

Distributed Operating Systems

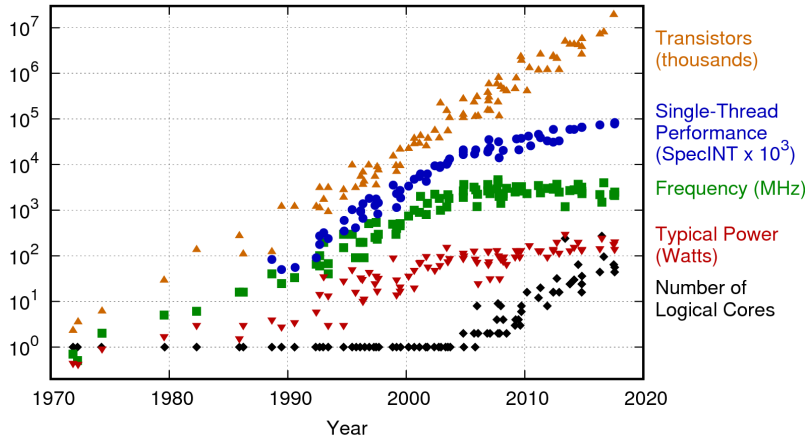
Synchronization in Parallel Systems

TILL SMEJKAL

June 16th, 2025

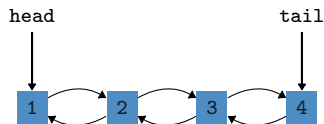
Why do we need synchronization?

42 Years of Microprocessor Trend Data

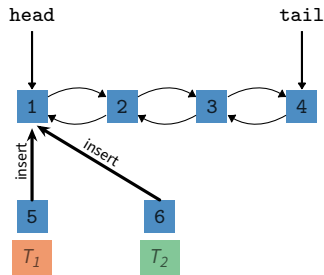


Original data up to the year 2010 collected and plotted by M. Horowitz, F. Labonte, O. Shacham, K. Olukotun, L. Hammond, and C. Batten
New plot and data collected for 2010-2017 by K. Rupp

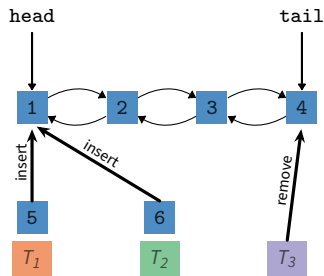
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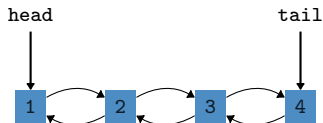
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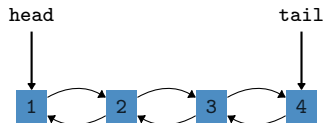


Why do we need synchronization?



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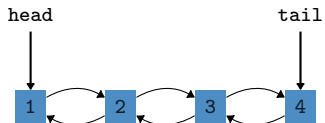
Why do we need synchronization?

 $T_1 \quad T_2$

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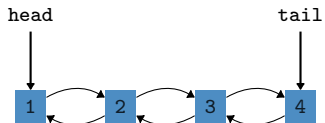
5
 T_1

T_2

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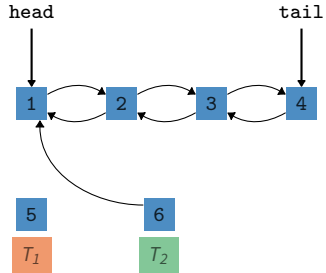
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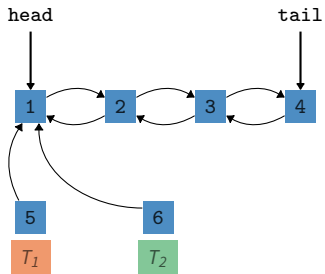
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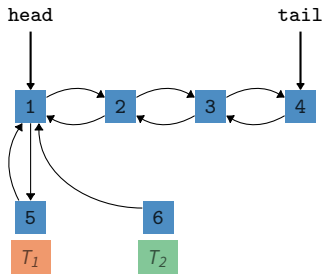
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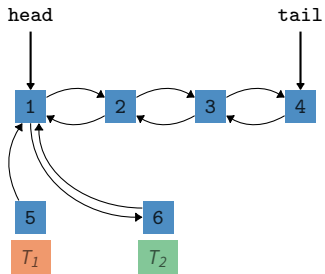
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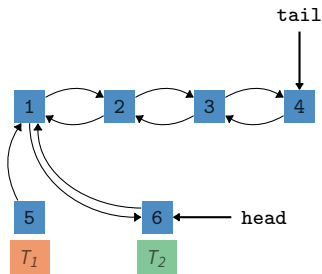
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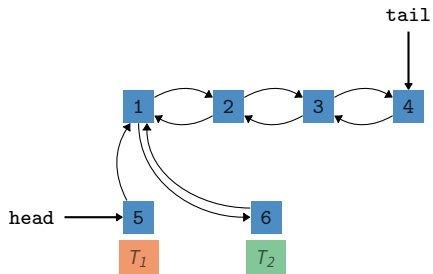
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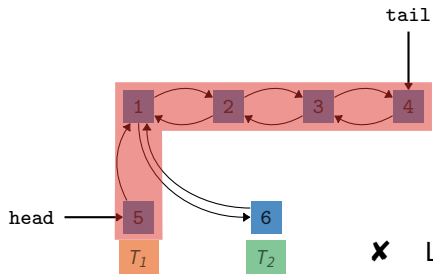
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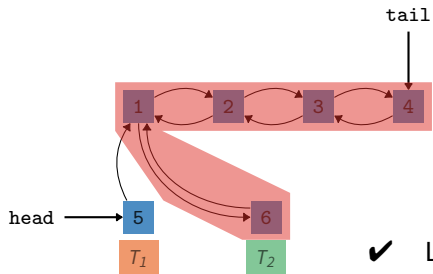
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- ✗ List structure correct
- ✓ head points to start of list

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Content

Basic Principles

Implementing Entersection & Leavesection

Atomicity on Hardware

- Cache Lock
- Observe Cache
- Atomic Instructions

Synchronization with Locks – Part I

- Test & Set Lock
- Test & Test & Set Lock
- Ticket Lock

Synchronization without Locks

Synchronization with Locks – Part II

- MCS Lock

Basic Principles

Atomicity Assumption

$$A \parallel B = A;B \vee B;A$$

Basic Principles

Atomicity Assumption

Parallel execu-
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Sequentiell execu-
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Parallel execution of A and B

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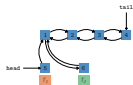
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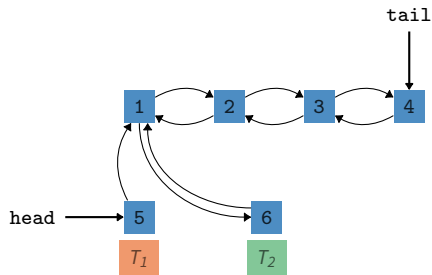
- Otherwise, the outcome of $A \parallel B$ is undefined
- Usually problematic for parallel *Read-Modify-Write* operations

Basic Principles

Mutual Exclusion



A || B



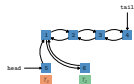
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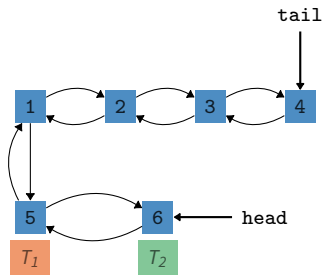
Mutual Exclusion



$A \parallel B$



$A; B$



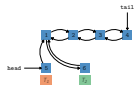
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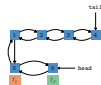
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Basic Principles

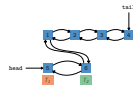
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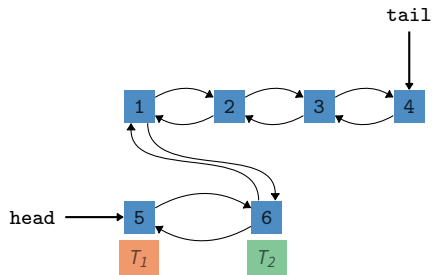
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A; B



B; A



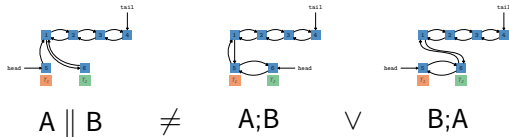
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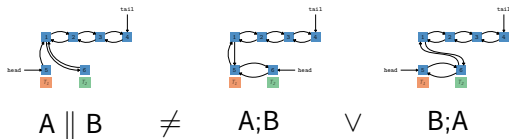
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Basic Principles

Mutual Exclusion



Need to ensure that only one thread at a time can execute the *Read-Modify-Write* operation.

