

Distributed Operating Systems

Security - Foundations, Covert Channels, Noninterference

Marcus Völp / Hermann Härtig

2009

Purpose of this Lecture

- Assurance
 - Can you trust the system you intend to use
 - to protect your private / valuable data?
 - to grant only those programs access to your data that you trust?
 - to grant your programs access to data when they need it?
- Formal methods
 - as a precise description of system behavior
 - as a tool to reason about security properties

What makes you believe that your system is secure

- Trust in the developer / company
 - I've built it so I know what's wrong!
 - I trust the guys at <add your favorite company here> (at least I can sue them)!
- Quality Assurance Processes
 - ISO 9000
 - There is a QA team that runs tests on the SW of the development team; QA- and SW teams are disjoint
- Security Evaluation
 - Common Criteria
 - DO 178b (Airplanes)
 - GISA (BSI) IT Security Evaluation Criteria
(old '89 proposal for CC)

What makes you believe that your system is secure

- because the system is described in a way that is
 - precise,
 - sufficiently small to be captured in its entirety and
 - easy to understand
 - Abstract Mathematical Model
- because all security claims of the system follow from this description
 - Mathematical Proofs
- because the description and the actual system correspond
 - Refinement Proofs

Security Evaluation

- Common Criteria (EAL 7)
 - Formal top level specification
 - Informal (through tests) correspondence of source code to abstract specification
- GISA IT Security Evaluation Criteria (Q7)
(a proposal for CC-EAL 7 - 1st version from '89)
 - “The machine language of the processor used shall to a great extent be formally defined.”
 - “The consistency between the lowest specification level and the source code shall be formally verified.”
 - “The source code will be examined for the existence of covert channels, applying formal methods. It will be checked that all covert channels detected which cannot be eliminated are documented. [...]”

Overview

- Introduction
- Security Policies
- Policy Enforcement
- Decidability of Leakage
- Take Grant Protection Model
- Covert Channels
- Compiler-Based Information Flow Control

Security Policies

- Example:
 - Only the owner of a file and root can have write privileges to this file.
- Security Policy
 - Defines what is allowed / secure and what is not allowed / unsecure
- Secure System
 - System that enforces a security policy

Notation

- iff = if and only if
- Definition :=

- Sets: S, O, R, L
- Elements: s, o, r, l

- States: $\sigma \in \Sigma$

- Subject: $s \in S$ 

- Object: $o \in O$ 

- Entity: $e \in E$ with $E = S \cup O$ 

- Right: $r \in R$

- Access rights:
 - $S \times O \rightarrow \wp(R)$
 - $R(s,o)$

- State Transition (command c):

$$\sigma \xrightarrow{c} \sigma'$$

with result state: σ'

- $\sigma \xrightarrow{u.c} \sigma'$

if u is the current user in σ that invokes c

- Secrecy / Integrity Levels: $l \in L$

- Dominates relation:

$$l_1 \leq l_2$$

Information flow: from l_1 to l_2

$$l_1 \longrightarrow l_2$$

no IF: $l_1 \sim/\sim > l_2$

Security Policies – A first abstract system Model

- Example:
 - No user except the owner of a file and root can have write privileges to this file.
- A first abstract **system** model:
(Abstracts from real-life system; keeps necessary information to reason about the above example)
 - State: $\sigma \in \Sigma$
 - **Users:** set of all possible users
 - **Files:** set of all possible files:
 - $\Sigma = \{(U_{\text{life}}, F_{\text{life}}, \text{owner}, \text{rights}, u_{\text{current}})\}$
 - $U_{\text{life}} \subseteq \text{Users}, F_{\text{life}} \subseteq \text{Files}, u_{\text{current}} \in U_{\text{life}},$
 $\text{owner}: F_{\text{life}} \rightarrow U_{\text{life}}, \text{rights}: U_{\text{life}} \times F_{\text{life}} \rightarrow \wp(\mathbb{R})$
 - $\sigma = (\{\text{root}, \text{myself}, \text{hermann}\}, \{\text{foo.txt}, \text{bar.txt}\}, \text{root},$
 $\{(\text{foo.txt}, \text{myself}), (\text{bar.txt}, \text{hermann})\}, \{(\text{root}, \text{foo.txt}, \{\text{rw}\})\})$

Security Policies – A first abstract system Model

- A first abstract **system** model:

- State transitions:

$c \in C$; $C := \{\text{read}(\text{file}), \text{write}(\text{file}), \text{create}(\text{user}), \text{delete}(\text{file}), \text{chmod}(u, f, R), \dots\}$

- $\sigma = (\{\text{root}, \text{myself}, \text{hermann}\}, \{\text{foo.txt}, \text{bar.txt}\}, \text{root}, \{(\text{foo.txt}, \text{myself}), (\text{bar.txt}, \text{hermann})\}, \{(\text{root}, \text{foo.txt}, \{\text{rw}\})\})$

- $\sigma \xrightarrow{c} \sigma'$

- Example:

$\sigma \xrightarrow{\text{read}(\text{bar.txt})} \sigma'$ with $\sigma' := \sigma$

$\sigma \xrightarrow{\text{delete}(\text{bar.txt})} \sigma'$ with

$\sigma' := (\{\text{root}, \text{myself}, \text{hermann}\}, \{\text{foo.txt}, \text{bar.txt}\}, \text{root}, \{(\text{foo.txt}, \text{myself}), (\text{bar.txt}, \text{hermann})\}, \{(\text{root}, \text{foo.txt}, \{\text{rw}\})\})$

if $u_{\text{current}} = \text{root} \vee \text{owner}(\text{bar.txt}, u_{\text{current}})$

$\sigma' := \sigma$ otherwise

Security Policies – A first abstract system Model

- A first abstract **system** model:
 - Initial State: σ_0
 - Reachable States: $\Sigma_{0,C}$
 - Set $\Sigma_{0,C}$ of states that are reachable from σ_0 through a sequence of transitions c in C
 - $\sigma_0 \xrightarrow{*} \sigma$ iff $\sigma \in \Sigma_{0,C}$
 - **Example:** (if we require that the creator of a file becomes its owner)
 $\sigma' := (\{\text{root}, \text{myself}\}, \{\text{foo.txt}, \text{bar.txt}, \text{orphan.txt}\}, \text{root}, \{(\text{foo.txt}, \text{myself}), (\text{bar.txt}, \text{hermann})\}, \{\})$
 - σ' is a state (i.e., $\sigma' \in \Sigma$), however σ' is not reachable
 - System := (Σ, C, σ_0)

Security Policies – A first abstract system Model

- Example Policy:
 - No user except the owner of a file and root can have write privileges to this file.
- Does the system (Σ, C, σ_0) enforce the example policy P?

- $P(\sigma) := \forall u, f. w \in \text{rights}(u, f) \Rightarrow \text{owner}(f, u) \vee u = \text{root}$

$$\sigma \xrightarrow{\text{myself.chmod}(u, \text{foo.txt}, \{w\})} \sigma'$$

- without further constraints: $u = \text{hermann} \Rightarrow \neg P(\sigma')$
 \Rightarrow the system is insecure
- but, the system is secure if we replace chmod with chmod':

$$\text{chmod}'(u, f, R)(\sigma) := \text{if } (u = \text{root} \vee \text{owner}(\text{file}, u)) \text{ chmod}(u, f, R)(\sigma) \text{ else } \sigma$$

Security Policies - Definition

- Definition (Bishop – Computer Security Art and Science):
 - A *security policy* P is a statement that partitions the states (Σ) of a system into a set of authorized (or secure) states ($\Sigma_{\text{sec}} = \{\sigma \mid P(\sigma)\}$) and a set of unauthorized (or nonsecure) states.
 - A *secure system* is a system that starts in an authorized state and that cannot enter an unauthorized state.

all reachable states must be secure: $\Sigma_{0,C} \subseteq \Sigma_{\text{sec}}$

Introduction:

Confidentiality, Integrity, Availability

- Confidentiality:
 - Prevent unauthorized disclosure of information

- Definition:

*Information I is confidential with respect to set of entities X if no member of X **can obtain information** about I.*

- *Example: My EC-Card Pin is XXXX*

Introduction:

Confidentiality, Integrity, Availability

- Integrity:

- Correctness of data and information

- Definition 1:

Information is current, correct and complete.

- *prevent damage*

- Definition 2: (fundamentally different to Def 1)

*Either information is current, correct, and complete (Def 1.), or it is possible to **detect** that these properties do not hold.*

- *detect damage*

- *Example: balance of my bank account*

- Recoverability:

- Definition:

Information that has been damaged can be recovered eventually.

Introduction:

Confidentiality, Integrity, Availability

- Availability:

- Accessibility of information and services

- Definition 1:

Resource I is available with respect to X if all members of X can access I.

- *In practice, availability has also quantitative aspects:*

- *real-time systems:*

- *I is available within t clock ticks*
- *I is available t clock ticks after a certain event*

- *fault-tolerant systems:*

- *In $1 - 10^{-6}$ % of all cases I is available to X*

Security Policies

- Classification

- Concern:

- Confidentiality e.g., Bell La Padula (Document Mgmt)
 - Integrity e.g., Biba, (Inventory System)
 - Availability
 - Hybrid e.g., Chinese Wall, (Clinical Information System)

- Types of Access Controls

- discretionary (identity based)
 - A user can configure the access control mechanism to allow or deny access to an object (it owns).
 - mandatory (rule based)
 - A system-wide mechanism controls access to objects based on a set of rules; individual users cannot alter these rules.

Security Policies

- Types of Access Controls

- discretionary (identity based)

- Example:

- A user is allowed to create new entities; it becomes the owner of these entities.
 - A user can change the access rights and the ownership of the files it owns.

- mandatory (rule based)

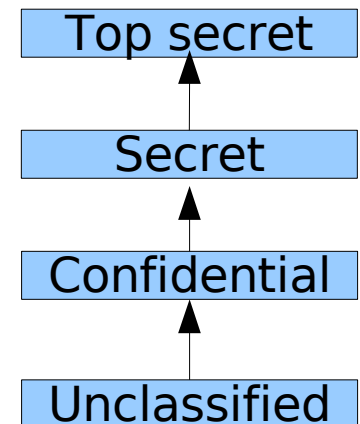
- Example:

Only system administrators are allowed to create new users.

=> A user attempt to create a new user will fail although users can create new entities.

Bell-LaPadula Model '73 (simple version)

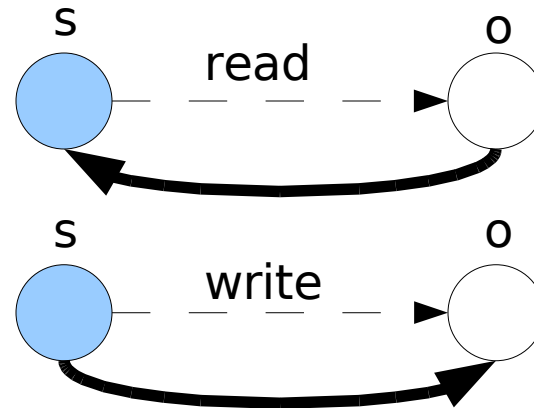
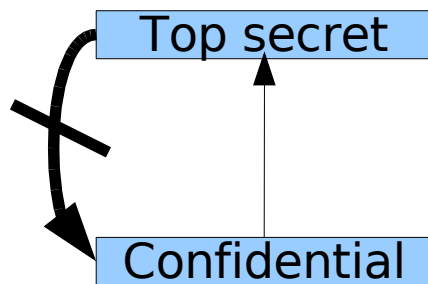
- Confidentiality Policy
- Totally ordered (by \leq) set of secrecy levels (L)
 - Higher secrecy level
 - => more sensitive information
 - => greater need to keep it confidential
 - Each subject has a **security clearance** ($\text{dom}(s) \in L$)
 - Each object has a **security classification** ($\text{dom}(o) \in L$)



- **Bell-LaPadula and the following security policies can be described as: (L, dom, \leq)**

Bell-LaPadula Model (simple version)

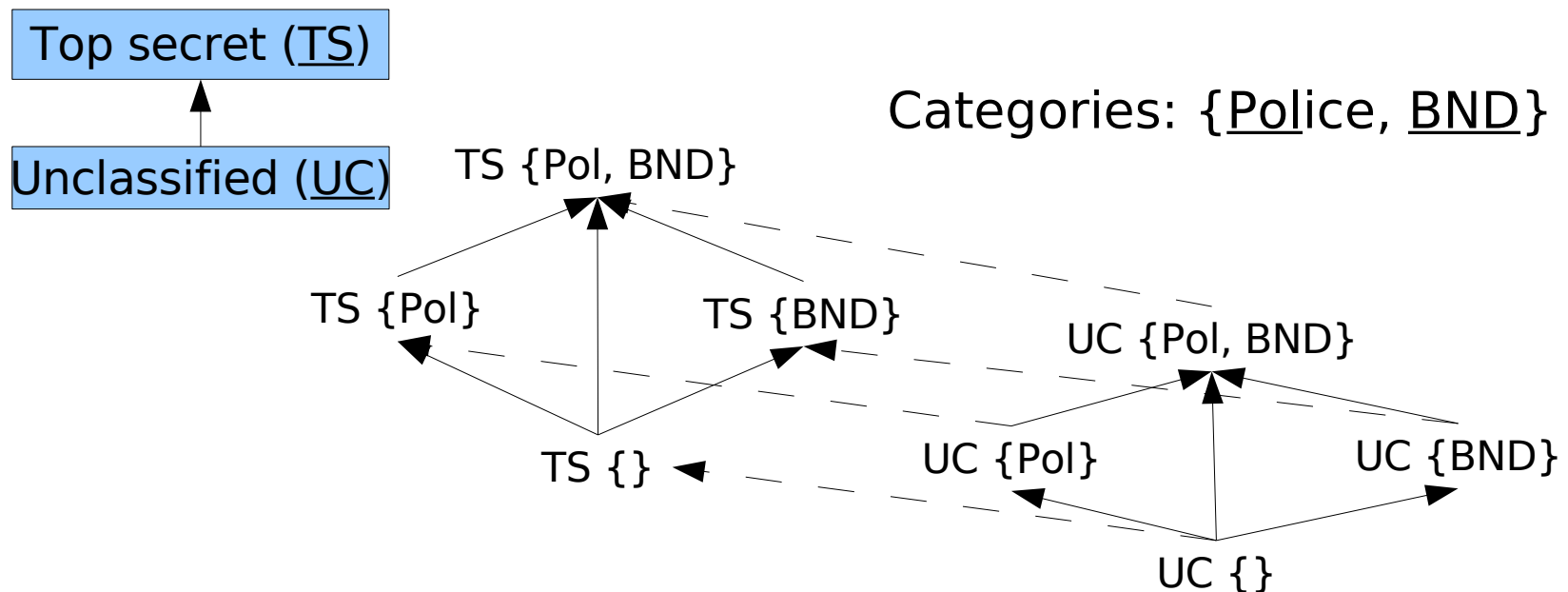
- Security Policy: (L, dom, \leq)



