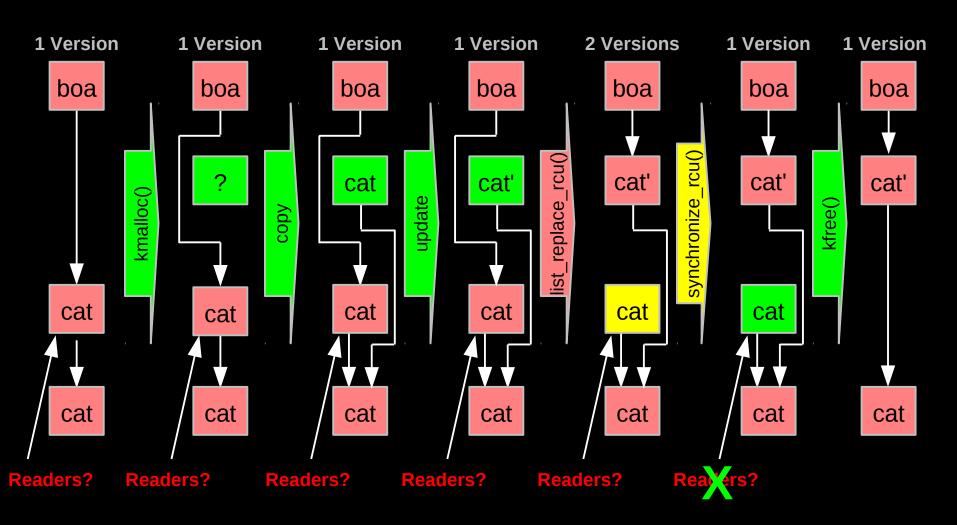
Only 9 of which are needed on SC systems... And some people still insist that RCU is complicated... ;-)



# **Complex Atomic-To-Reader Updates**



# **RCU Replacement Of Item In Linked List**





## **RCU Grace Periods: Conceptual and Graphical Views**



## **RCU Grace Periods: A Conceptual View**

#### RCU read-side critical section

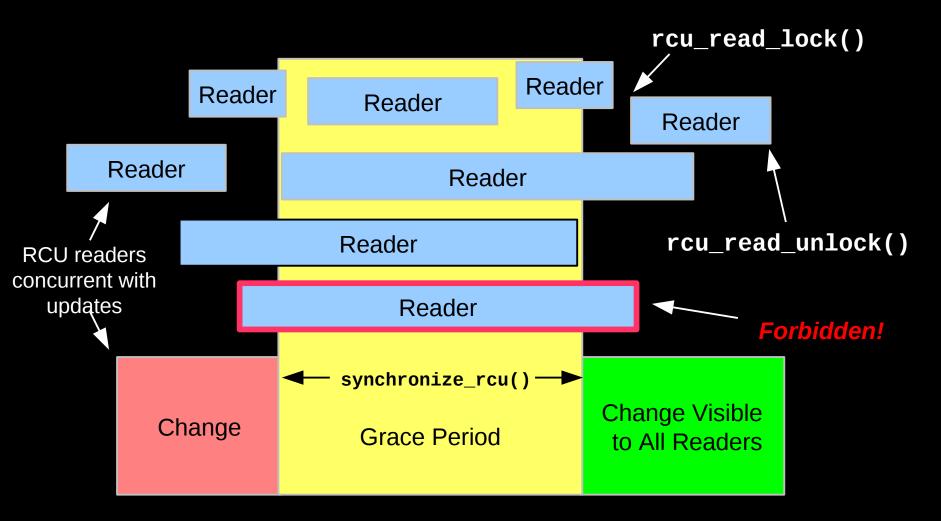
- -Begins with rcu\_read\_lock(), ends with rcu\_read\_unlock(), and may contain rcu\_dereference()
- Quiescent state
  - -Any code that is not in an RCU read-side critical section
- Extended quiescent state
  - -Quiescent state that persists for a significant time period

#### RCU grace period

- Time period when every thread is in at least one quiescent state
- Ends when all pre-existing readers complete
- Guaranteed to complete in finite time iff all RCU read-side critical sections are of finite duration
- But what happens if you try to extend an RCU read-side critical section across a grace period?