$\Rightarrow$ **Mutual Exclusion**

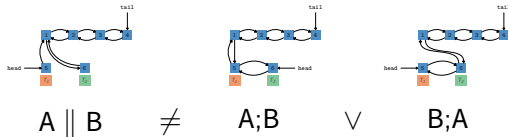
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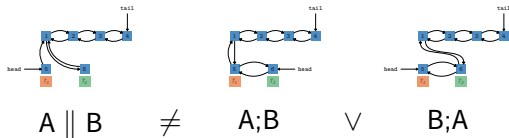
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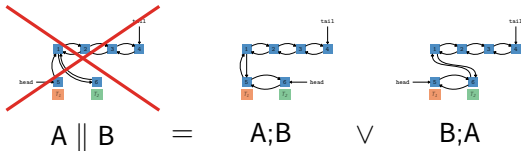
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Should run with mutual exclusion!

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Should run with mutual exclusion!

Basic Principles

Entersection & Leavesection

Simple protocol to establish mutual exclusion for critical sections.

```
1 struct ele_t *new_ele = new ele_t;
2 entersection();
3 new_ele->next = head;
4 head->prev = new_ele;
5 head = new_ele;
6 leavesection();
```

} CS

```
1 void entersection() {
2     while (!cs_free) wait();
3     cs_free = false;
4 }
```

```
1 void leavesection() {
2     cs_free = true;
3     wake_next();
4 }
```

Basic Principles

Entersection & Leavesection

Simple protocol to establish mutual exclusion for critical sections.

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Rules:

- entersection and leavesection *must always* exist in pairs
- entersection *must always* be before the corresponding leavesection

Basic Principles

Entersection & Leavesection

Simple protocol to establish mutual exclusion for critical sections.

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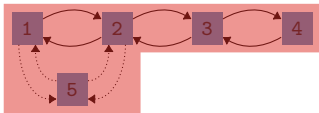
Basic Principles

Coarse Grained vs. Fine Grained

Critical Sections should be as long as necessary but also as short as possible.

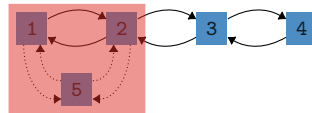
- Length of critical sections are important for scalability → Amdahl's Law

Coarse Grained



- Worse scalability (no parallel operations)
- + Easier to implement

Fine Grained



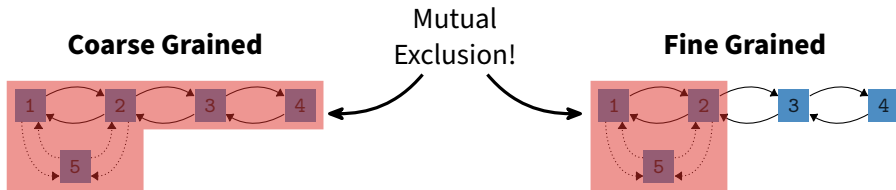
- + Better scalability (parallel operations possible)
- More difficult to implement
- Deadlocks may happen

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Coarse Grained vs. Fine Grained

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- Deadlocks may happen

Implementing Intersection & Leavesection

Peterson Algorithm

```
1 bool free[2] = {true, true};
2 int turn = 0;
3
4 void lock() {
5     int other = 1 - TID;          /* TID: ID of the current thread ({0,1}) */
6     free[TID] = false;
7     turn = other;
8     while (!free[other] && turn == other) {}
9 }
10
11 void unlock() {
12     free[TID] = true;
13 }
```

- Works for two threads (more threads are possible but it gets complicated)
- Requires atomic load and stores and sequential consistency (or additional fence)

Implementing Entersection & Leavesection

Naive Spinlock (*Wrong!*)

```
1 int l = 0;
2
3 void lock() {
4     while (l == 1) {}
5     l = 1;
6 }
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8 void unlock() {
9     l = 0;
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```

- Works for any number of threads
- Simple approach which can work on any hardware architecture

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Diagram illustrating a naive spinlock implementation. The code shows a lock variable `l` initialized to 0. The `lock()` function enters a `while` loop that checks if `l` is equal to 1. If it is, the thread spins. An annotation `l == 0` with an arrow points to the condition `l == 1`, indicating that the condition is false, and the thread should proceed. However, the code is marked as *Wrong!* because it does not ensure mutual exclusion.

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Diagram illustrating a naive spinlock implementation. A variable `l` is initialized to 0. The `lock()` function enters a `while` loop that checks if `l == 1`. If true, it spins. An arrow points from the condition `l == 1` to the loop body, indicating the spin. The `unlock()` function sets `l` back to 0.

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Diagram illustrating a naive spinlock implementation. A green arrow points to the start of the `lock()` function, and an orange arrow points to the `while` loop. A label `l == 0` with a downward arrow indicates the initial state of the lock variable `l`.

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Diagram illustrating a naive spinlock implementation. A variable `l` is initialized to 0. The `lock()` function enters a `while` loop that checks if `l == 1`. If true, it spins (indicated by a green bar). If false, it sets `l = 1` and exits the loop. The diagram shows the state where `l == 0` and the `while` loop condition is being evaluated.

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Naive Spinlock (*Wrong!*)

```
1 int l = 0;
2
3 void lock() {
4     while (l == 1) {}
5     l = 1;
6 }
7
8 void unlock() {
9     l = 0;
10 }
```

```
1 /* do other stuff */
2 lock();
3 /* critical section */
4 unlock();
```

- Works for any number of threads
- Simple approach which can work on any hardware architecture
- Requires solving internal critical section → hardware support

Implementing Entersection & Leavesection

Naive Spinlock (*Wrong!*)

```
1 int l = 0;
2
3 void lock() {
4     while (l == 1) {}
5     l = 1; ←
6 } ←
7
8 void unlock() {
9     l = 0;
10 }
```

```
1 /* do other stuff */
2 lock();
3 /* critical section */
4 unlock();
```

- Works for any number of threads
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Implementing Entersection & Leavesection

Naive Spinlock (*Wrong!*)

```
1 int l = 0;
2
3 void lock() {
4     while (l == 1) {}
5     l = 1; ←
6 }
7
8 void unlock() {
9     l = 0;
10 }
```

```
1 /* do other stuff */
2 lock();
3 /* critical section */ ←
4 unlock();
```

- Works for any number of threads
- Simple approach which can work on any hardware architecture
- Requires solving internal critical section → hardware support

Implementing Entersection & Leavesection

Naive Spinlock (*Wrong!*)

```
1 int l = 0;
2
3 void lock() {
4     while (l == 1) {}
5     l = 1;
6 } ←
7
8 void unlock() {
9     l = 0;
10 }
```

```
1 /* do other stuff */
2 lock();
3 /* critical section */ ←
4 unlock();
```

- Works for any number of threads
- Simple approach which can work on any hardware architecture
- Requires solving internal critical section → hardware support

Implementing Entersection & Leavesection

Naive Spinlock (*Wrong!*)

```
1 int l = 0;
2
3 void lock() {
4     while (l == 1) {}
5     l = 1;
6 }
7
8 void unlock() {
9     l = 0;
10 }
```

```
1 /* do other stuff */
2 lock();
3 /* critical section */ ←
4 unlock();
```

- Works for any number of threads
- Simple approach which can work on any hardware architecture
- Requires solving internal critical section → hardware support

Implementing Entersection & Leavesection

Naive Spinlock (*Wrong!*)

```
1 int l = 0;
2
3 void lock() {
4     while (l == 1) {}
5     l = 1;
6 }
7
8 void unlock() {
9     l = 0;
10 }
```

```
1 /* do other stuff */
2 lock();
3 /* critical section */ ⚡
4 unlock();
```

- Works for any number of threads
- Simple approach which can work on any hardware architecture
- Requires solving internal critical section → hardware support

Implementing Entersection & Leavesection

Naive Spinlock (*Wrong!*)

```
1 int l = 0;
2
3 void lock() {
4     while (l == 1) {} } CS (internal)
5     l = 1;
6 }
7
8 void unlock() {
9     l = 0;
10 }
```

```
1 /* do other stuff */
2 lock();
3 /* critical section */ ⚡
4 unlock();
```

- Works for any number of threads
- Simple approach which can work on any hardware architecture
- Requires solving internal critical section → hardware support

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A; B \vee B; A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 cmp [x] $0;  
2 jne retry;
```

Core 2

```
1 mov $1 [x];
```

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax;  
2 cmp %eax $0;  
3 jne retry;
```

Core 2

```
1 store $1 [x];
```

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax;  
2 cmp %eax $0;  
3 jne retry;
```

Core 2

```
1 store $1 [x];
```

Core 1

Memory

x:0

Core 2

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax; ←  
2 cmp %eax $0;  
3 jne retry;
```

Core 2

```
1 store $1 [x];
```

Core 1

eax:0

Memory

x:0

Load(x)

Core 2

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax; ←  
2 cmp %eax $0;  
3 jne retry;
```

Core 2

```
1 store $1 [x]; ←
```

Core 1

eax:0

Memory

x:1

Core 2

Store(x)

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax;  
2 cmp %eax $0;  
3 jne retry;
```

Core 2

```
1 store $1 [x];
```

Core 1

eax:0

Memory

x:1

Core 2

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax;  
2 cmp %eax $0; ⚡  
3 jne retry;
```

Comparison with 0
although x == 1 already

Core 2

```
1 store $1 [x]; ←
```

Core 1

eax:0

Memory

x:1

Core 2

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 add [x] $1;
```

Core 2

```
1 mov $2 [x];
```


Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax;  
2 add %eax $1;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x];
```

Core 1

Memory

x:0

Core 2

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax; ←  
2 add %eax $1;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x];
```

Core 1

eax:0

Memory

x:0

Load(x)

Core 2

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax; ←  
2 add %eax $1;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x]; ←
```

Core 1

eax:0

Memory

x:2

Core 2

Store(x)

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A; B \vee B; A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax;  
2 add %eax $1;   
3 store %eax [x];
```

Core 2

```
1 store $2 [x]; 
```

Core 1

eax:1

Memory

x:2

Core 2

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax;  
2 add %eax $1;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x];
```

Core 1

eax:1

Memory

x:1

Store(x)

Core 2

Atomicity on Hardware

Atomicity Assumption on Hardware

$$A \parallel B = A;B \vee B;A$$

- Always guaranteed for single-core systems
- Usually not guaranteed for multi-core systems
- Especially problematic for *Read-Modify-Write* instructions

Core 1

```
1 load [x] %eax;
2 add %eax $1;
3 store %eax [x];
```

Core 1

eax: 1

Core 2

```
1 store $2 [x];
```

Core 2

x == 1 although
A;B: x == 2 or B;A: x == 3

Memory

x: 1 ⚡

Atomicity on Hardware

Atomic Hardware Instructions

How to make instructions atomic?