- Simple Security Condition
 - a subject s can only read lower or equally classified objects o
 - s can read o iff $\text{dom}(o) \leq \text{dom}(s)$
- *-Property
 - a subject s can only write higher or equally classified objects o
 - S can write o iff $\text{dom}(s) \leq \text{dom}(o)$

Bell-LaPadula Model (MLS)

- Security clearance comprised of hierarchical level and set of nonhierarchical categories
- Partial order (\leq); (L, \leq) form a lattice

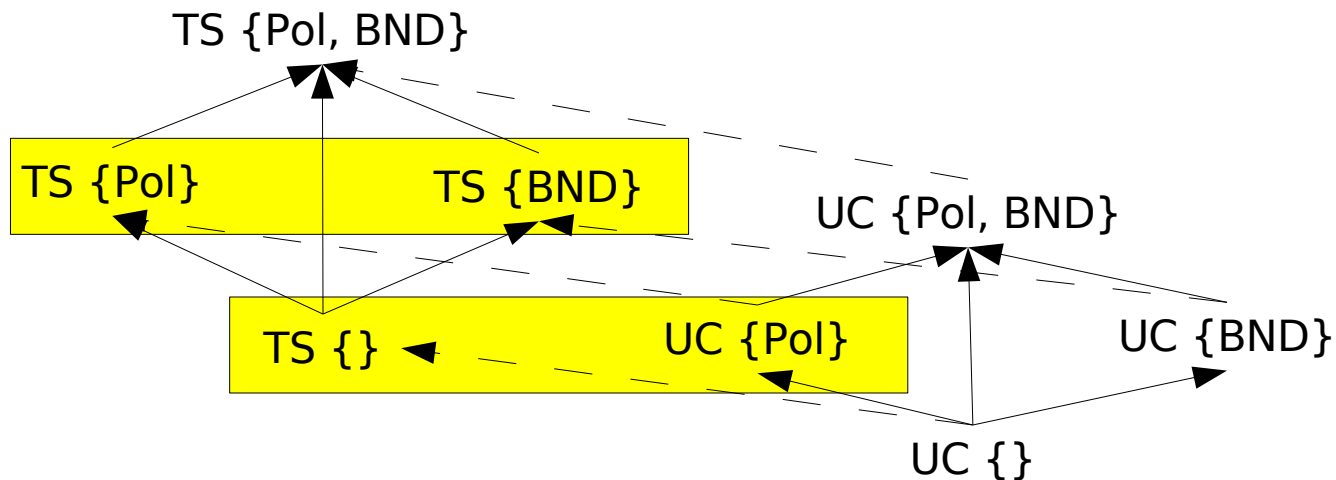


- German law (Bundesverfassungsschutzgesetz §17 - §26):
In general, no information exchange between BND and Police.

Bell-LaPadula Model (MLS)

- Security clearance comprised of hierarchical level and set of nonhierarchical categories
- Partial order (\leq); (L, \leq) form a lattice

Incompatible / Incomparable Classifications



Biba '77: Integrity Policies

(to prevent damage on integer data (Def. 1))

- Strict Integrity Policy (Biba Model)
 - Set of hierarchical integrity levels L
 - Integrity policy as triple (L, dom, \leq)
 - s can read o iff $\text{dom}(s) \leq \text{dom}(o)$
 - s can write o iff $\text{dom}(o) \leq \text{dom}(s)$
 - Strict Integrity Policy is dual to MLS
 - It **prevents** subjects from reading less integer objects
 - Alternative: allow subjects to read less integer data but prevent the consequences such a read may have on other objects => Low Water Mark.

Biba: Integrity Policies

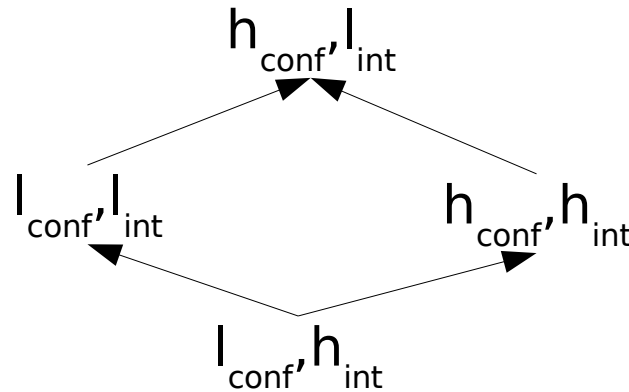
- Low Water Mark
 - s can write to o if and only if $\text{dom}(o) \leq \text{dom}(s)$
 - If s reads o then **$\text{dom}'(s) = \min(\text{dom}(s), \text{dom}(o))$**
 - Problem: label creep
 - decrease of subjects integrity level and thus the integrity level of the subject's results.
 - (dual for confidentiality policies:
increase object's confidentiality level)

D.Denning '76: Lattice Model (+ R. Sandhu '93)

- Most security policies can be expressed by the triple (L, dom, \leq) where (L, \leq) is a lattice.
- Confidentiality and integrity are dual properties; they can be combined into a single lattice, which describes the flow of information between the classified objects and subjects.

Confidentiality: $l_{\text{conf}} \leq h_{\text{conf}}$

Integrity: $h_{\text{int}} \leq l_{\text{int}}$

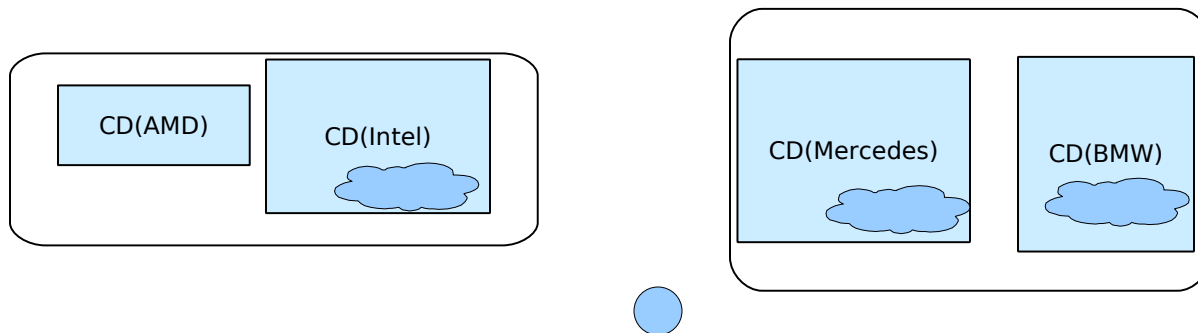
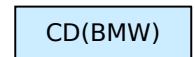


Chinese Wall (Brewer '89)

- Conflict of Interest

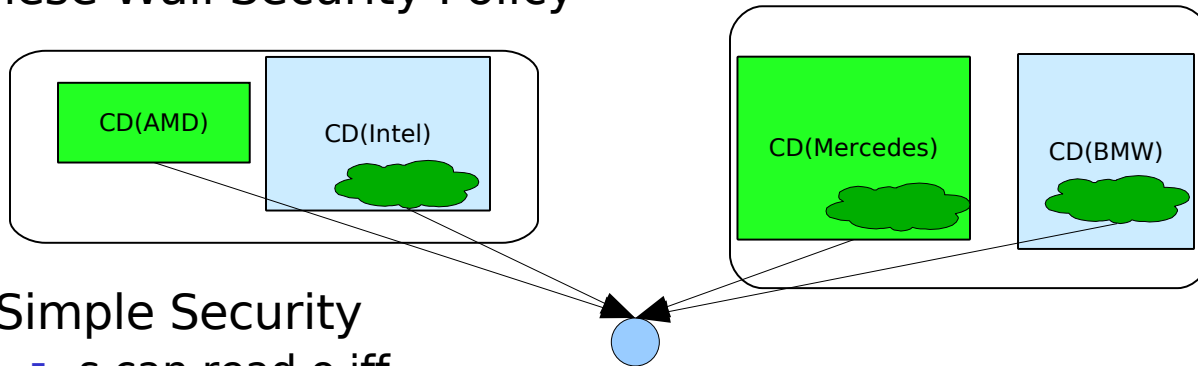
- E.g., British law for stock exchange
 - Trader must not represent two competitors. Otherwise, the trader could help one to gain an advantage at the expense of the other.

- Company Dataset (CD):
set of objects (files) related to a single company
- Conflict of Interest Class (COI):
datasets of companies in competition
- Sanitized Objects: objects cleared to the public
- Subjects: s (*the traders, not the companies*)



Chinese Wall

- Chinese Wall Security Policy



- Simple Security

- s can read o iff

- s has already access to an object of this company:
 $\exists o' \text{ accessed by } s \text{ with } CD(o') = CD(o),$

- or

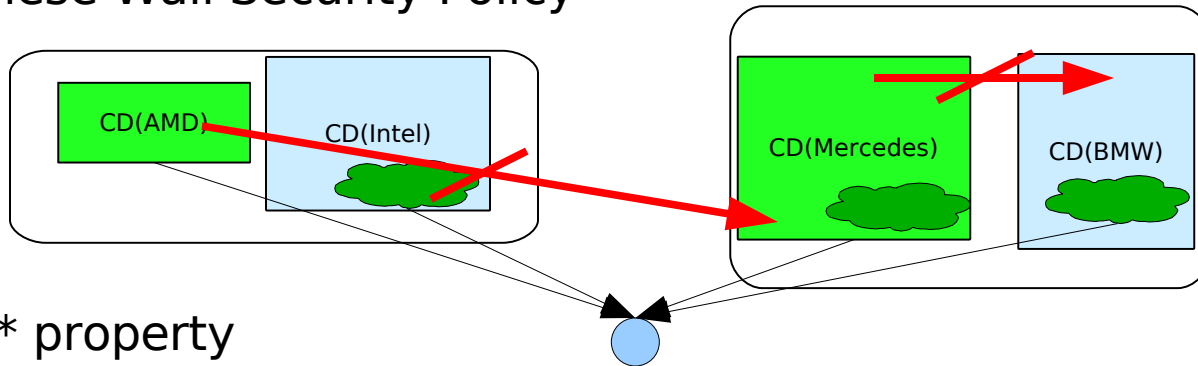
- no object o' that s has read is in conflict to o:
 $\forall o' \text{ read by } s \Rightarrow COI(o') \neq COI(o)$

- or

- o is sanitized

Chinese Wall

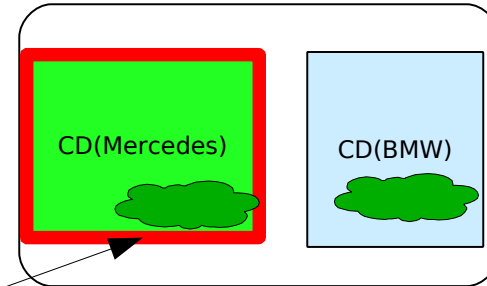
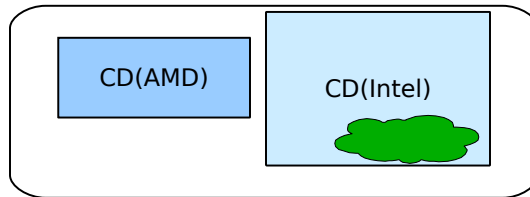
- Chinese Wall Security Policy



- * property
 - s can write o iff
 - s can read o,
 - and
 - If s can read an **unsanitized** object o', then o' must belong to the same company as o:
 $\forall o'. s \text{ can read } o' \Rightarrow CD(o') = CD(o)$
- That is, s must not leak data to another company unless this release is explicitly allowed (by sanitizing the data).

Chinese Wall

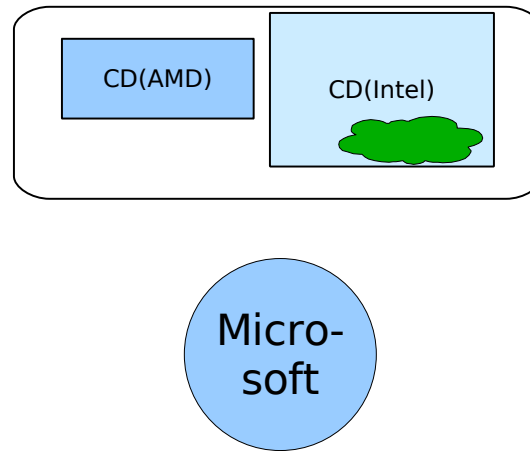
- Chinese Wall Security Policy



- * property
 - s can write o iff
 - s can read o,
 - and
 - If s can read an **unsanitized** object o', then o' must belong to the same company as o:
 $\forall o'. s \text{ can read } o' \Rightarrow CD(o') = CD(o)$
- That is, s must not leak data to another company unless this release is explicitly allowed (by sanitizing the data).