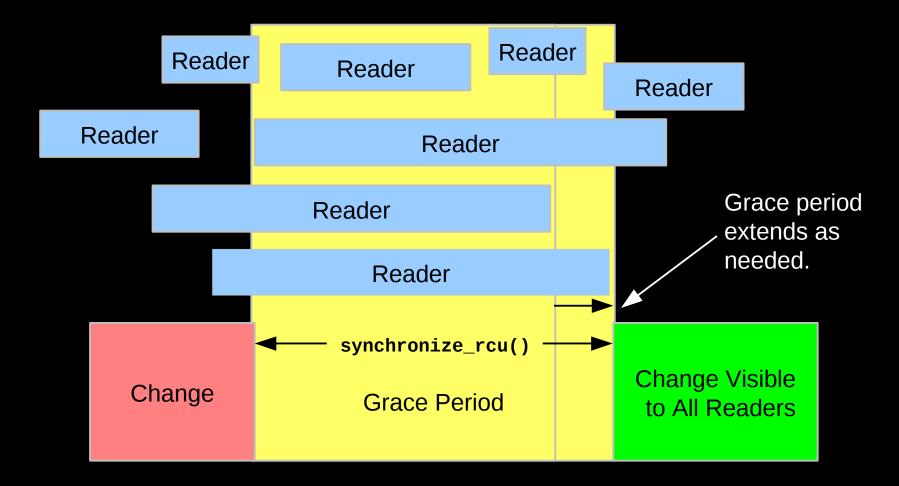
## **RCU Grace Periods: A Graphical View**



So what happens if you try to extend an RCU read-side critical section across a grace period?



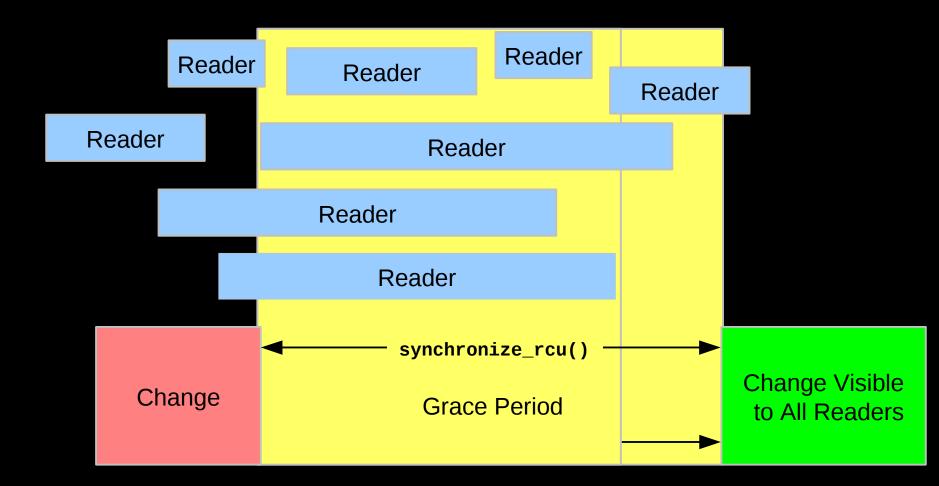
# **RCU Grace Period: A Self-Repairing Graphical View**



A grace period is not permitted to end until all pre-existing readers have completed.



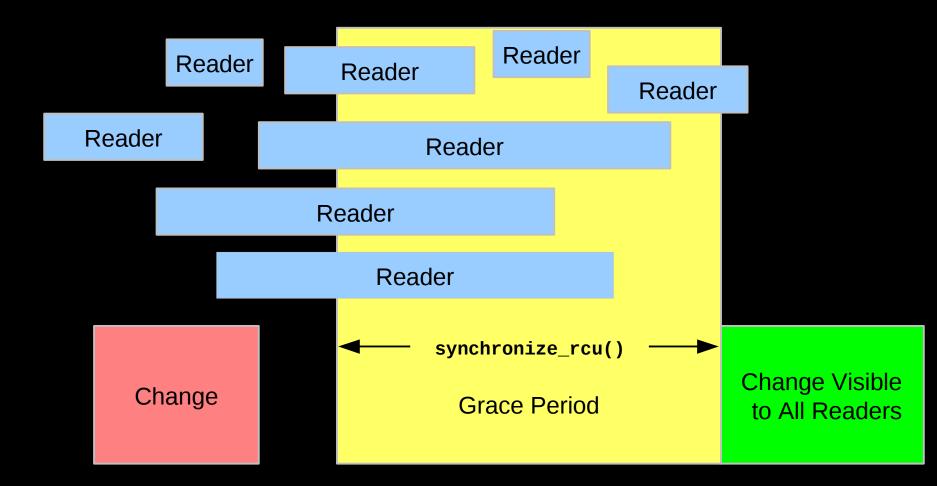
#### **RCU Grace Period: A Lazy Graphical View**