- Bus Lock
 - Lock whole memory bus until all memory accesses of instruction are completed
 - Used in older x86 CPUs (Intel® Pentium 3 and older)
 - Uses `lock` assembler attribute

Atomicity on Hardware

Atomic Hardware Instructions

How to make instructions atomic?

- Bus Lock
 - Lock whole memory bus until all memory accesses of instruction are completed
 - Used in older x86 CPUs (Intel® Pentium 3 and older)
 - Uses `lock` assembler attribute
- Cache Lock
 - Delay cache coherency traffic until all memory accesses of instruction are completed
 - Used in newer x86 CPUs (Intel® Pentium 4 and newer)
 - Special atomic instructions (e.g. `cmpxchg` or `xadd`)

Atomicity on Hardware

Atomic Hardware Instructions

How to make instructions atomic?

- Bus Lock
 - Lock whole memory bus until all memory accesses of instruction are completed
 - Used in older x86 CPUs (Intel® Pentium 3 and older)
 - Uses `lock` assembler attribute
- Cache Lock
 - Delay cache coherency traffic until all memory accesses of instruction are completed
 - Used in newer x86 CPUs (Intel® Pentium 4 and newer)
 - Special atomic instructions (e.g. `cmpxchg` or `xadd`)
- Observe Cache
 - Install watchdog on load and check at corresponding store if a concurrent access happened and abort
 - Used on arm and Alpha CPUs
 - Uses special `ldrex` and `strex` instructions

Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 add $1 [x];
```

Core 2

```
1 mov $2 [x];
```

Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x];
```

Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x];
```

Core 1

x:0 → S

Memory

x:0

Core 2

x:0 → S

Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

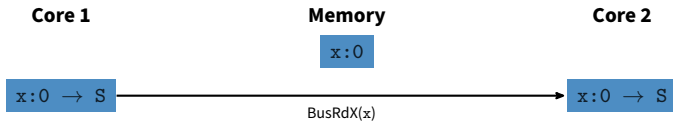
Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax; ←  
2 add $1 %eax;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x];
```



Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

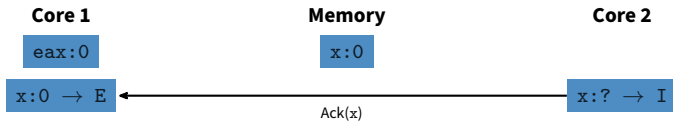
Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax; ←  
2 add $1 %eax;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x];
```



Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax; ←  
3 store %eax [x];
```

Core 2

```
1 store $2 [x];
```

Core 1

eax:1

x:0 → E

Memory

x:0

Core 2

x:? → I

Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax; ←  
3 store %eax [x];
```

Core 2

```
1 store $2 [x]; ←
```

Core 1

eax:1

x:0 → E

Memory

x:0

Core 2

x:? → I

Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

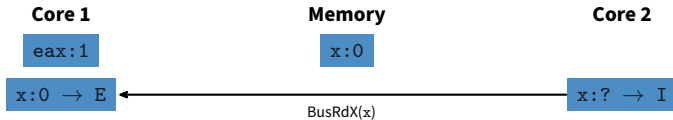
Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax; ←  
3 store %eax [x];
```

Core 2

```
1 store $2 [x]; ←
```



Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

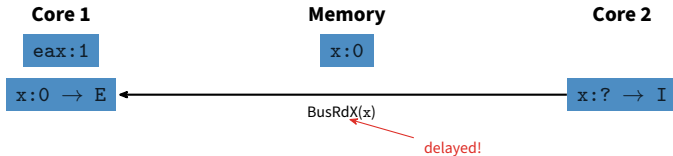
Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax; ←  
3 store %eax [x];
```

Core 2

```
1 store $2 [x]; ←
```



Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

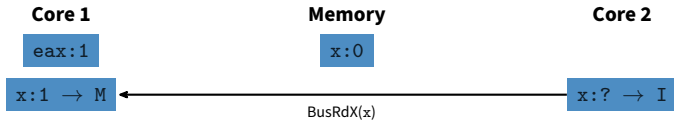
Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax;  
3 store %eax [x]; ←
```

Core 2

```
1 store $2 [x]; ←
```



Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

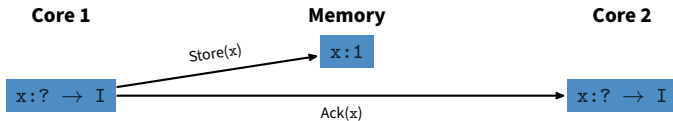
Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax;  
3 store %eax [x]; ←
```

Core 2

```
1 store $2 [x]; ←
```



Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x]; ←
```

Core 1

x: ? → I

Memory

x: 1

Load(x)

Core 2

x: 1 → E

Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x]; ←
```

Core 1

x:? → I

Memory

x:1

Core 2

x:2 → M

Atomicity on Hardware

Atomic Instructions with Cache Lock

General Idea

Delay all cache coherency traffic (*snoop messages*) until all memory accesses of an *atomic* Read-Modify-Write instruction are finished.

Core 1

```
1 loadx [x] %eax;  
2 add $1 %eax;  
3 store %eax [x];
```

Core 2

```
1 store $2 [x];
```

Core 1

x:? → I

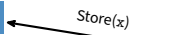
Memory

x:2

Core 2

x:? → I

Store(x)



Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 add $1 [x];
```

Core 2

```
1 mov $2 [x];
```

Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax;  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x];
```

Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax;  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x];
```

Core 1

x:0 → S

Memory

x:0

Core 2

x:0 → S

Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

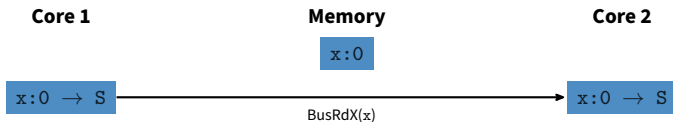
Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax; ←  
2 add $1 %eax;  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x];
```



Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

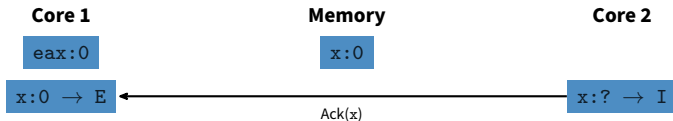
Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax; ←  
2 add $1 %eax;  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x];
```



Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax; ←  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x];
```

Core 1

eax:1

x:0 → E

Memory

x:0

Core 2

x:? → I

Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax;  
3 strex %eax [x]; ←
```

Core 2

```
1 store $2 [x];
```

Core 1

x:1 → M

Memory

x:0

Core 2

x:? → I

Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

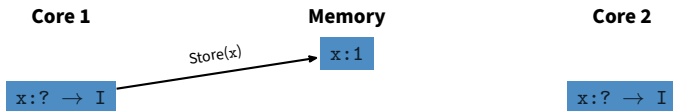
Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax;  
3 strex %eax [x]; ← ✓ Success
```

Core 2

```
1 store $2 [x];
```



Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

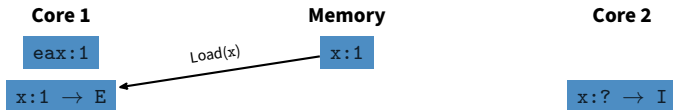
Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax; ←  
2 add $1 %eax;  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x];
```



Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax; ←  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x];
```

Core 1

eax:2

x:1 → E

Memory

x:1

Core 2

x:? → I

Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

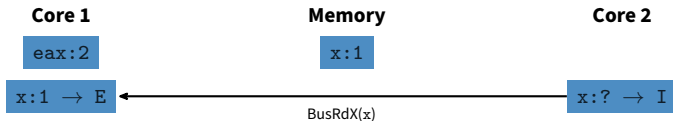
Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax; ←  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x]; ←
```



Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

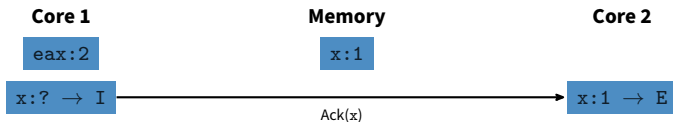
Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax; ←  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x]; ←
```



Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax; ←  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x]; ←
```

Core 1

eax:2

x:? → I

Memory

x:1

Core 2

x:2 → M

Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax; ←  
3 strex %eax [x];
```

Core 2

```
1 store $2 [x];
```

Core 1

eax:2

x:? → I

Memory

x:2

Core 2

x:? → I

Store(x)

Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax;  
3 strex %eax [x]; ←
```

Core 2

```
1 store $2 [x];
```

Core 1

eax:2

x:? → I

Memory

x:2

Core 2

Atomicity on Hardware

Atomic Instructions with Observe Cache

General Idea

Install a watchdog when the *atomic* instruction references the memory location and check for parallel accesses before storing to the memory location again. In case of parallel accesses, abort the store and retry the whole *atomic* instruction.