Chinese Wall

- Chinese Wall Security Policy



- NDAs: a real-life example for OS developers
 - MS needs early access to hardware to adjust Windows
 - Intel and AMD need to protect their IP from respective competitor
- Chinese Wall in Practice:
 - 1 Group of MS Developers with Intel
 - 1 Group of MS Developers with AMD
 - NO information exchange between these groups

Overview

- Introduction
- Security Policies
- Policy Enforcement
- Decidability of Leakage
- Take Grant Protection Model
- Covert Channels
- Compiler-Based Information Flow Control

Policy Enforcement Mechanisms:

- Access Control Matrix (ACM):
 - Subjects S, Objects O, Entities $E = S \cup O$, Rights R
 - Matrix: $S \times E \times R$
 - any operation c from s on o (or s') checks the respective cell $R(s,o)$ of the ACM for sufficient rights for this operation c.

	o1	o2	s1	s2
s1	rd,wr	rd	rd,wr	rd
s2	rd,wr	-	wr	rd,wr

- Operations: C
 - read entity, write entity
 - create subject, create object
 - destroy subject, destroy object
 - **enter right r into cell $R(s,o)$, delete right r from cell $R(s,o)$**

Policy Enforcement Mechanisms:

- Access Control List:
 - Each entity has a list of tuples: Subjects S x Rights R
 - e.g., foo.txt: (MV, {rd,wr}), (root, {rd})
 - Abbreviations:
 - Owner, Groups: Unix, AIX (e.g., [user;group;all])
 - Wildcards: foo.txt: (sysadmin_*, {rd,wr})
 - Conflicts:
 - two opposing rights in ACL: u - r; g + r
 - order of occurrence in ACL: u - r; g + r => access
(e.g., Cisco Router) g + r; u - r => denied
 - deny rule has precedence over allow rule (e.g., AIX)

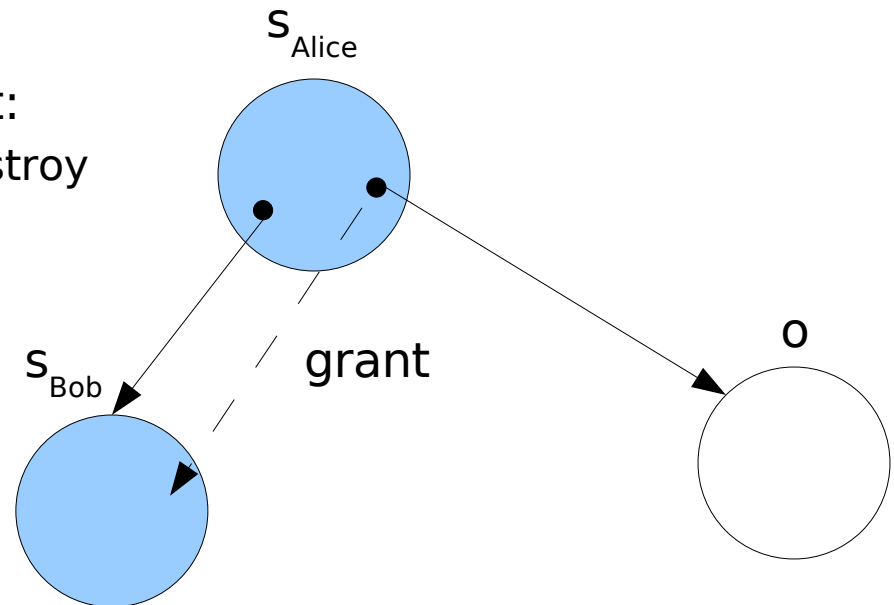
Policy Enforcement Mechanisms:

- Problem: Who is allowed to modify the ACM / ACLs?
 - Ownership: foo.txt: (MV, {rd,wr,own}), (HH, {rd})
 - Principle of Attenuation:
(in German: Abschwächung, Verminderung)
 - A subject s must not give away rights it does not possess!
 - In principle, cannot be enforced with above ACM operations:
any subject i can invoke **enter r into $R(s,o)$**
 - Solution: replace **enter r into $R(s,o)$** with:
 - **i.grant r into $R(s,o)$** :=
if $r \in R(i,o)$ then enter r into $R(s,o)$
- (Notation: $s.c$ = the command c invoked by subject s)

Policy Enforcement Mechanisms:

■ Capabilities:

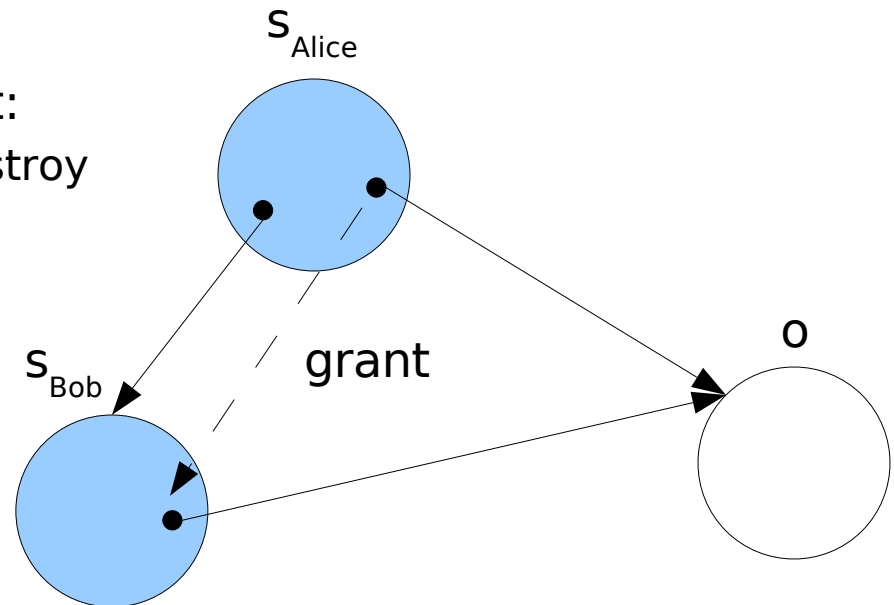
- Capability = unforgeable token (e, R)
 - with $e \in \text{Entity}$, $R \subseteq \text{Rights}$
- Possession of a Capability is necessary and sufficient to access the referenced entity.
- Operations
 - on the referenced object:
 - read, write, create, destroy
 - on the capability itself:
 - take, grant
 - diminish, remove



Policy Enforcement Mechanisms:

■ Capabilities:

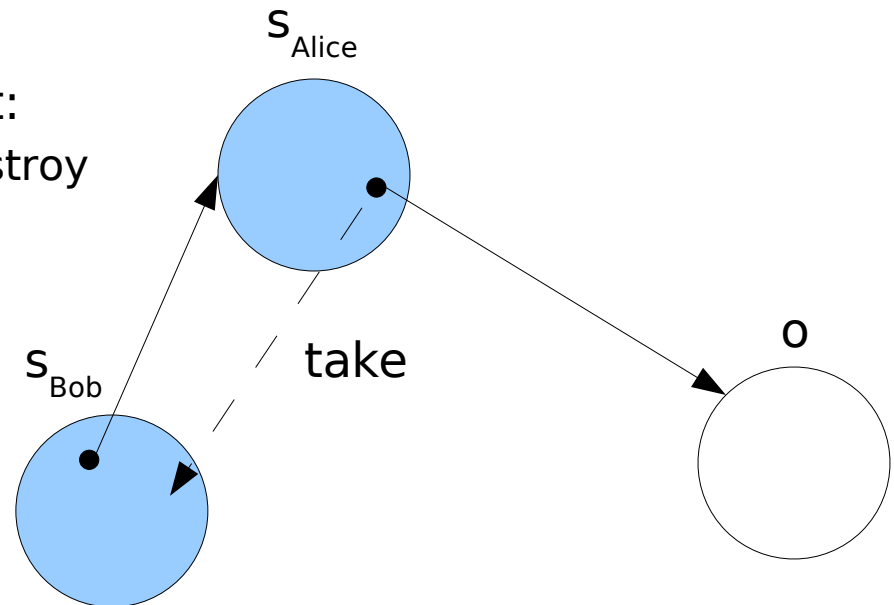
- Capability = unforgeable token (e, R)
 - with $e \in \text{Entity}$, $R \subseteq \text{Rights}$
- Possession of a Capability is necessary and sufficient to access the referenced entity.
- Operations
 - on the referenced object:
 - read, write, create, destroy
 - on the capability itself:
 - take, grant
 - diminish, remove



Policy Enforcement Mechanisms:

■ Capabilities:

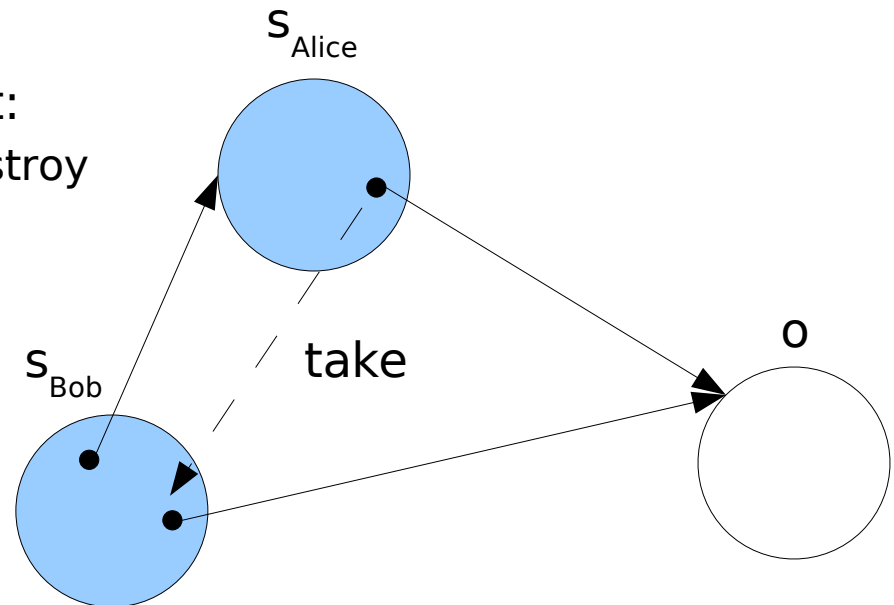
- Capability = unforgeable token (e, R)
 - with $e \in \text{Entity}$, $R \subseteq \text{Rights}$
- Possession of a Capability is necessary and sufficient to access the referenced entity.
- Operations
 - on the referenced object:
 - read, write, create, destroy
 - on the capability itself:
 - take, grant
 - diminish, remove



Policy Enforcement Mechanisms:

■ Capabilities:

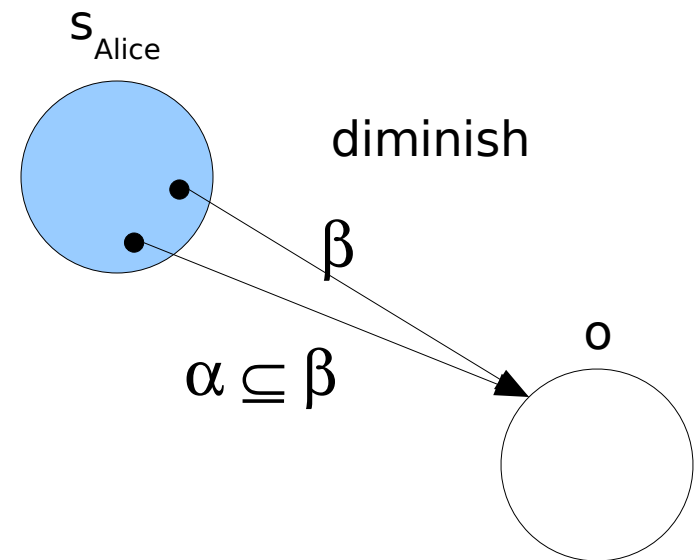
- Capability = unforgeable token (e, R)
 - with $e \in \text{Entity}$, $R \subseteq \text{Rights}$
- Possession of a Capability is necessary and sufficient to access the referenced entity.
- Operations
 - on the referenced object:
 - read, write, create, destroy
 - on the capability itself:
 - take, grant
 - diminish, remove



Policy Enforcement Mechanisms:

■ Capabilities:

- Capability = unforgeable token (e, R)
 - with $e \in \text{Entity}$, $R \subseteq \text{Rights}$
- Possession of a Capability is necessary and sufficient to access the referenced entity.
- Operations
 - on the referenced object:
 - read, write, create, destroy
 - on the capability itself:
 - take, grant
 - diminish, remove



Policy Enforcement Mechanisms:

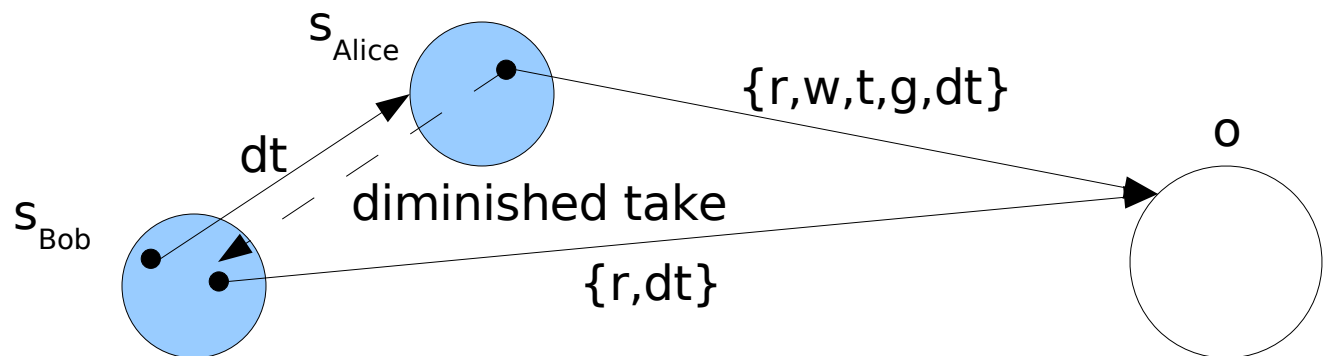
- Capabilities:
 - Implementation:
 - Software: OS protected segment / memory page
 - Hardware: Cambridge CAP / TLB
 - Cryptography: Amoeba
 - Problems:
 - How to control the propagation of capabilities?
 - How to revoke capabilities?