But it is OK for RCU to be lazy and allow a grace period to extend longer than necessary



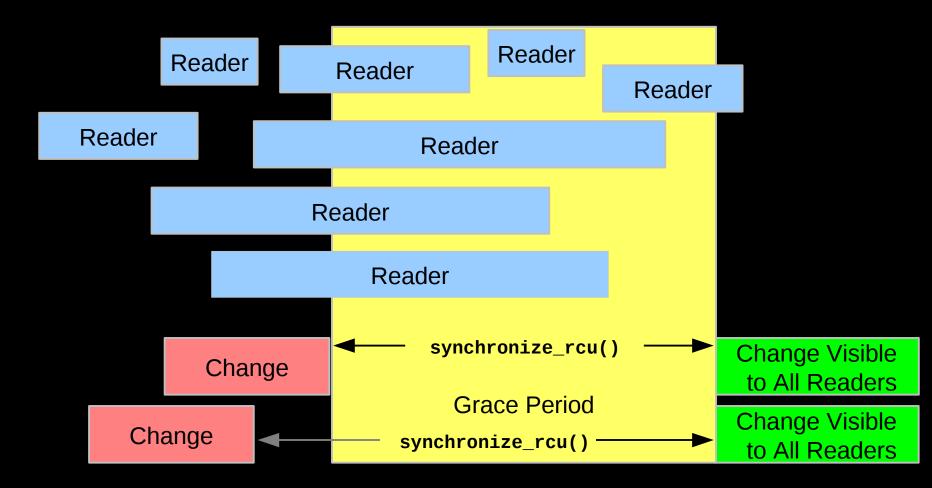
#### **RCU Grace Period: A Really Lazy Graphical View**



And it is also OK for RCU to be even more lazy and start a grace period later than necessary But why is this useful?



### **RCU Grace Period: A Usefully Lazy Graphical View**



Starting a grace period late can allow it to serve multiple updates, decreasing the per-update RCU overhead. But...

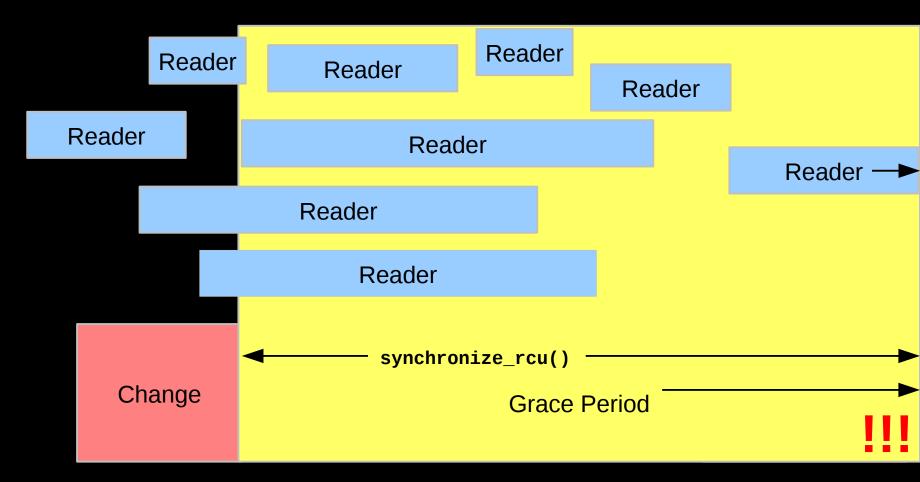


#### **The Costs and Benefits of Laziness**

- Starting the grace period later increases the number of updates per grace period, reducing the per-update overhead
- Delaying the end of the grace period increases grace-period latency
- Increasing the number of updates per grace period increases the memory usage
  - Therefore, starting grace periods late is a good tradeoff if memory is cheap and communication is expense, as is the case in modern multicore systems
  - And if real-time threads avoid waiting for grace periods to complete –However...