Core 1

```
1 ldrex [x] %eax;  
2 add $1 %eax;  
3 strex %eax [x]; ← ✗ Abort
```

Core 2

```
1 store $2 [x];
```

Core 1

eax:2

x:? → I

Memory

x:2

Core 2

Atomicity on Hardware

Examples of Atomic Instructions

- `swap(mem1, mem2)`

```
1 mov [mem1] %eax;  
2 mov [mem2] [mem1];  
3 mov %eax [mem2];
```

- `xadd(mem, reg)`

```
1 mov [mem] %eax;  
2 add [mem] reg;  
3 return %eax;
```

- `cas(mem, expected, desired)`

```
1 cmp [mem] [expected];  
2 jne fail;  
3 mov [desired] [mem];  
4 return true;  
5 fail: return false;
```

Synchronization with Locks

Properties

Main Properties

- Mutual Exclusion
 - Required by every *correct* implementation of the Entersection & Leavesection protocol
- Overhead
 - Acquiring a lock should be a cheap operation
 - If the lock is currently free, acquiring the lock should be especially cheap
- Fairness
 - Every thread should be able to acquire the lock eventually

Synchronization with Locks

Properties

Advanced Properties

- Concurrent access to critical section
 - Allow multiple threads to acquire the lock simultaneously
- Abort pending lock operations
 - Abort acquiring a currently taken lock after a timeout
 - Kill threads currently acquiring a lock
- Lock holder preemption
 - Prevent the threads currently holding the lock from making progress
- Priority inversion
 - Prevent higher priority threads from making progress because of a lower priority thread holding a shared lock
- Spinning vs. Blocking

Test & Set Lock

```
1 struct ts_lock_t {
2     volatile int lock;
3 };

4 void lock(ts_lock_t *l) {
5     do {
6         int tmp = 1;
7         swap(&(l->lock), &(tmp));
8     } while (tmp == 1);
9 }

11 void unlock(ts_lock_t *l) {
12     l->lock = 0;
13 }
```

- Very easy to implement
- Only requires one atomic instruction

But

- High cache-coherency bus traffic when lock is taken
- No fairness between threads

Test & Set Lock

Overhead

```
1 struct ts_lock_t {
2     volatile int lock;
3 };

4 void lock(ts_lock_t *l) {
5     do {
6         int tmp = 1;
7         swap(&(l->lock), &(tmp));
8     } while (tmp == 1);
9 }

11 void unlock(ts_lock_t *l) {
12     l->lock = 0;
13 }
```

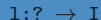
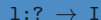
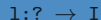
```
1 struct ts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */
5     lock(&l);
6     /* CS */
7     unlock(&l);
8 }
```

Test & Set Lock

Overhead

```
1 struct ts_lock_t {
2     volatile int lock;
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4
4 void lock(ts_lock_t *l) {
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6         int tmp = 1;
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1 struct ts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */
5     lock(&l);
6     /* CS */
7     unlock(&l);
8 }
```

Core 1l:? → I**Core 2**l:? → I**Core 3**l:? → I

Test & Set Lock

Overhead

```
1 struct ts_lock_t {
2     volatile int lock;
3 };
4
4 void lock(ts_lock_t *l) {
5     do {
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8     } while (tmp == 1);
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11 void unlock(ts_lock_t *l) {
12     l->lock = 0;
13 }
```

```
1 struct ts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */ ←
5     lock(&l); ←
6     /* CS */
7     unlock(&l);
8 }
```

Core 1

l:? → I

Core 2

l:? → I

Core 3

l:? → I

Test & Set Lock

Overhead

```
1 struct ts_lock_t {
2     volatile int lock;
3 };
4
4 void lock(ts_lock_t *l) {
5     do {
6         int tmp = 1; ←
7         swap(&(l->lock), &(tmp));
8     } while (tmp == 1);
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```

```
1 struct ts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */ ←
5     lock(&l);
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7     unlock(&l);
8 }
```

Core 1**1: ? → I****Core 2****1: ? → I****Core 3****1: ? → I**

Test & Set Lock

Overhead

```
1 struct ts_lock_t {
2     volatile int lock;
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4 void lock(ts_lock_t *l) {
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1 struct ts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */ ←
5     lock(&l);
6     /* CS */
7     unlock(&l);
8 }
```

Core 1

l:1 → M

Core 2

l:? → I

Core 3

l:? → I

Test & Set Lock

Overhead

```
1 struct ts_lock_t {
2     volatile int lock;
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4 void lock(ts_lock_t *l) {
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3 void thread_fn(void) {
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8 }
```

Core 1

l:1 → M

Core 2

l:? → I

Core 3

l:? → I

Test & Set Lock

Overhead

```
1 struct ts_lock_t {
2     volatile int lock;
3 };
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4 void lock(ts_lock_t *l) {
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3 void thread_fn(void) {
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8 }
```

Core 1

l:1 → M

Core 2

l:? → I

Core 3

l:? → I

Test & Set Lock

Overhead

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1 struct ts_lock_t {
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4     /* Other stuff */
5     lock(&l);
6     /* CS */
7     unlock(&l);
8 }
```

Core 1

l:1 → M

Core 2

l:? → I

Core 3

l:? → I

Test & Set Lock

Overhead

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1 struct ts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */ ←
5     lock(&l);
6     /* CS */ ←
7     unlock(&l);
8 }
```

Core 1

l:1 → M

Core 2

l:? → I

Core 3

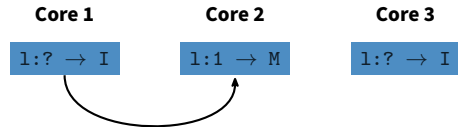
l:? → I

Test & Set Lock

Overhead

```
1 struct ts_lock_t {
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3 };
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Test & Set Lock

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2
3 void thread_fn(void) {
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5     lock(&l);
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```

Core 1**l: ? → I****Core 2****l: 1 → M****Core 3****l: ? → I**

Test & Set Lock

Overhead

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7     unlock(&l);
8 }
```

Core 1

l:? → I

Core 2

l:1 → M

Core 3

l:? → I

Test & Set Lock

Overhead

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```

Core 1

l:? → I

Core 2

l:1 → M

Core 3

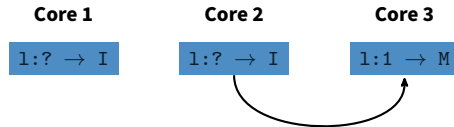
l:? → I

Test & Set Lock

Overhead

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Test & Set Lock

Overhead

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```

Core 1 $l: ? \rightarrow I$ **Core 2** $l: ? \rightarrow I$ **Core 3** $l: 1 \rightarrow M$

Test & Set Lock

Overhead

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1 struct ts_lock_t l;
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7     unlock(&l);
8 }
```

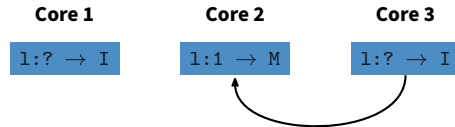
Core 1 $l: ? \rightarrow I$ **Core 2** $l: ? \rightarrow I$ **Core 3** $l: 1 \rightarrow M$

Test & Set Lock

Overhead

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Test & Set Lock

Overhead

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2
3 void thread_fn(void) {
4     /* Other stuff */
5     lock(&l);
6     /* CS */ ←
7     unlock(&l);
8 }
```

Core 1

l:? → I

Core 2

l:1 → M

Core 3

l:? → I

Test & Test & Set Lock

```
1 struct tts_lock_t {
2     volatile int lock;
3 };

4 void lock(tts_lock_t *l) {
5     do {
6         int tmp = 1;
7         do {} while (l->lock == 1);
8         swap(&(l->lock), &(tmp));
9     } while (tmp == 1);
10 }

11 void unlock(tts_lock_t *l) {
12     l->lock = 0;
13 }
```

- As simple as Test & Set Lock but with less cache traffic
- Most widespread lock implementation

But

- No fairness between threads

Test & Test & Set Lock

Overhead

```
1 struct tts_lock_t {
2     volatile int lock;
3 };