Capability Propagation

- Controlling Propagation
 - Dual to controlling modification of ACM / ACL
 - Permissions on channel capability:
 - take-permission (t), grant-permission (g)
 - Copy permission on the to be transferred capability
 - Right-diminishing channels: (an extension of TG)

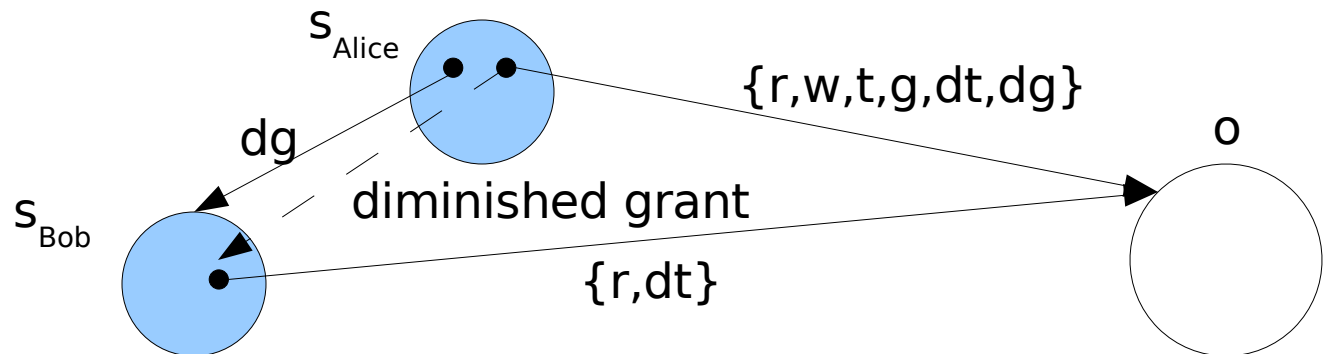
Capability Propagation

- Controlling Propagation
 - Right-diminishing channels: (an extension of TG)
 - s may take from s' but the caps taken are diminished
 - diminished-take perm. (dt) on channel
 - diminished take $(s,c) := \text{diminish}(\text{take}(s,c), \{w,t,g,dg\})$
 - Can be used to ensure that s can only ever **receive** information from s'



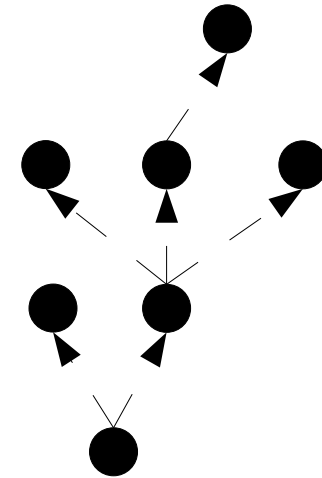
Capability Propagation

- Controlling Propagation
 - Right-diminishing channels: (an extension of TG)
 - s may grant to s' but the caps granted are diminished
 - Diminished-grant perm. (dg) on channel
 - Diminished grant $(s,c) := \text{diminish}(\text{grant}(s,c), \{w,t,g,dg\})$
 - Can be used to ensure that s can only ever **send** information to s'

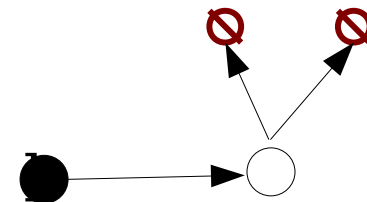


Capability Revocation

- Find and invalidate all direct and indirect copies



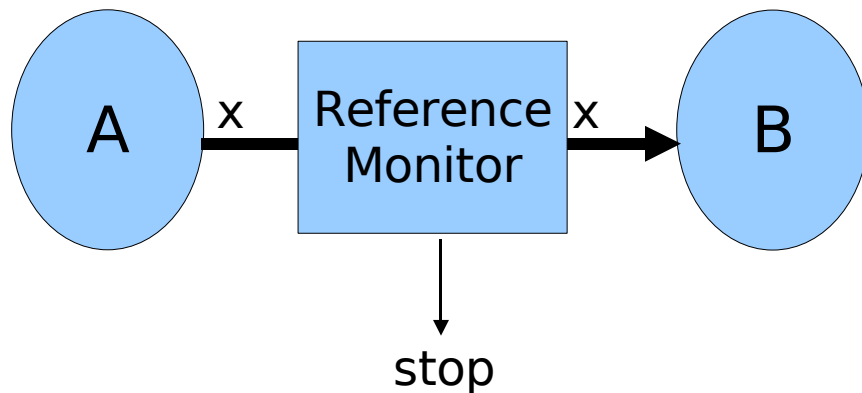
- Indirection Object:
 - Stores capabilities
 - Allows stored caps to be used but not to be taken out
 - Revoke by destruction of indirection object



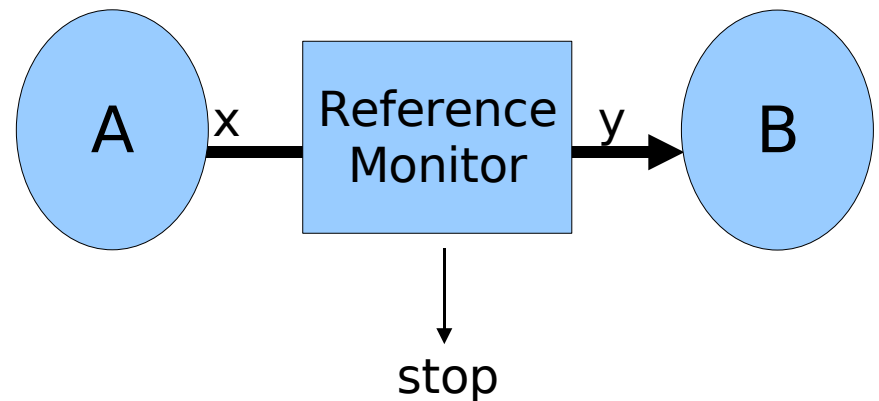
Policy Enforcement Mechanisms

- Reference Monitor:

EM: suppress, pass

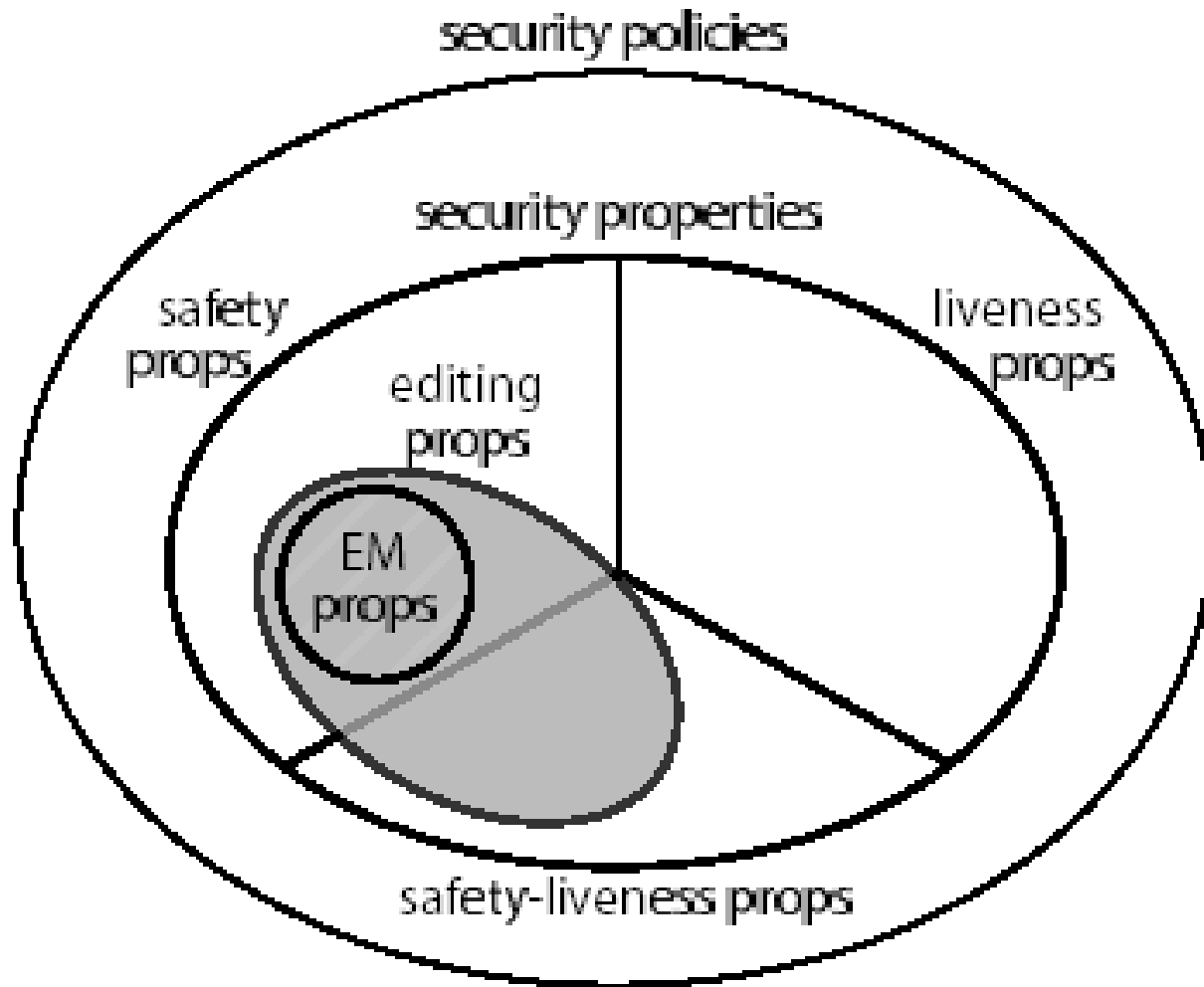


Edit



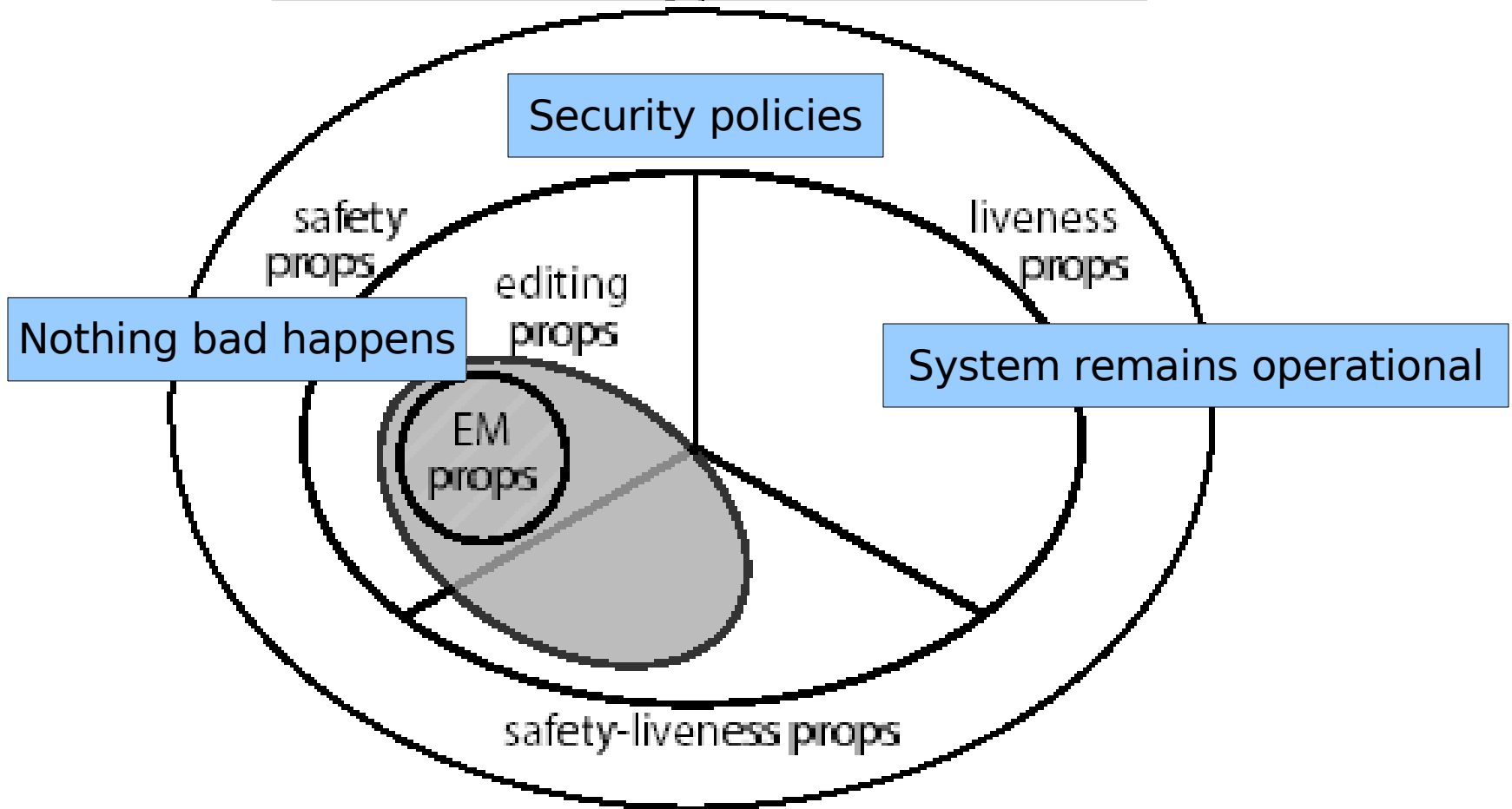
- Schneider [98] / Bauer [02]:
Which security policies are enforceable by reference monitors that are modeled as:
 - EM automata
 - Edit automata
- !!! results are based on a different system model !!!**