#### **RCU Grace Period: A Too-Lazy Graphical View**



And it is OK for the system to complain (or even abort) if a grace period extends too long. Too-long of grace periods are likely to result in death by memory exhaustion anyway.



# **RCU Asynchronous Grace-Period Detection**



#### **RCU Asynchronous Grace-Period Detection**

The call\_rcu() function registers an RCU callback, which is invoked after a subsequent grace period elapses

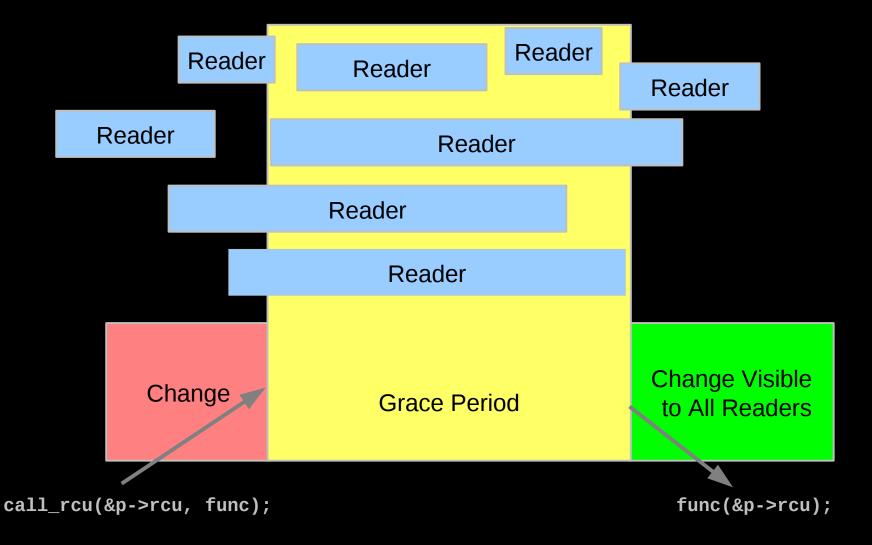
```
API:
    call_rcu(struct rcu_head head,
        void (*func)(struct rcu_head *rcu));
The rcu_head structure:
    struct rcu_head {
        struct rcu_head *next;
        void (*func)(struct rcu_head *rcu);
```

```
};
```

The rcu\_head structure is normally embedded within the RCUprotected data structure