4 void lock(tts_lock_t *l) {
5     do {
6         int tmp = 1;
7         do {} while (l->lock == 1);
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1 struct tts_lock_t l;
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3 void thread_fn(void) {
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8 }
```

Test & Test & Set Lock

Overhead

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1 struct tts_lock_t {
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```

```
1 struct tts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */
5     lock(&l);
6     /* CS */
7     unlock(&l);
8 }
```

Core 1

l:? → I

Core 2

l:? → I

Core 3

l:? → I

Test & Test & Set Lock

Overhead

```
1 struct tts_lock_t {
2     volatile int lock;
3 };
4
4 void lock(tts_lock_t *l) {
5     do {
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```
1 struct tts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */ ←
5     lock(&l); ←
6     /* CS */
7     unlock(&l);
8 }
```

Core 1

l:? → I

Core 2

l:? → I

Core 3

l:? → I

Test & Test & Set Lock

Overhead

```
1 struct tts_lock_t {
2     volatile int lock;
3 };
4
5 void lock(tts_lock_t *l) {
6     do {
7         int tmp = 1;
8         do {} while (l->lock == 1);
9         swap(&(l->lock), &(tmp));
10    } while (tmp == 1);
11 }
12
13 void unlock(tts_lock_t *l) {
14     l->lock = 0;
15 }
```

```
1 struct tts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */
5     lock(&l);
6     /* CS */
7     unlock(&l);
8 }
```

Core 1

l:? → I

Core 2

l:? → I

Core 3

l:? → I

Test & Test & Set Lock

Overhead

```
1 struct tts_lock_t {
2     volatile int lock;
3 };
4
5 void lock(tts_lock_t *l) {
6     do {
7         int tmp = 1;
8         do {} while (l->lock == 1); ←
9         swap(&(l->lock), &(tmp));
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11 }
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13 void unlock(tts_lock_t *l) {
14     l->lock = 0;
15 }
```

```
1 struct tts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */ ←
5     lock(&l);
6     /* CS */
7     unlock(&l);
8 }
```

Core 1

l:0 → E

Core 2

l:? → I

Core 3

l:? → I

Test & Test & Set Lock

Overhead

```
1 struct tts_lock_t {
2     volatile int lock;
3 };

4 void lock(tts_lock_t *l) {
5     do {
6         int tmp = 1;
7         do {} while (l->lock == 1);
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```

```
1 struct tts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */ ←
5     lock(&l);
6     /* CS */
7     unlock(&l);
8 }
```

Core 1

l:1 → M

Core 2

l:? → I

Core 3

l:? → I

Test & Test & Set Lock

Overhead

```
1 struct tts_lock_t {
2     volatile int lock;
3 };
4
5 void lock(tts_lock_t *l) {
6     do {
7         int tmp = 1;
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```
1 struct tts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */ ←
5     lock(&l);
6     /* CS */
7     unlock(&l);
8 }
```

Core 1

l:1 → M

Core 2

l:? → I

Core 3

l:? → I

Test & Test & Set Lock

Overhead

```
1 struct tts_lock_t {
2     volatile int lock;
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4 void lock(tts_lock_t *l) {
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1 struct tts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */ ←
5     lock(&l);
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7     unlock(&l);
8 }
```

Core 1

l:1 → M

Core 2

l:? → I

Core 3

l:? → I

Test & Test & Set Lock

Overhead

```
1 struct tts_lock_t {
2     volatile int lock;
3 };
4
5 void lock(tts_lock_t *l) {
6     do {
7         int tmp = 1;
8         do {} while (l->lock == 1);
9         swap(&(l->lock), &(tmp));
10    } while (tmp == 1);
11 }
12
13 void unlock(tts_lock_t *l) {
14     l->lock = 0;
15 }
```

```
1 struct tts_lock_t l;
2
3 void thread_fn(void) {
4     /* Other stuff */
5     lock(&l);
6     /* CS */
7     unlock(&l);
8 }
```

Core 1

l:1 → M

Core 2

l:? → I

Core 3

l:? → I

Test & Test & Set Lock

Overhead

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Core 1

l:1 → M

Core 2

l:? → I

Core 3

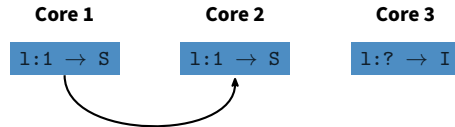
l:? → I

Test & Test & Set Lock

Overhead

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Test & Test & Set Lock

Overhead

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Core 1

l:1 → S

Core 2

l:1 → S

Core 3

l:? → I

Test & Test & Set Lock

Overhead

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Core 1

l:1 → S

Core 2

l:1 → S

Core 3

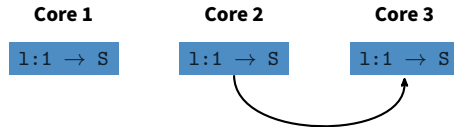
l:? → I

Test & Test & Set Lock

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Test & Test & Set Lock

Overhead

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Core 1

l:1 → S

Core 2

l:1 → S

Core 3

l:1 → S



Test & Test & Set Lock

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Core 1

l:1 → S

Core 2

l:1 → S

Core 3

l:1 → S



Test & Test & Set Lock

Fairness

```
1 struct tts_lock l;  
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3 void thread_fn(void) {  
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 T_1 T_2 T_3

Test & Test & Set Lock

Fairness

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 T_1 T_2 T_3

Test & Test & Set Lock

Fairness

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 T_1 T_2 T_3

Test & Test & Set Lock

Fairness

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 T_1 T_2 T_3

Test & Test & Set Lock

Fairness

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 T_1 T_2 T_3

Test & Test & Set Lock

Fairness

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 T_1 T_2 T_3

lock

Test & Test & Set Lock

Fairness

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 T_1  T_2  T_3

lock

Test & Test & Set Lock

Fairness

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 T_1  T_2  T_3

lock

Test & Test & Set Lock

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 T_1  T_2  T_3

lock

Test & Test & Set Lock

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 T_1

lock

 T_2

test

 T_3

Test & Test & Set Lock

Fairness

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 T_1

lock

 T_2

test

 T_3

Test & Test & Set Lock

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 T_1

lock

 T_2

test

 T_3

Test & Test & Set Lock

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 T_1

lock

 T_2

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Test & Test & Set Lock

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 T_1

lock

unlock

 T_2

test

 T_3

test

Test & Test & Set Lock

Fairness

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```

 T_1

lock

unlock

 T_2

test

 T_3

test

Test & Test & Set Lock

Fairness

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 T₁

lock

unlock


 T₂

test

lock


 T₃

test

Test & Test & Set Lock

Fairness

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 T₁

lock

unlock


 T₂

test

lock


 T₃

test

Test & Test & Set Lock

Fairness

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 T₁

lock

unlock


 T₂

test

lock


 T₃

test

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Test & Test & Set Lock

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 T₁

lock

unlock


 T₂

test

lock

unlock


 T₃

test

test

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 T₁

lock

unlock


 T₂

test

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unlock


 T₃

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 T₁

lock

unlock


 T₂

test

lock

unlock


 T₃

test

test

Test & Test & Set Lock

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 T₁

lock

unlock


 T₂

test

lock

unlock


 T₃

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```


 T₁

lock

unlock


 T₂

test

lock

unlock


 T₃

test

test

Test & Test & Set Lock

Fairness

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 T₁

lock

unlock

lock


 T₂

test

lock

unlock


 T₃

test

test

Test & Test & Set Lock

Fairness

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```


 T₁

lock

unlock

lock


 T₂

test

lock

unlock


 T₃

test

test

Test & Test & Set Lock

Fairness

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```


 T₁

lock

unlock

lock


 T₂

test

lock

unlock


 T₃

test

test

test

Ticket Lock

```
1 struct ticket_lock_t {
2     int next;
3     volatile int current;
4 };

5 void lock(ticket_lock_t *l) {
6     int t = xadd(&(l->next), 1);
7     do {} while (l->current != t);
8 }

10 void unlock(ticket_lock_t *l) {
11     l->current++;
12 }
```

- As simple and cheap as Test & Test & Set Lock
- Ensures fairness between threads

But

- High bus traffic on `unlock`
- Aborting `lock` is difficult

Ticket Lock

Fairness

```

1 struct ticket_lock_t l;
2
3 void thread_fn(void) {
4     while (true) {
5         /* Other stuff */
6         lock(&l);
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8         unlock(&l);
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13     int t = xadd(&(l->next), 1);
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15 }
16
17 void unlock(ticket_lock_t *l) {
18     l->current++;
19 }

```


 T_1

 T_2

 T_3
 T_1 T_2 T_3

t

l.next: 0

l.current: 0

Ticket Lock

Fairness

```

1 struct ticket_lock_t l;
2
3 void thread_fn(void) {
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18     l->current++;
19 }

```

 T_1 T_2 T_3 T_1 T_2 T_3

t

l.next: 0

l.current: 0

Ticket Lock

Fairness

```

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17 void unlock(ticket_lock_t *l) {
18     l->current++;
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```