(More) Enforceable Security Policies



(More) Enforceable Security Policies

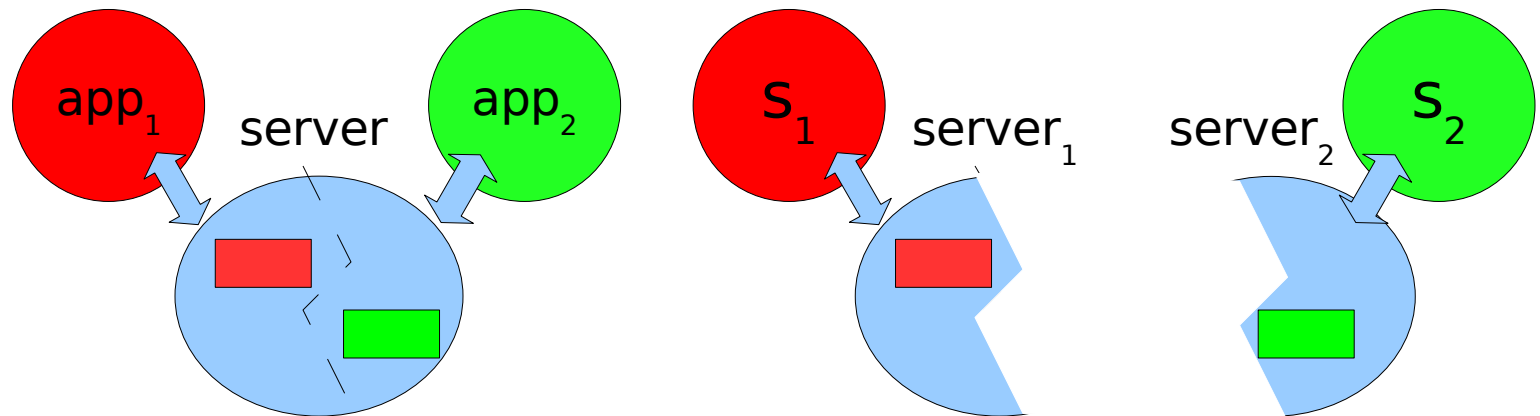
More general security policies



Policy Enforcement Mechanisms

- Compile-time analyzes to enforce security policies

- Problem:

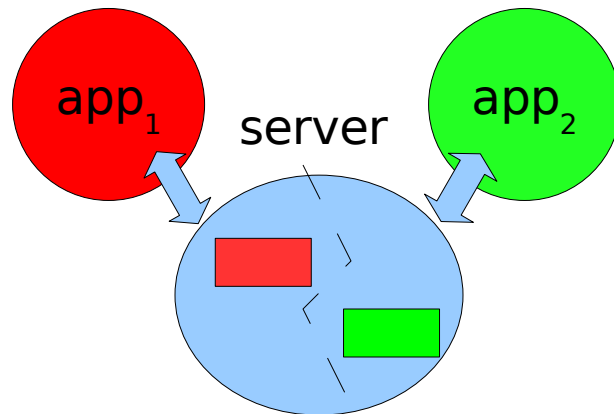


- OS-based (“peripheral”) policy enforcement mechanisms cannot control process-internal information flows.
- Solutions:
 - 1) Reinstantiate server for differently classified clients
not possible / feasible for all servers
(device drivers, buffer cache, OS kernel)

Policy Enforcement Mechanisms

- Compile-time analyzes to enforce security policies

- Problem:

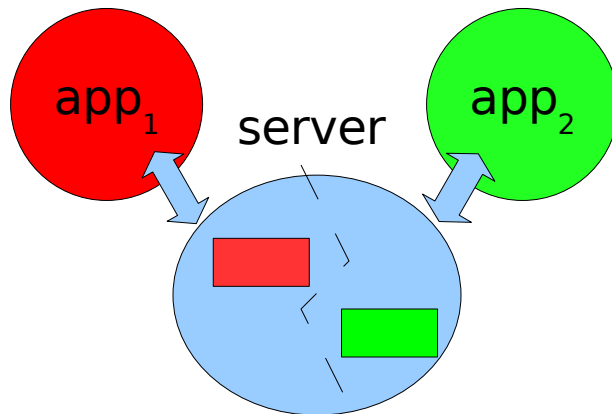


- OS-based (“peripheral”) policy enforcement mechanisms cannot control process-internal information flows.
- Solutions:
 - 2) Trust server to enforce security policy (without enforcement mechanism)

Policy Enforcement Mechanisms

- Compile-time analyzes to enforce security policies

- Problem:



- OS-based (“peripheral”) policy enforcement mechanisms cannot control process-internal information flows.
- Solutions:
 - 3) Check policy enforcement with static (compile-time) analysis of server programRun only successfully checked servers on differently classified confidential data

Policy Enforcement Mechanisms

- Example of server internal information flow:

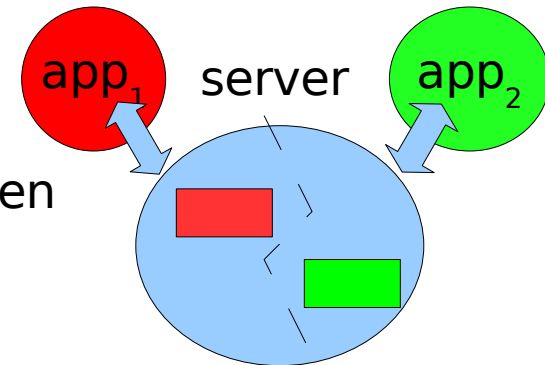
- Server State:

```
int h;    // in red part of server state
          // possibly contains secret data
int l;    // eventually becomes visible to green
          // e.g., located in shared memory
```

- Server Function:

```
void foo(int c) {
    if (c < 5)
        l = h;    // possible information leak from red to green
}
```

- Check program at compile time for the occurrence of expressions such as $l = h$
 - Note: static analysis cannot decide whether certain input will ever occur in reality – here: server is secure if $c \geq 5$



Overview

- Introduction
- Security Policies
- Policy Enforcement
- Decidability of Leakage
- Take Grant Protection Model
- Covert Channels
- Compiler-Based Information Flow Control

Decidability of Leakage

- Given
 - a security policy P
 - an enforcement mechanism (e.g., the ACM)
 - initial state σ_0
- Can we decide before the system runs (i.e., by considering only the initial state σ_0) whether it will reach a state in which P does not hold?

If P is a security policy based on access rights

- Can we decide before the system runs whether the system can reach a state in which a subject s has r rights over an object o (i.e., r is leaked to $R(s,o)$)?
- **Theorem:**
 - It is undecidable for generic ACM-enforced systems whether they will reach a state in which a subject s has a generic right r over an object o !

Decidability of Leakage: ACM

- Definition:
 - Leakage: r is entered in $R(s,o)$
 - Does not take into account whether the security policy P authorizes $r \in R(s,o)$.
 - Decidability of Leakage:
 - Is there an algorithm that is able to decide before the system runs whether the system will leak a generic right r on an object o to a subject s
 - Theorem:
 - Leakage is undecidable for ACMs.
 - Proof: by reduction to the halting problem of a turing machine

Decidability of Leakage: ACM

- Theorem:
 - It is undecidable whether a system, which evolves from an initial state s_0 , will leak a generic right r on o to s .
 - Proof by contradiction:
Reduction to halting problem of Turing machine.
 - Simulate a Turing Machine with the help of an ACM
 - Relate the state of the ACM in which r is leaked to $R(s,o)$ to the state of the TM in which a corresponding program halts

=>

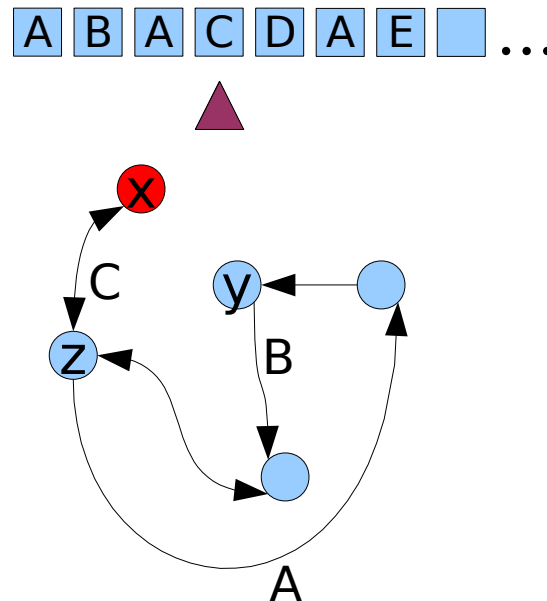
 - because the specific ACM implements the TM such that the ACM leaks whenever the TM program halts
 - if leakage is decidable so would be the TM halting problem
- Leakage is decidable (in linear time) for the Take-Grant Protection Model

Turing Machine

■ <http://wiki...>

■ Turing Machine

- infinite tape
- tape symbols $M : A, B, C, \dots$
- state automaton $K : x, y, z, \dots$
- head



■ TM transition: δ

- read symbol from tape (at position of head)
- perform an automaton transition dependent on this symbol
- write a new symbol to the tape
- move head one step to the left or to the right

$$\delta : K \times M \rightarrow K \times M \times \{L, R\}$$

Halting Problem

- <http://wiki...>

Halting Problem:

Given a TM and a Program P, find a program of the TM that decides whether P will terminate (halt).

- (TM \cong universal TM \cong while)

- Proof by contradiction: assume such a program exists

```
does_P_terminate_on_E (P, E) :=  
  if P(E) terminates  
    return true  
  return false
```

```
test(P) :=  
  while(does_P_terminate_on_E(P, P)) {}
```

- if **does_P_terminate(test, test)** returns true \Rightarrow **test(test)** must terminate (if condition)
- but then the condition of the while loop is true \Rightarrow **test(test)** does not terminate

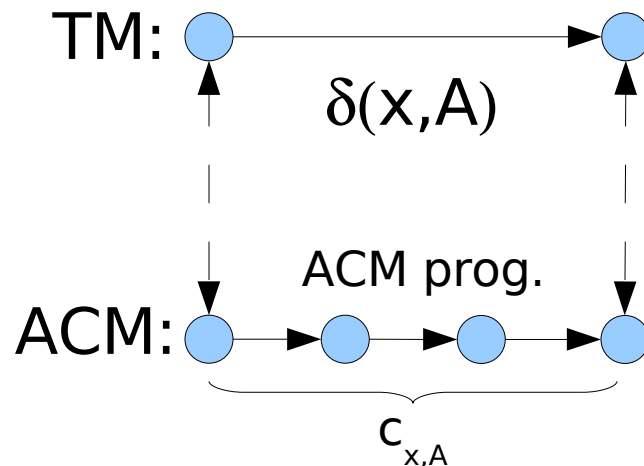


\Rightarrow there can be no test such as **P(E) terminates** for all P, E

Proof:

Leakage is undecidable with ACM

- 1) Formally define ACM and the ACM operations.
- 2) Construct a specific ACM, which simulates a generic TM.
 - a) Construct a mapping between states of a generic TM and states of a specific ACM
 - b) Simulate TM transitions with ACM programs such that each program yields a valid state that corresponds to a state of the TM
- 4) Correlate the state in which the ACM leaks r into $R(s,o)$ to the state in which the TM halts given $P(E)$



Access Control Matrix

	o1	o2	s1	s2
s1	rd,wr	rd	rd,wr	rd
s2	rd,wr	-	wr	rd,wr

- ACM operations: C
 - create subject s
 - create object o
 - destroy subject s
 - destroy object o
 - enter right r into $R(s,o)$
 - delete right r from $R(s,o)$

Access Control Matrix

■ create subject s

Pre: $s \notin S,$

Post: $S' = S \cup \{s\},$ // new subject
 $E' = E \cup \{s\},$ // subject also object
 $\forall x \in E': R'(s, x) = \emptyset,$ // new subject has no rights
 $\forall y \in S': R'(y, s) = \emptyset,$ // no rights on new subject
 $\forall x \in E, y \in S:$ // no change of old ACM cells
 $R'(x, y) = R(x, y)$

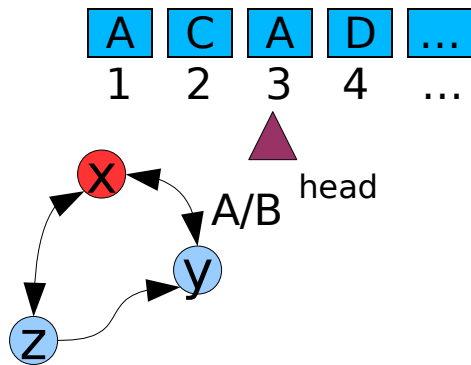
■ enter r into $R(s,o)$

Pre: $s \in S, o \in E$

Post: $S' = S, E' = E,$ // only $R(s,o)$ changes
 $\forall x \in E', y \in S':$
 $(s,o) \neq (x, y) \Rightarrow R'(x,y) = R(x, y)$
 $R'(s, o) = R(s, o) \cup \{r\}$ // add r to $R(s,o)$

Leakage is undecidable with ACM

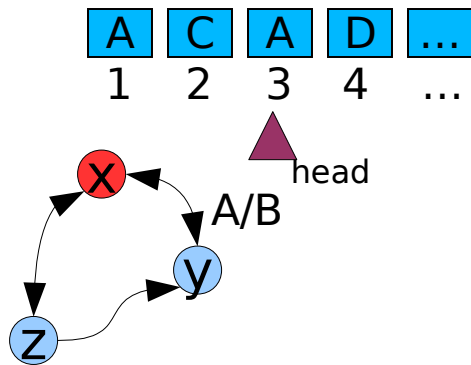
- Proof Sketch:



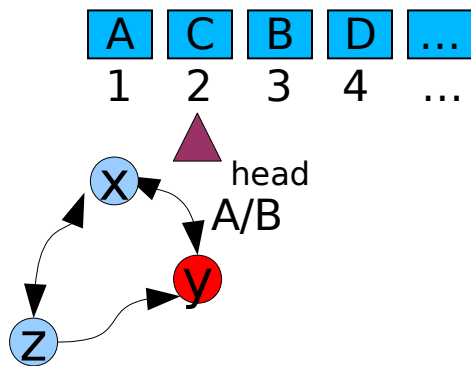
	S_1	S_2	S_3	S_4
S_1	A			
S_2		C		
S_3			A, x	
S_4			head	D

Leakage is undecidable with ACM

- Proof Sketch:



$\delta: (x, A) \rightarrow (y, B, L)$



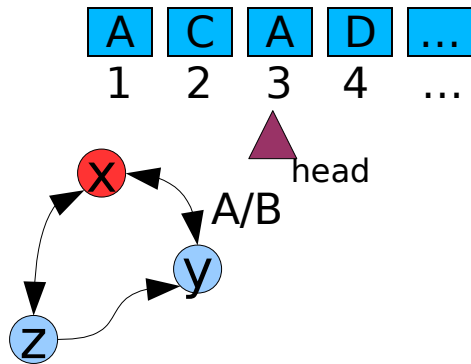
	s_1	s_2	s_3	s_4
s_1	A			
s_2		C		
s_3			A,x	
s_4				D

	s_1	s_2	s_3	s_4
s_1	A			
s_2		C,y		
s_3			B	
s_4				D

$C_{x,A}$

Leakage is undecidable with ACM

- Proof Sketch:



	s_1	s_2	s_3	s_4
s_1	A			
s_2		C		
s_3			A,x	
s_4				D

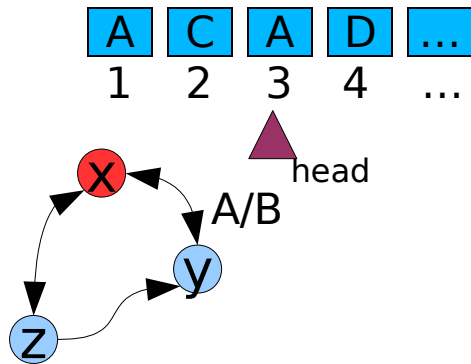
- $\delta: (x, A) \rightarrow (y, B, L)$

$$C_{x,A}(s_{\text{head}}, s_{\text{left}}) :=$$

if $x \in R(s_{\text{head}}, s_{\text{head}})$ and
 $A \in R(s_{\text{head}}, s_{\text{head}})$ then
 ...