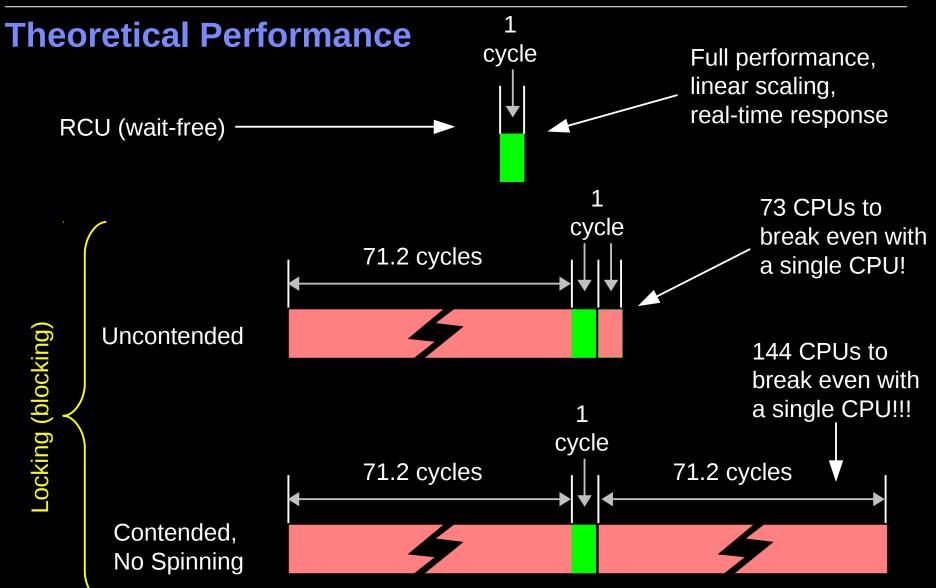


### **RCU Grace Period: An Asynchronous Graphical View**





#### Performance

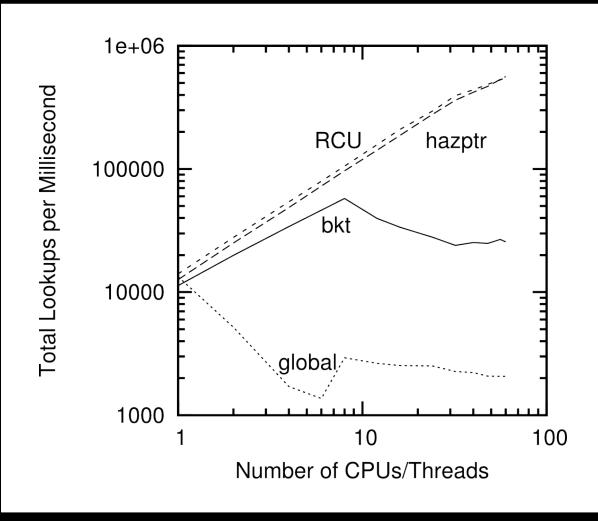




#### **Measured Performance**



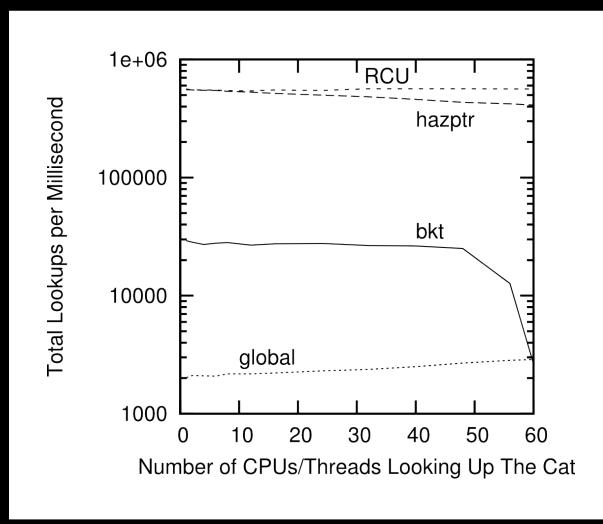
# Schrödinger's Zoo: Read-Only



RCU and hazard pointers scale quite well!!!



# Schrödinger's Zoo: Read-Only Cat-Heavy Workload



RCU handles locality quite well, hazard pointers not bad, bucket locking horribly

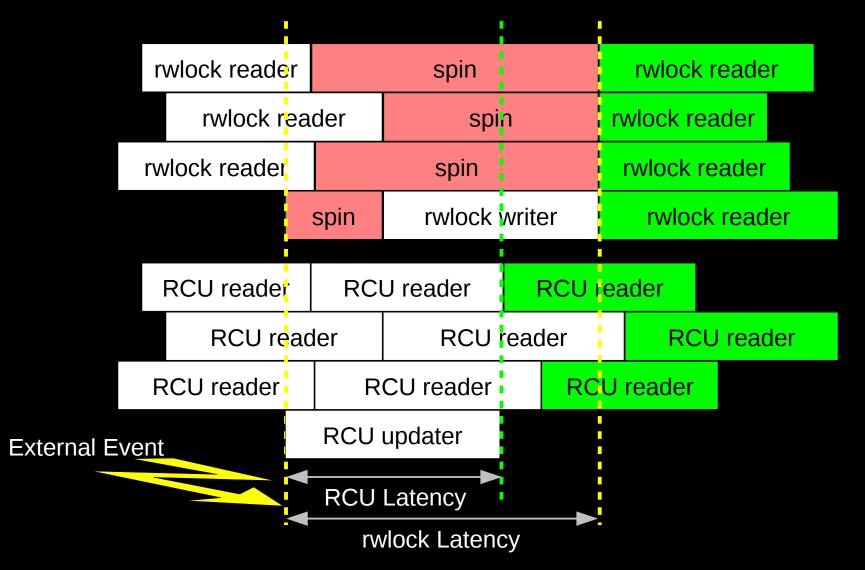
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# **Real-Time Response to Changes**



#### **RCU vs. Reader-Writer-Lock Real-Time Latency**





#### **RCU Performance: "Free is a Very Good Price!!!"**



## RCU Performance: "Free is a *Very* Good Price!!!" And Nothing Is Faster Than Doing Nothing!!!



### **RCU Area of Applicability**

Read-Mostly, Stale & Inconsistent Data OK (RCU Works Great!!!)