 T_1

 T_2

 T_3

lock

 T_1 T_2 T_3

t

l.next: 0

l.current: 0

Ticket Lock

Fairness

```

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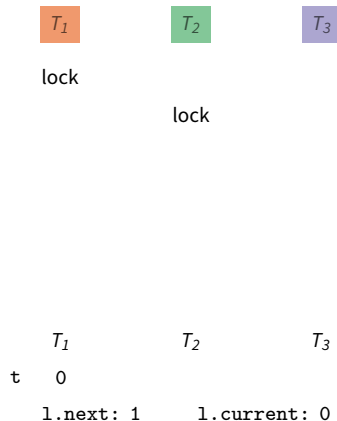
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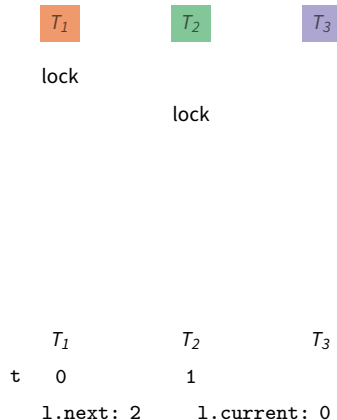
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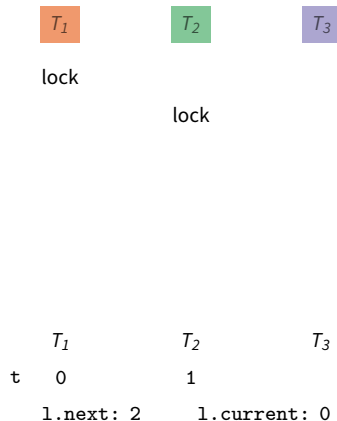
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Ticket Lock

Fairness

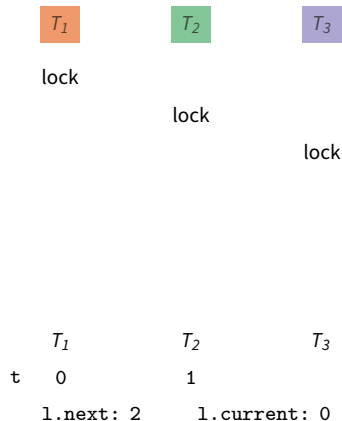
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Ticket Lock

Fairness

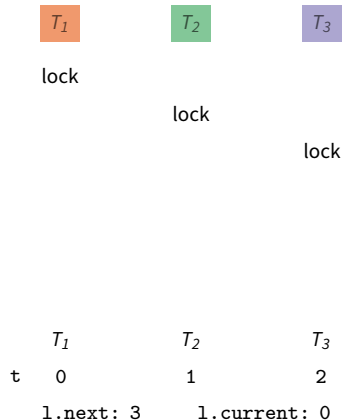
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Ticket Lock

Fairness

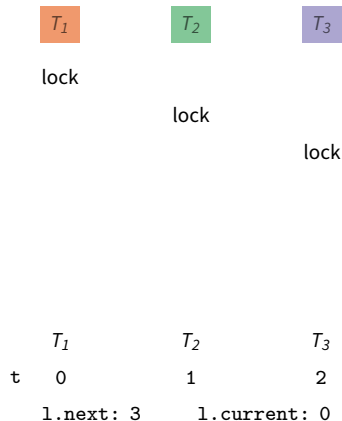
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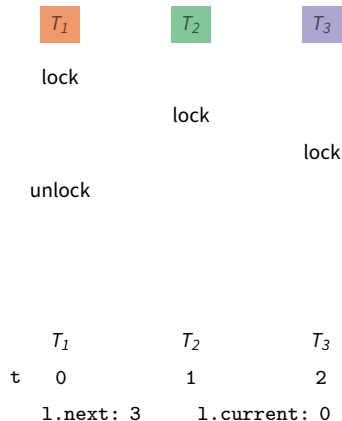
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Fairness

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```



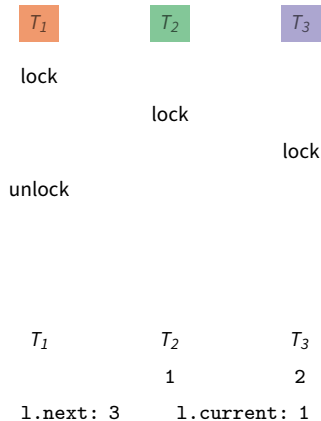
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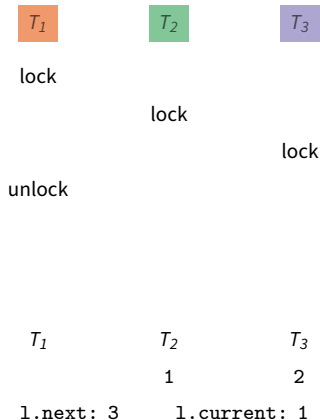
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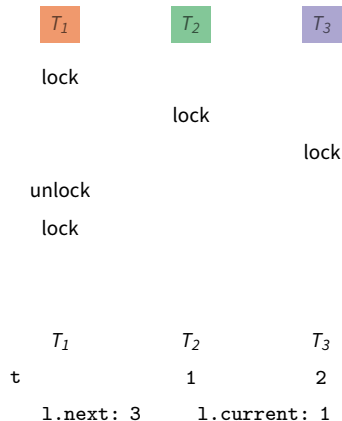
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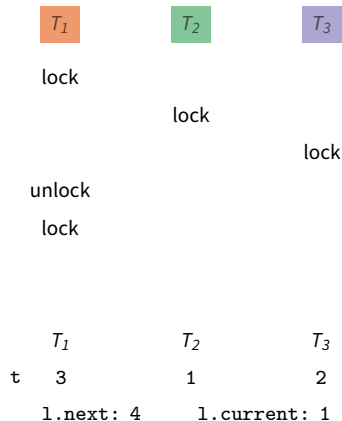
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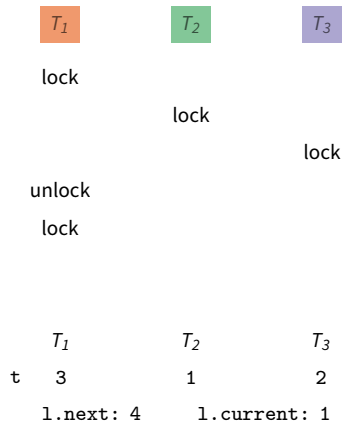
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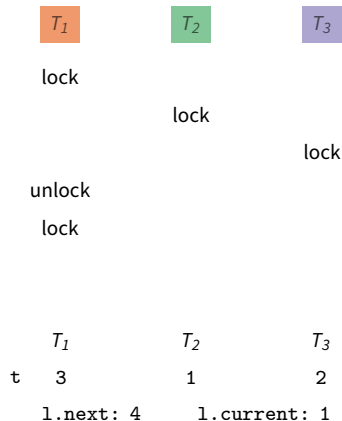
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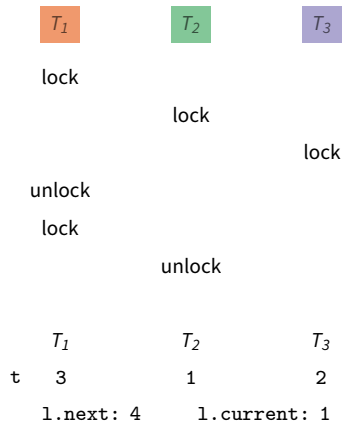
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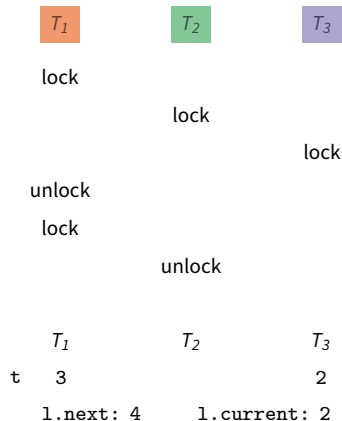
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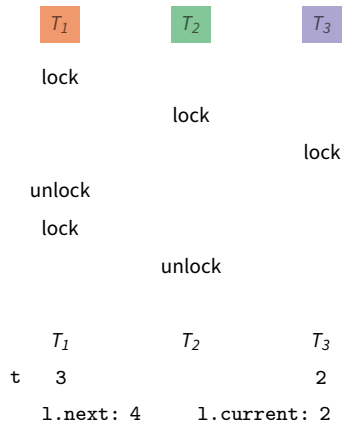
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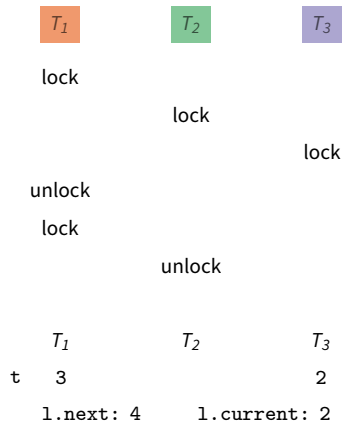
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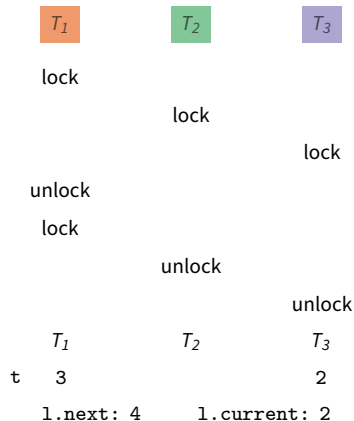
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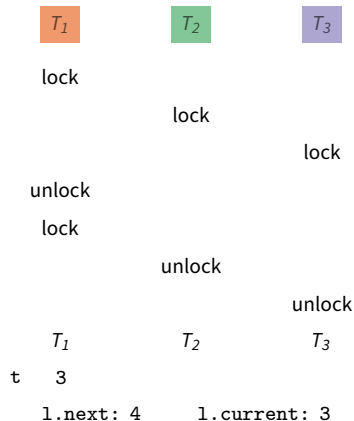
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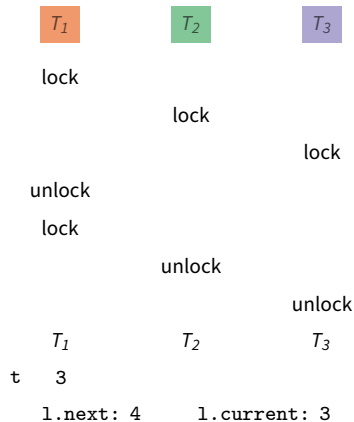
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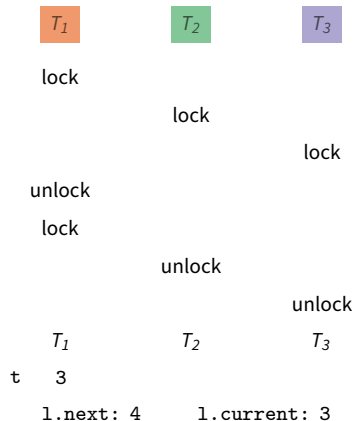
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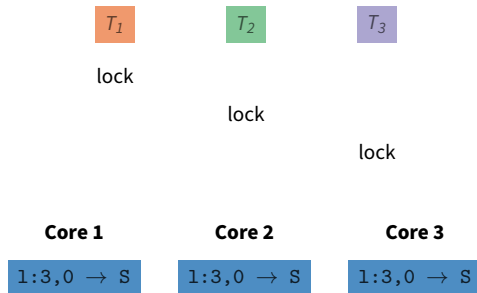
Ticket Lock

Overhead

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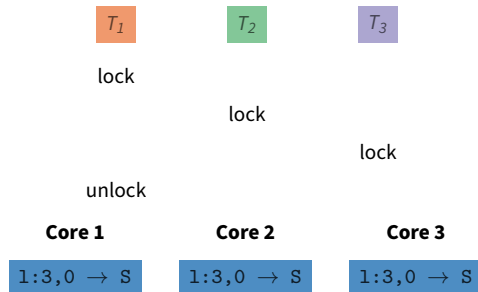
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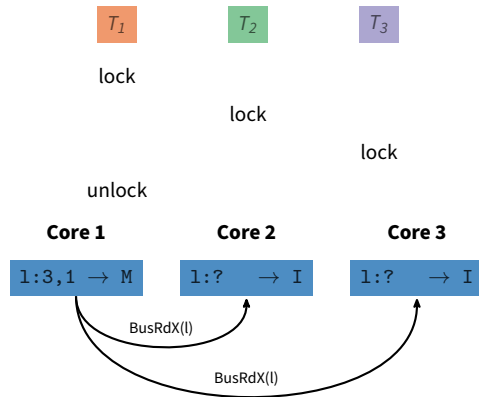
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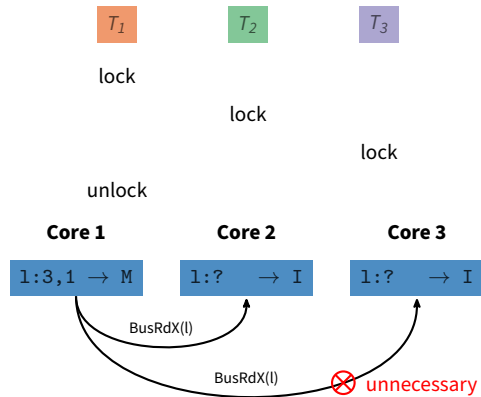
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```



Lock-Free Data Structures

Many data structures can be implemented without the usage of locks but instead directly with atomic hardware instructions.

- Single-Linked List