Leakage is undecidable with ACM

- Proof Sketch:



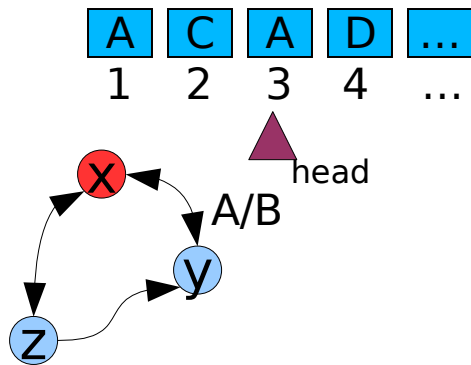
	s_1	s_2	s_3	s_4
s_1	A			
s_2		C		
s_3			A	
s_4				D

- $\delta: (x, A) \rightarrow (y, B, L)$

$C_{x, A}(s_{\text{head}}, s_{\text{left}}) :=$
 if $x \in R(s_{\text{head}}, s_{\text{head}})$ and
 $A \in R(s_{\text{head}}, s_{\text{head}})$ then
 delete x from $R(s_{\text{head}}, s_{\text{head}})$
 ...

Leakage is undecidable with ACM

- Proof Sketch:



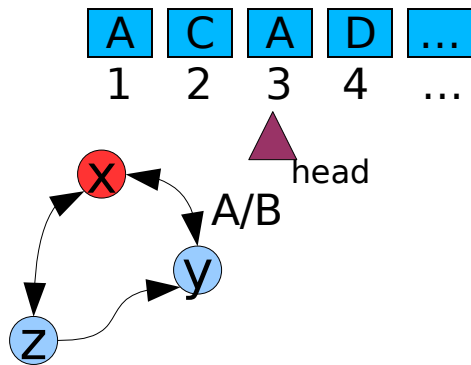
	s_1	s_2	s_3	s_4
s_1	A			
s_2		C		
s_3				
s_4				D

- $\delta: (x, A) \rightarrow (y, B, L)$

$C_{x, A}(s_{\text{head}}, s_{\text{left}}) :=$
 if $x \in R(s_{\text{head}}, s_{\text{head}})$ and
 $A \in R(s_{\text{head}}, s_{\text{head}})$ then
 delete x from $R(s_{\text{head}}, s_{\text{head}})$
 delete A from $R(s_{\text{head}}, s_{\text{head}})$
 ...

Leakage is undecidable with ACM

- Proof Sketch:



	s_1	s_2	s_3	s_4
s_1	A			
s_2		C		
s_3			B	
s_4				D

- $\delta: (x, A) \rightarrow (y, B, L)$

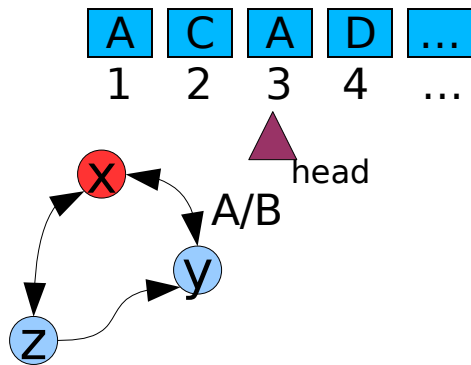
$$C_{x, A}(s_{\text{head}}, s_{\text{left}}) :=$$

if $x \in R(s_{\text{head}}, s_{\text{head}})$ and
 $A \in R(s_{\text{head}}, s_{\text{head}})$ then
 delete x from $R(s_{\text{head}}, s_{\text{head}})$
 delete A from $R(s_{\text{head}}, s_{\text{head}})$
 enter B into $R(s_{\text{head}}, s_{\text{head}})$

...

Leakage is undecidable with ACM

- Proof Sketch:



	s_1	s_2	s_3	s_4
s_1	A			
s_2		C,y		
s_3			B	
s_4				D

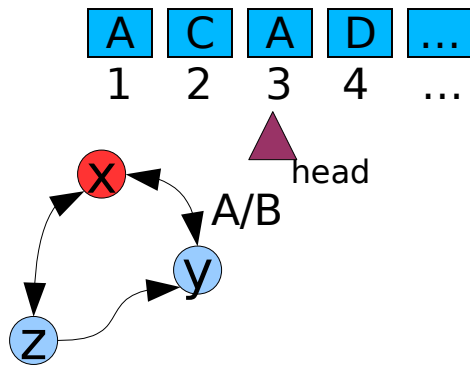
- $\delta: (x, A) \rightarrow (y, B, L)$

$$C_{x,A}(s_{\text{head}}, s_{\text{left}}) :=$$

if $x \in R(s_{\text{head}}, s_{\text{head}})$ and
 $A \in R(s_{\text{head}}, s_{\text{head}})$ then
 delete x from $R(s_{\text{head}}, s_{\text{head}})$
 delete A from $R(s_{\text{head}}, s_{\text{head}})$
 enter B into $R(s_{\text{head}}, s_{\text{head}})$
 enter y into $R(s_{\text{left}}, s_{\text{left}})$

Leackage is undecidable with ACM

- Proof Sketch:



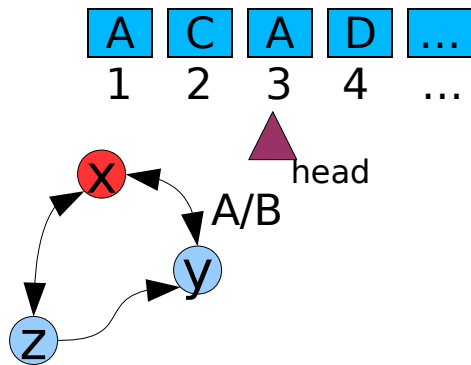
	s_1	s_2	s_3	s_4
s_1	A			
s_2		C		
s_3			A	
s_4				D,x,end

- **Problem 1:**

- $\delta: (x, D) \rightarrow (y, B, R)$ if head is in last cell (s_4, s_4)
 - distinguished right end to mark last cell
 - insert new subject s_5
 - propagate end right to s_5

Leakage is undecidable with ACM

- Proof Sketch:

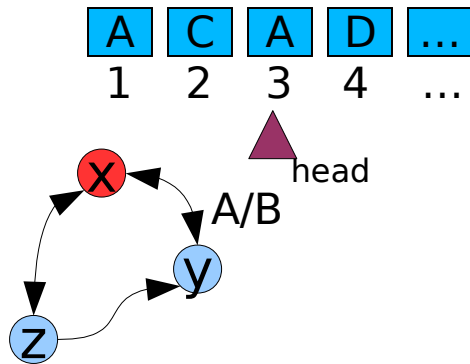


	s_1	s_2	s_3	s_4
s_1	A			
s_2		C		
s_3			A,x	
s_4				D,end

- Problem 2:** $\delta: (x, A) \rightarrow (y, B, L)$ $c_{x,A}(s_{\text{head}}, s_{\text{left}})$
 - Non-trivial problem:
 - Finite states + tape symbols but infinite many tape cells
 \Rightarrow subjects must remain parameters
 (otherwise infinite many ACM programs)
 - ACM has no way to express neighborhood (e.g., s_{left} is left of s_{head})

Leakage is undecidable with ACM

- Proof Sketch:

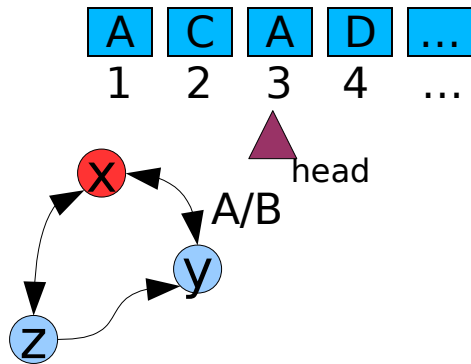


	s_1	s_2	s_3	s_4
s_1	A	own		
s_2		C	own	
s_3			A,x	own
s_4				D,end

- Problem 2:** $\delta: (x, A) \rightarrow (y, B, L)$ $c_{x, A}(s_{\text{head}}, s_{\text{left}})$
 - Non-trivial problem:
 - Finite states + tape symbols but infinite many tape cells
 => subjects must remain parameters
 (otherwise infinite many ACM programs)
 - ACM has no way to express neighborhood (e.g., s_{left} is left of s_{head})
 - Solution: $\text{own} \in R(s_{\text{head}}, s_{\text{left}})$

Leakage is undecidable with ACM

- Proof Sketch:



	s_1	s_2	s_3	s_4
s_1	A	own		
s_2		C	own	
s_3			A,x	own
s_4				D,end

- $\delta: (x, A) \rightarrow (y, B, L)$

- $c_{x,A}(s_{head'}, s_{left}) :=$
 - if $own \in R(s_{left}, s_{head})$ and
 - $x \in R(s_{head}, s_{head})$ and
 - $A \in R(s_{head}, s_{head})$ then
 - delete x from $R(s_{head}, s_{head})$
 - delete A from $R(s_{head}, s_{head})$
 - enter B into $R(s_{head}, s_{head})$
 - enter y into $R(s_{left}, s_{left})$

\Rightarrow TM (executing $P(E)$) halts at tape cell n in automaton state x with head tape symbol A **iff** A,x is leaked to $R(s_n, s_n)$.

\Rightarrow if leakage would be decidable so is the halting problem



Overview

- Introduction
- Security Policies
- Policy Enforcement
- Decidability of Leakage
- **Take Grant Protection Model**
- Covert Channels
- **Compiler-Based Information Flow Control**

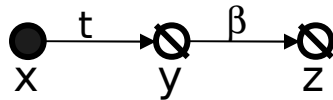
Take-Grant Protection Model

- Directed Graph

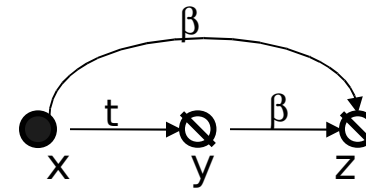
- Vertices: \bigcirc object, \bullet subject (\bigcirc either object or subject)
- Edges: $\bullet \xrightarrow{r} \bigcirc$ subject has capability with r right on object

- Transition Rules:

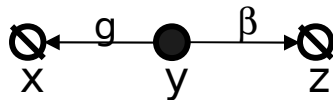
- Take



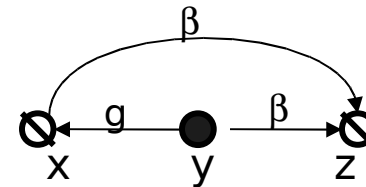
\vdash



- Grant



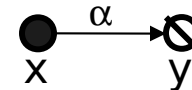
\vdash



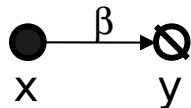
- Create



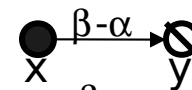
\vdash



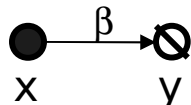
- Remove



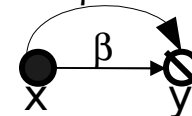
\vdash



- Diminish

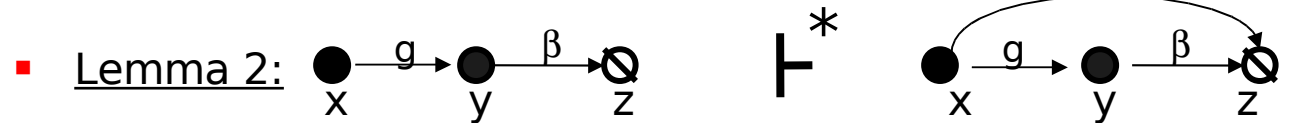
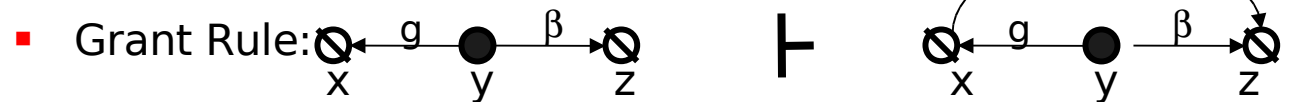
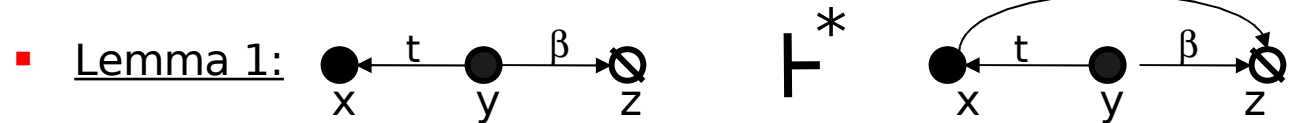
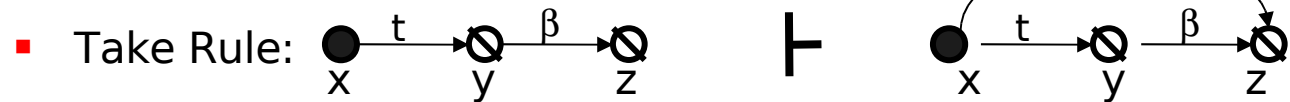