Read-Mostly, Need Consistent Data (RCU Works OK)

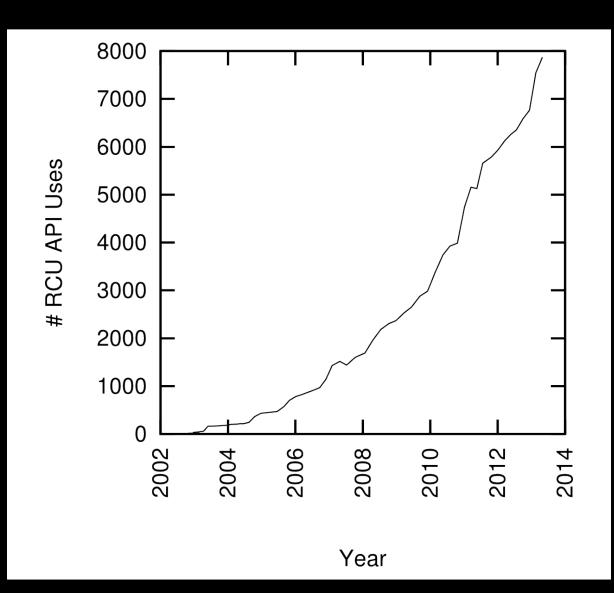
Read-Write, Need Consistent Data (RCU *Might* Be OK...)

Update-Mostly, Need Consistent Data (RCU is **Really** Unlikely to be the Right Tool For The Job, But It Can: (1) Provide Existence Guarantees For Update-Friendly Mechanisms (2) Provide Wait-Free Read-Side Primitives for Real-Time Use)

Schrodinger's zoo is in blue: Can't tell exactly when an animal is born or dies anyway! Plus, no lock you can hold will prevent an animal's death...



## **RCU** Applicability to the Linux Kernel





# Summary



### Summary

- Synchronization overhead is a big issue for parallel programs
- Straightforward design techniques can avoid this overhead
  - -Partition the problem: "Many instances of something good!"
  - -Avoid expensive operations
  - -Avoid mutual exclusion

### RCU is part of the solution

- -Excellent for read-mostly data where staleness and inconsistency OK
- -Good for read-mostly data where consistency is required
- -Can be OK for read-write data where consistency is required
- -Might not be best for update-mostly consistency-required data
- -Used heavily in the Linux kernel
- Much more information on RCU is available...



# **To Probe Further:**

- https://queue.acm.org/detail.cfm?id=2488549
  - "Structured Deferral: Synchronization via Procrastination"
- http://doi.ieeecomputersociety.org/10.1109/TPDS.2011.159 and http://www.computer.org/cms/Computer.org/dl/trans/td/2012/02/extras/ttd2012020375s.pdf
  - "User-Level Implementations of Read-Copy Update"
- git://lttng.org/userspace-rcu.git (User-space RCU git tree)
- http://people.csail.mit.edu/nickolai/papers/clements-bonsai.pdf
  - Applying RCU and weighted-balance tree to Linux mmap\_sem.
- http://www.usenix.org/event/atc11/tech/final\_files/Triplett.pdf
  - RCU-protected resizable hash tables, both in kernel and user space
- http://www.usenix.org/event/hotpar11/tech/final\_files/Howard.pdf
  - Combining RCU and software transactional memory
- http://wiki.cs.pdx.edu/rp/: Relativistic programming, a generalization of RCU
- http://lwn.net/Articles/262464/, http://lwn.net/Articles/263130/, http://lwn.net/Articles/264090/ - "What is RCU?" Series
- http://www.rdrop.com/users/paulmck/RCU/RCUdissertation.2004.07.14e1.pdf
  - RCU motivation, implementations, usage patterns, performance (micro+sys)
- http://www.livejournal.com/users/james\_morris/2153.html
  - System-level performance for SELinux workload: >500x improvement
- http://www.rdrop.com/users/paulmck/RCU/hart\_ipdps06.pdf
  - Comparison of RCU and NBS (later appeared in JPDC)
- http://doi.acm.org/10.1145/1400097.1400099
  - History of RCU in Linux (Linux changed RCU more than vice versa)
- http://read.seas.harvard.edu/cs261/2011/rcu.html
  - Harvard University class notes on RCU (Courtesy Eddie Koher)
- http://www.rdrop.com/users/paulmck/RCU/ (More RCU information)



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# **Questions**?