```
1 void insert(ele_t *new_ele, ele_t *prev) {  
2     do {  
3         new_ele->next = prev->next;  
4     } while (!cas(&(prev->next), new_ele->next, new_ele));  
5 }
```

Lock-Free Data Structures

Many data structures can be implemented without the usage of locks but instead directly with atomic hardware instructions.

- Single-Linked List
- Double-Linked List

```
1 void insert(ele_t *new_ele, ele_t *prev) {  
2     do {  
3         new_ele->next = prev->next;  
4         new_ele->prev = prev;  
5     } while (!dcas(&(prev->next), &(prev->next->prev),  
6                  new_ele->next, new_ele->prev,  
7                  new_ele, new_ele));  
8 }
```

Lock-Free Data Structures

Many data structures can be implemented without the usage of locks but instead directly with atomic hardware instructions.

- Single-Linked List
- Double-Linked List
- Binary Tree

Lock-Free Data Structures

Many data structures can be implemented without the usage of locks but instead directly with atomic hardware instructions.

- Single-Linked List
- Double-Linked List
- Binary Tree
- Red-Black Tree

Mellor-Crummey and Scott (MCS Lock)

```
1 struct mcs_node_t {           6 struct mcs_lock_t {
2     mcs_node_t *next;         7     mcs_node_t *queue;
3     bool free;                 8 };
4 };
5
10 void lock(mcs_lock_t *l, mcs_node_t *cur) {
11     cur->next = NULL; cur->free = false;
12     auto prev = fetch_and_store(&(l->queue), cur);
13     if (prev) {
14         prev->next = cur;
15         do {} while (!cur->free);
16     }
17 }
18
19 void unlock(mcs_lock_t *l, mcs_node_t *cur) {
20     if (!cur->next) {
21         if (cas(&(l->queue), cur, NULL)) return;
22         do {} while (!cur->next);
23     }
24     cur->next->free = true;
25 }
```

- Fair between threads
- Only local spinning
- No unnecessary cache trashing
- Easy to abort lock operation

But:

- Difficult to implement correctly

MCS Lock

Fairness & Overhead

```

1 struct mcs_node_t {
2     mcs_node_t *next;
3     bool free;
4 };
5
6 void lock(mcs_lock_t *l, mcs_node_t *cur) {
7     cur->next = NULL; cur->free = false;
8     auto prev = fetch_and_store(&(l->queue), cur);
9     if (prev) {
10         prev->next = cur;
11         do {} while (!cur->free);
12     }
13 }
14
15 void unlock(mcs_lock_t *l, mcs_node_t *cur) {
16     if (!cur->next) {
17         if (cas(&(l->queue), cur, NULL)) return;
18         do {} while (!cur->next);
19     }
20     cur->next->free = true;
21 }

```

```

1 struct mcs_lock_t l;
2
3 void thread_fn(void) {
4     struct mcs_node_t n;
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```


 T_1

 T_2

 T_3

 queue

MCS Lock

Fairness & Overhead

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1 struct mcs_node_t {
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6 void lock(mcs_lock_t *l, mcs_node_t *cur) {
7     cur->next = NULL; cur->free = false;
8     auto prev = fetch_and_store(&(l->queue), cur);
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11         do {} while (!cur->free);
12     }
13 }
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 T_1 T_2 T_3

queue

MCS Lock

Fairness & Overhead

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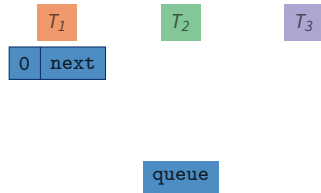
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MCS Lock

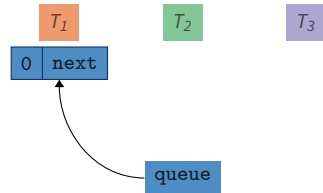
Fairness & Overhead

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MCS Lock

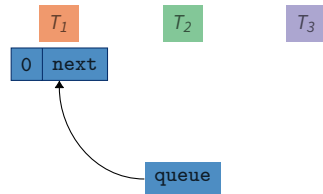
Fairness & Overhead

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MCS Lock

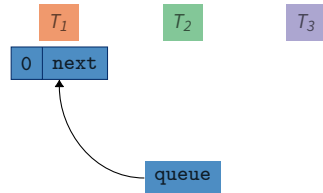
Fairness & Overhead

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MCS Lock

Fairness & Overhead

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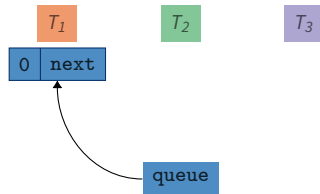
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MCS Lock

Fairness & Overhead

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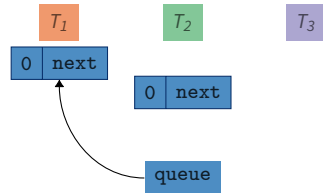
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MCS Lock