\vdash



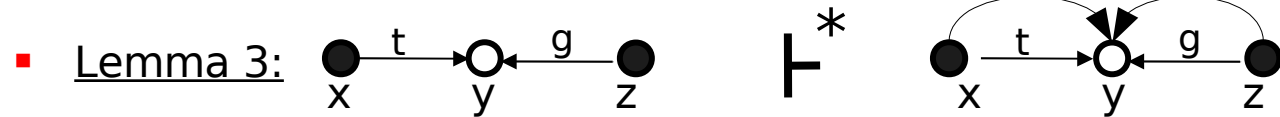
Take-Grant Protection Model

- 3 Lemmas:



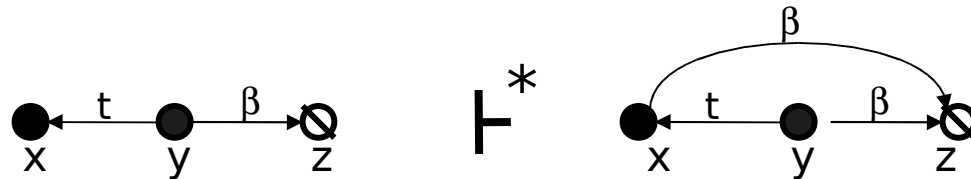
Take-Grant Protection Model

- 3 Lemmas:



Take-Grant Protection Model

- Proof of Lemma 1:



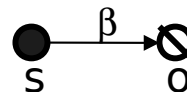
- Proof:

$x.create\ v\ (tg) ; y.take\ g ; \underline{y.grant\ \beta\ to\ v} ; x.take\ \beta\ from\ v$

- See exercises for the proof of Lemmas 2, 3

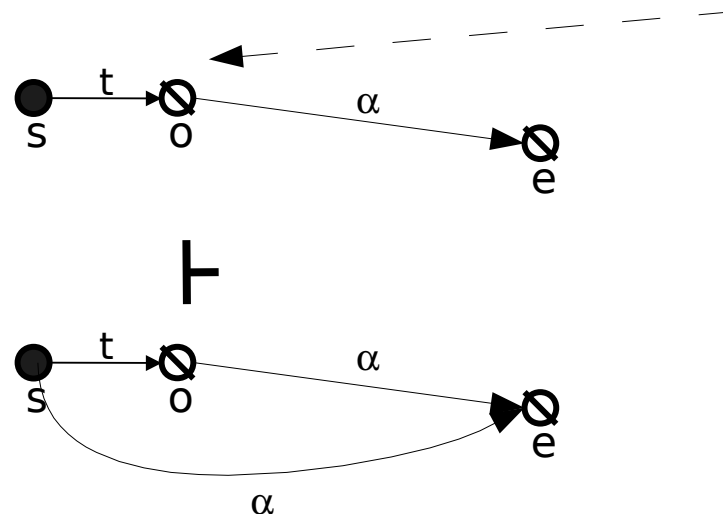
Take-Grant Protection Model

- Leakage is decidable in linear time in the Take-Grant Protection model.
 - Proof Sketch for decidability: (not: decidability in linear time)
 - construct potential-access graph (worst case rights propagation)
 - apply take + grant transition rules + the 3 lemmas until the no more rights can be added (i.e., the resulting potential-access graph no longer changes)
 - (delete, diminish, remove only reduce access rights)
 - (create establishes a new entity which cannot get no more privileges than its creator)
 - a right r on an object o can be leaked to a subject s if the potential access graph contains



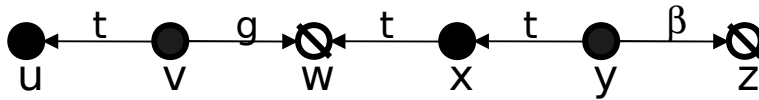
Take-Grant Protection Model

- Creating an Entity gives all rights to Creator
 - The creator s of an object o gets all permissions on o . In particular, s gets take permissions on o .
 - Assume a right r on e is leaked to o (i.e., o holds a capability (e, R) with $r \in R$)
 - Then s can take this capability from o .
 $\Rightarrow s$ can get all of o 's rights



Take-Grant Protection Model

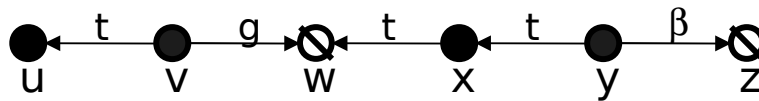
- Example: propagation of b on z to u (towards a potential access graph)



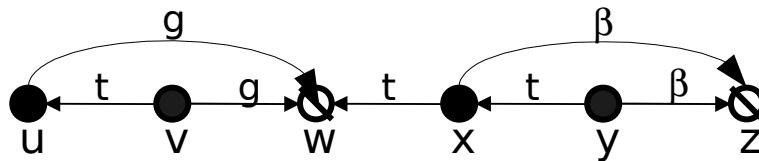
\vdash^* by Lemma 1

Take-Grant Protection Model

- Example: propagation of b on z to u (towards a potential access graph)



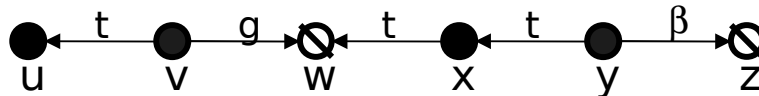
\vdash^* by Lemma 1



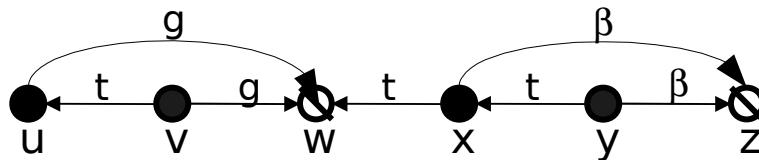
\vdash^* by Lemma 3

Take-Grant Protection Model

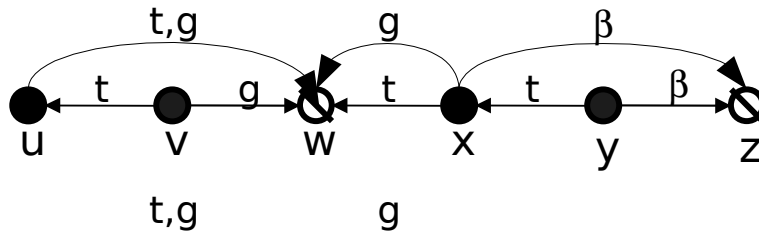
- Example: propagation of b on z to u (towards a potential access graph)



\vdash^* by Lemma 1



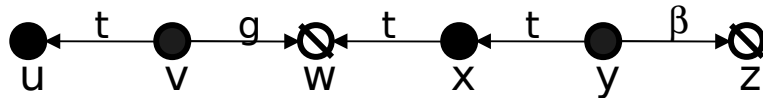
\vdash^* by Lemma 3



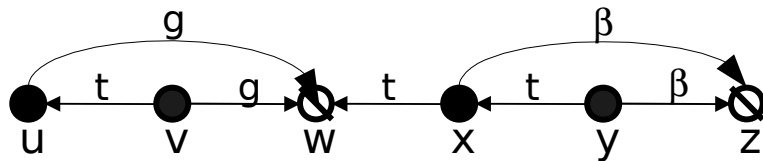
\vdash^* x.grant β on z to h
u.take β on t from h

Take-Grant Protection Model

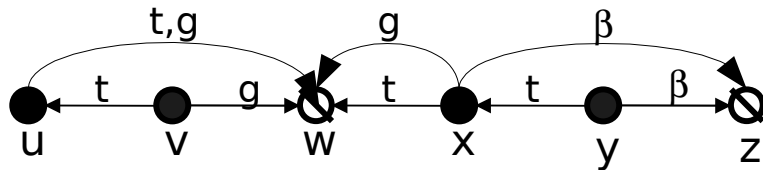
- Example: propagation of b on z to u (towards a potential access graph)



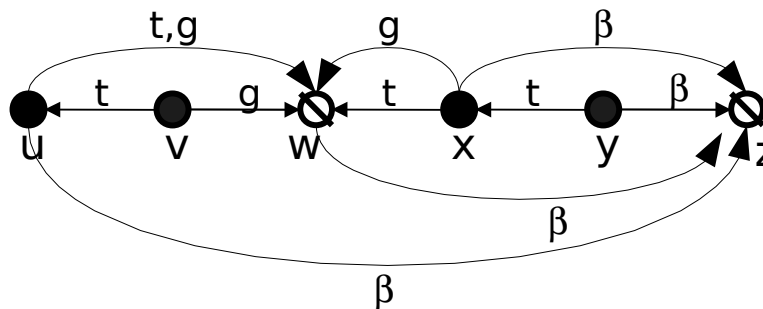
\vdash^* by Lemma 1



\vdash^* by Lemma 3



\vdash^* $x.\text{grant } \beta \text{ on } z \text{ to } h$
 $u.\text{take } \beta \text{ on } t \text{ from } h$



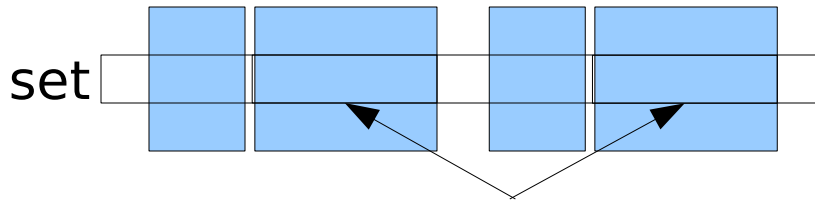
Overview

- Introduction
- Security Policies
- Policy Enforcement
- Decidability of Leakage
- Take Grant Protection Model
- Covert Channels
- **Compiler-Based Information Flow Control**

Covert Channels

- Covert Channel:
 - Lampson [73]:
 - Overt channel:
 - means of communication in the interface (e.g., read, write, error code)
 - Covert channel:
 - channel not intended for communication
 - TCSEC (Canadian predecessor of Common Criteria)
 - Covert channel:
 - Information flow in violation to the system's security policy
- Noise:
 - noiseless - only sender writes to covert channel
 - noisy - also other writers

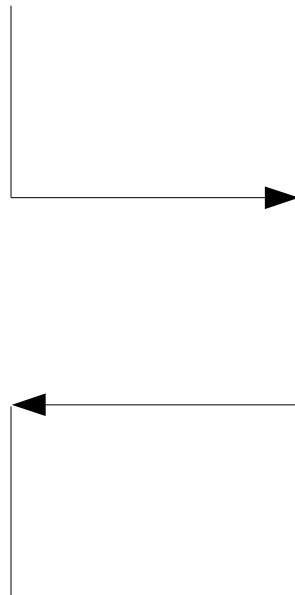
Covert Channels: Cache



- Certain memory locations map to the same set of cache lines
- Cache replacement policy is set internal

n-way associative: n cache lines

receiver sender

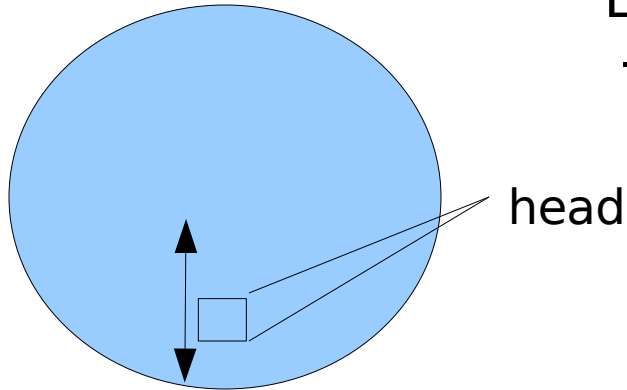


prepare cache:
by accessing n memory locations that map to the same set

access certain cacheline of same set
(e.g., AES – key dependent table lookups [Osvik])

probe timing of n memory locations:
short: sender did not access CL of this set
long: sender has evicted one (or more) of the n
memory locations

Covert Channels: Disk [Wray]



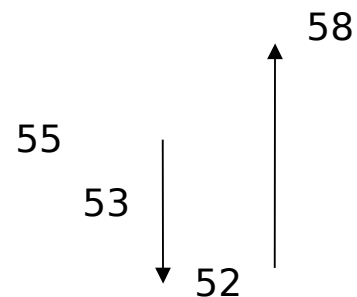
Elevator algorithm:
- cylinders in head movement direction are accessed first

Prepare:
read cyl. 55 ;
wait for completion

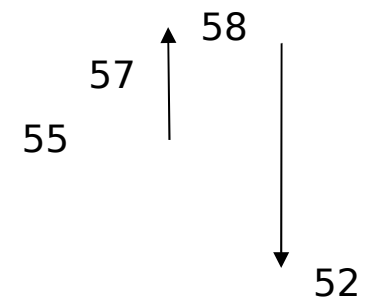
Send:
read cyl. 53 to send 0 or
read cyl. 57 to send 1
wait for completion

Probe:
read cyl. 52 and 58
observer order of completion

Send 0:



Send 1:



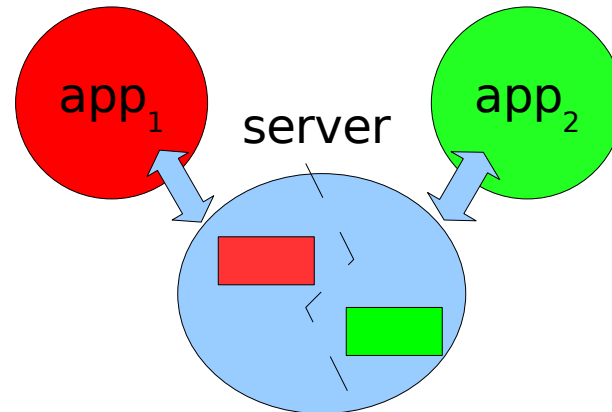
Covert Channels: in Programs

```
int l;    // eventually becomes observable by an l-classified observer
int h;    // stores a secret to which the l-classified observer is not cleared
```

```
// explicit flow
l = h;
```

```
// implicit flow
if (h % 2){
    l = 1;
} else {
    l = 0;
}
```

```
// probabilistic
if (h % 2) {
    l = random (0, ..., 1);
} else {
    l = 1;
}
```



```
// internal timing channel
if (h % 2) {
    l = 1 ; spin (10ms);
} else {
    spin (10ms) ; l = 1;
}
```

Covert Channels: in Programs

```
int l;    // eventually becomes observable by an l-classified observer
int h;    // stores a secret to which the l-classified observer is not cleared
```

```
// external timing channel
```

```
if (h % 2) {
    // long op
    for (int i = 0; i < 10000; i++) {}
} else {
    // short op
}
```

```
also h-dependent blocking:
    sleep(n ms)
```

```
// termination
```

```
if (h % 2) while (true) {}
```

```
// power, heat, ...
```

```
if (h % 2)
    float_ops()
else
    int_ops()
```


Noninterference

- Noninterference

- Prevailing formalization for the complete absence of covert channels in deterministic systems (e.g., programs)
- An l -classified observer sees the same output of a program p despite variations in secret (i.e., l' -classified) inputs (with $l \not\leq l'$).

$$s \sim_l s' \Rightarrow p(s) \sim_l p(s')$$

- $s \sim_l s'$ stands for s, s' are indistinguishable by an l -classified observer.

Information Flow

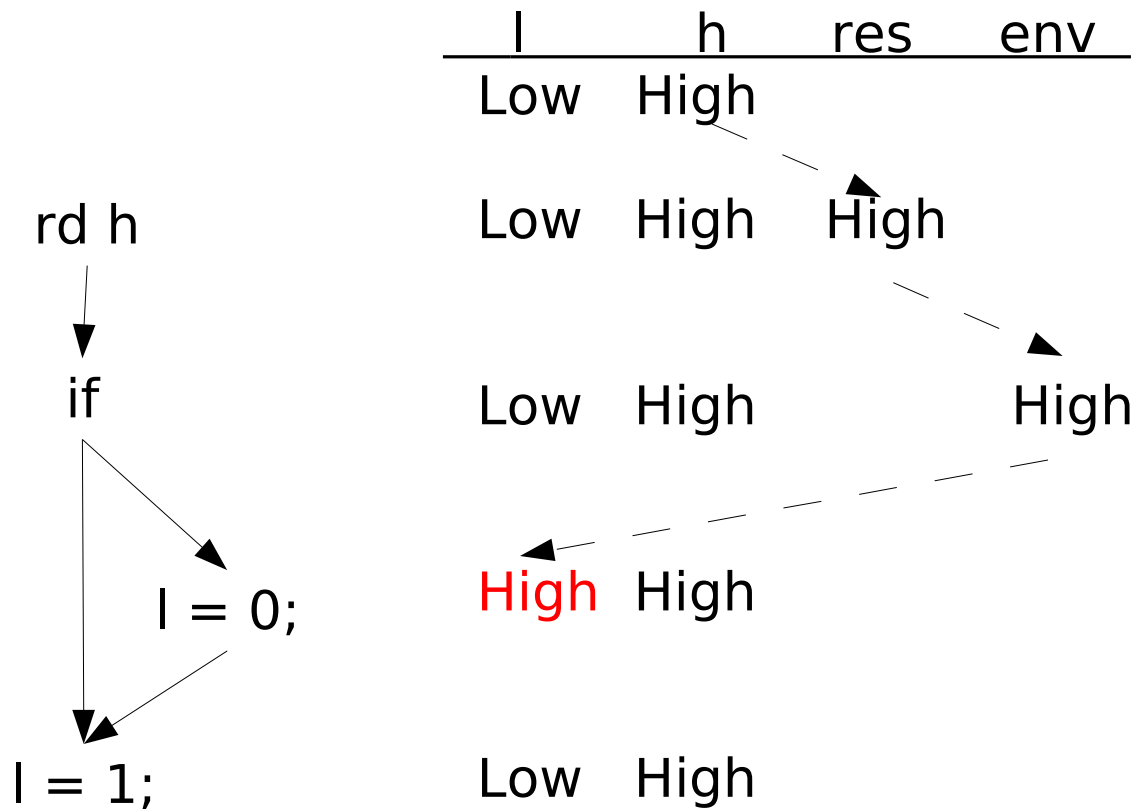
- A new (more general?) formalism:
 - Confidentiality (Denning [67])
 - $A \sim/\sim > B \Rightarrow$
B cannot deduce information on A (A's data), **A is confidential** with respect to B
 - Integrity (Denning [67])
 - $A \sim/\sim > B \Rightarrow$
B's integrity is independent of information / results from A, B is integer with respect to A
 - Availability (Myers [05])
 - $A \sim/\sim > B \Rightarrow$
B's availability is independent of information / results from A, B's availability cannot be affected by A
- Open Question: Is it possible to express any interesting access-control policy in terms of information flow?

Compile-Time Information-Flow Analysis

- Flow Insensitive (Denning, Volpano)
- Flow Sensitive (Hunt, Warnier)
 - Abstract from concrete system state:
 - Start with:
 - clearance of output variables
 - classification of input variables / initially stored secrets
 - Abstract from concrete values;
 - maintain only secrecy levels of stored information
 - Abstractly interpret program
 - side-effect free expression: $\mathbf{f(in_0, \dots, in_1) = out}$
 - out can only encode secrets of in_i :
 $\mathbf{dom(out) = least_upper_bound(dom(in_i))}$
 - control flow:
 - secrecy level \mathbf{env} for the instruction pointer:
 $\mathbf{wr(a, h) \Rightarrow dom(a) = lub(dom(h), env)}$

Compile-Time Information-Flow Analysis

- Example: `if (h) { l = 0; } l = 1;`

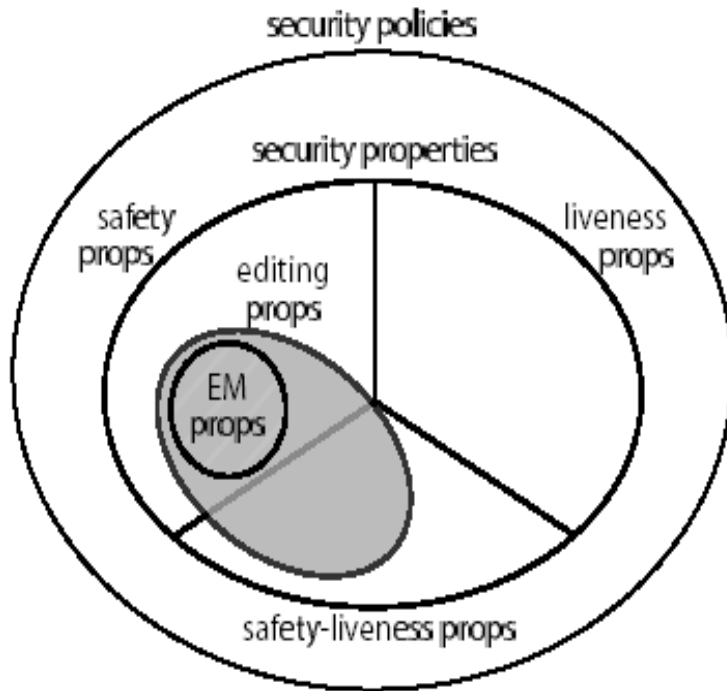


Questions

■ References

- B. Lampson: A note on the confinement problem
- Matt Bishop – Text Book: Computer Security – Art and Science
- P. Gallagher: A Guide to Understanding the Covert Channel Analysis of Trusted Systems [TCSEC – CC Guide]
- Proctor, Neumann: Architectural Implications of Covert Channels
- Sabelfeld, Myers: Language-based information-flow security
- Karger, Wray: Storage Channels in Disk Arm Optimizations
- Alpern, Schneider 87: Recognizing safety and liveness
- Alves, Schneider: Enforceable security policies
- Walker, Bauer, Ligatti: More enforceable security policies
- Osvik, Shamir, Tromer: Cache Attacks and Countermeasures: the Case of AES
- Denning 67: A Lattice Model of Secure Information Flow
- Denning: Certification of programs for secure information flow.
- Hunt, Sands: On flow-sensitive security types
- Volpano, Irvine, Smith: A sound type system for secure inform. flow analysis
- Warnier: Statically checking confidentiality via dynamic labels
- Zheng, Myers: End-to-End Availability Policies and Noninterference
- Shapiro, Smith, Farber: EROS: A Fast Capability System

Security Policies – Safety / Liveness



System:

- Commands $C := \{c_1, c_2, \dots, c_n\}$
- Set of action traces
 $T := \{ \langle c_1 c_2 c_1 \rangle, \langle c_3 c_1 c_6 c_4 \rangle, \dots \}$

Security Policy:

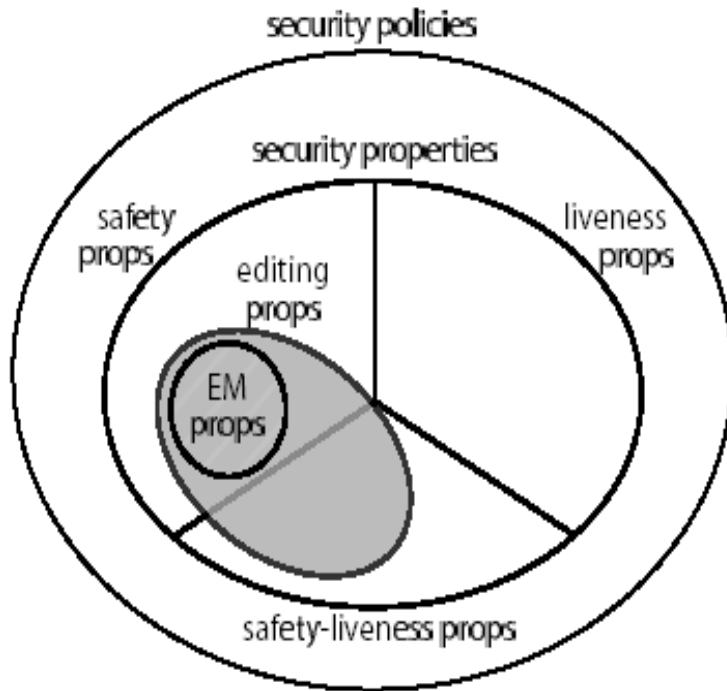
- Predicate on subsets of T

Security Property:

- Predicate on a single trace
 $P(T) := \forall t \in T. P'(t)$

- Security Property:
 - Decision whether system is secure can be made by just observing a single execution of the system
- Security Policy:
 - Can also compare multiple executions of the system

Security Policies – Safety / Liveness



System:

- Commands $C := \{c_1, c_2, \dots, c_n\}$
- Set of action traces
 $T := \{ \langle c_1 c_2 c_1 \rangle, \langle c_3 c_1 c_6 c_4 \rangle, \dots \}$

Example: Noninterference

- Indistinguishable despite variations in high inputs
- $H \subseteq C$ actions $c_i(h)$ on high input (h)
- $c_3 c(h)_6 c_4$ and $c_3 c(h')_6 c_4$ produce I-similar results

=> Noninterference is Security Policy but not a Security Property!

Security Policies – Safety / Liveness



Safety property:

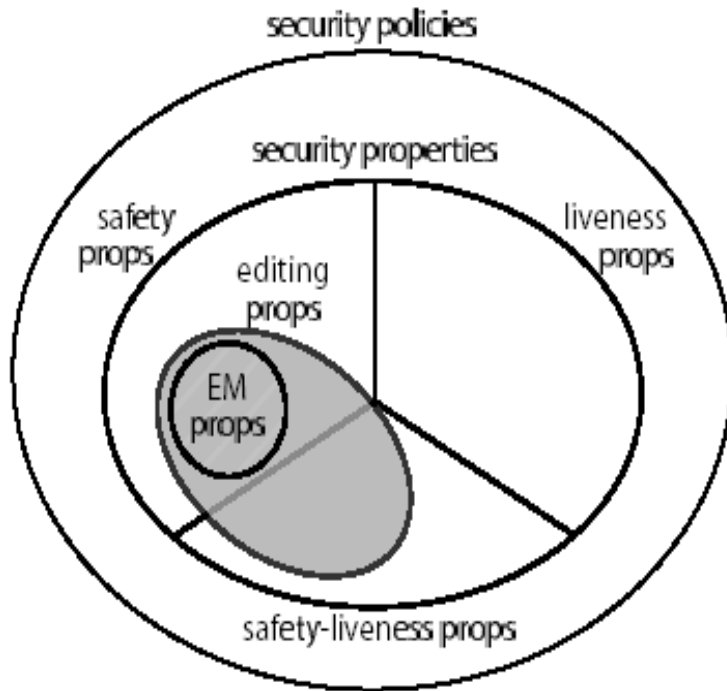
- “Rules out bad things”
- $\neg P(t)$ states that the system is insecure because $\sigma_0 \xrightarrow{t} \sigma'$ and something “bad” is going on in σ'
- $\neg P(t) \Rightarrow \forall t'. \neg P(t t')$
 - A system that is insecure will remain insecure when it continues to execute.

Liveness property:

- “A system can stay good”
 - $\forall \sigma. \exists \sigma'. \sigma \rightarrow^* \sigma' \Rightarrow P(\sigma')$

- Alpern, Schneider [87]: “Recognizing safety and liveness”
 - Any security property can be expressed as a conjunct of safety and liveness properties.

Security Policies – Safety / Liveness



- **Alves, Schneider: “Enforceable Security Policies”**
 - EM automata can only enforce safety properties
- **Walker, Bauer, Ligatti: “More enforceable Sec. Policies”**
 - Edit automata can also enforce some safety+liveness properties
 - Neither EM nor Edit automata can enforce pure liveness properties