Fairness & Overhead

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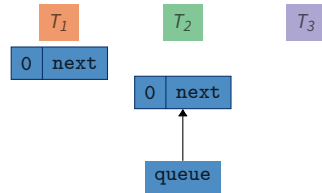
6 struct mcs_lock_t {
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8 };

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MCS Lock

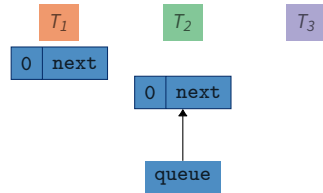
Fairness & Overhead

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MCS Lock

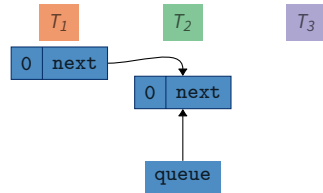
Fairness & Overhead

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MCS Lock

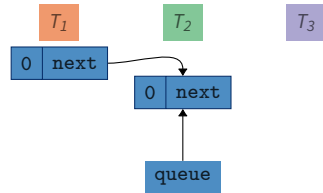
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MCS Lock

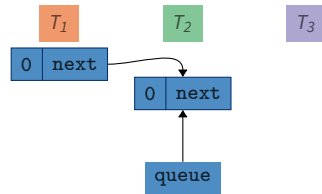
Fairness & Overhead

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MCS Lock

Fairness & Overhead

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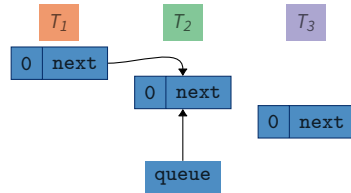
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MCS Lock

Fairness & Overhead

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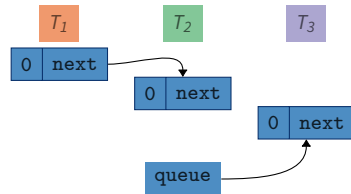
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MCS Lock

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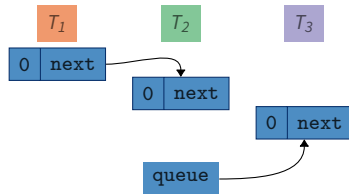
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MCS Lock

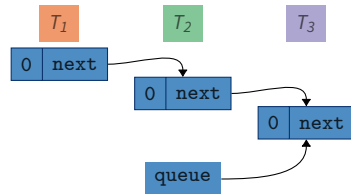
Fairness & Overhead

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MCS Lock

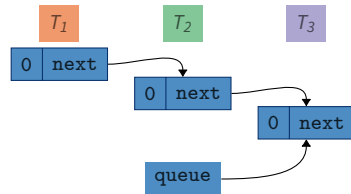
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MCS Lock

Fairness & Overhead

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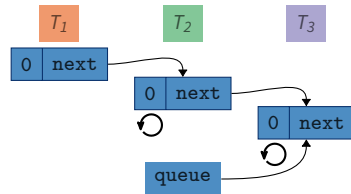
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MCS Lock

Fairness & Overhead

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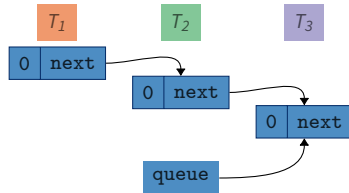
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MCS Lock

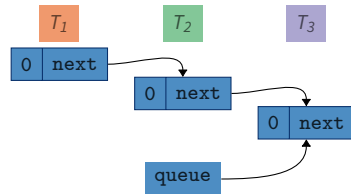
Fairness & Overhead

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MCS Lock

Fairness & Overhead

```

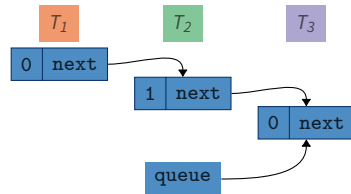
1 struct mcs_node_t {
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MCS Lock

Fairness & Overhead

```

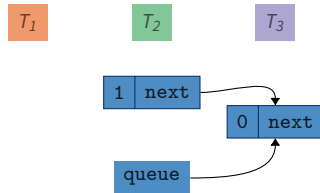
1 struct mcs_node_t {
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MCS Lock

Fairness & Overhead

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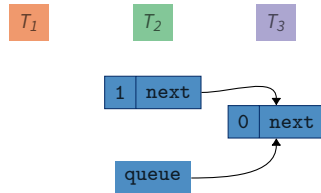
1 struct mcs_node_t {
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MCS Lock

Fairness & Overhead

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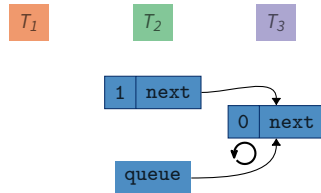
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MCS Lock

Fairness & Overhead

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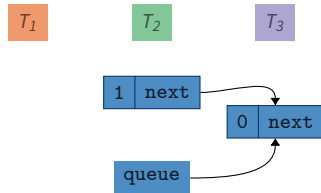
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MCS Lock

Fairness & Overhead

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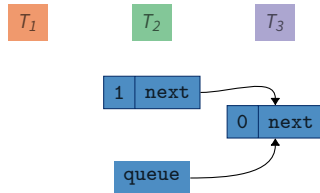
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MCS Lock

Fairness & Overhead

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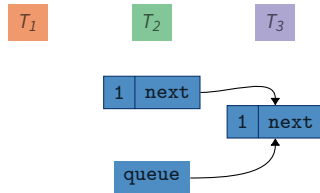
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MCS Lock

Fairness & Overhead

```

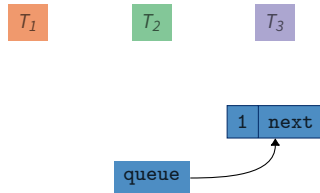
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MCS Lock

Fairness & Overhead

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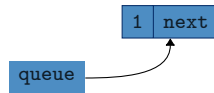
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 T_1

 T_2

 T_3


MCS Lock

Fairness & Overhead

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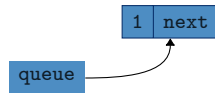
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 T_1

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 T_3


MCS Lock

Fairness & Overhead

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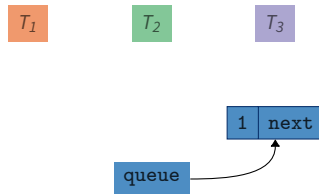
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MCS Lock

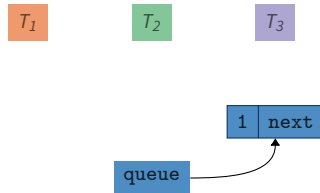
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Fairness & Overhead

MCS Lock

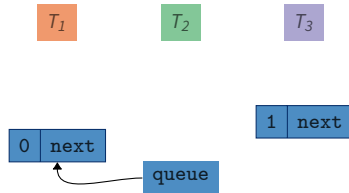
Fairness & Overhead

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MCS Lock

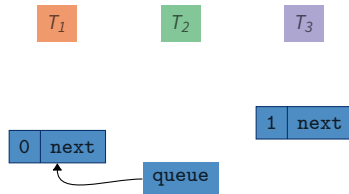
Fairness & Overhead

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MCS Lock

Fairness & Overhead

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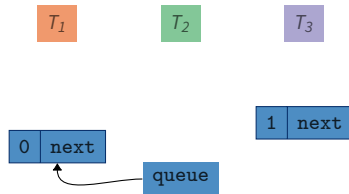
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MCS Lock

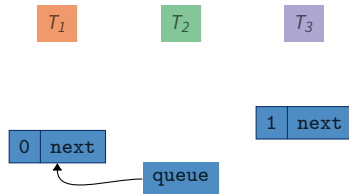
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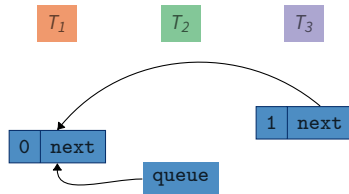
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MCS Lock

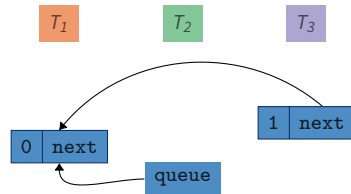
Fairness & Overhead

```

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2     mcs_node_t *next;
3     bool free;
4 };
5
6 void lock(mcs_lock_t *l, mcs_node_t *cur) {
7     cur->next = NULL; cur->free = false;
8     auto prev = fetch_and_store(&(l->queue), cur);
9     if (prev) {
10         prev->next = cur;
11         do {} while (!cur->free);
12     }
13 }
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18         do {} while (!cur->next);
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MCS Lock

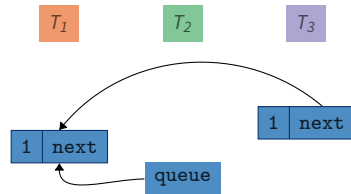
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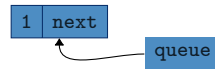
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 T_1

 T_2

 T_3


MCS Lock

Fairness & Overhead

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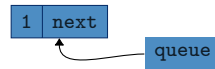
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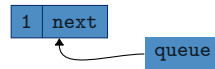
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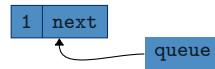
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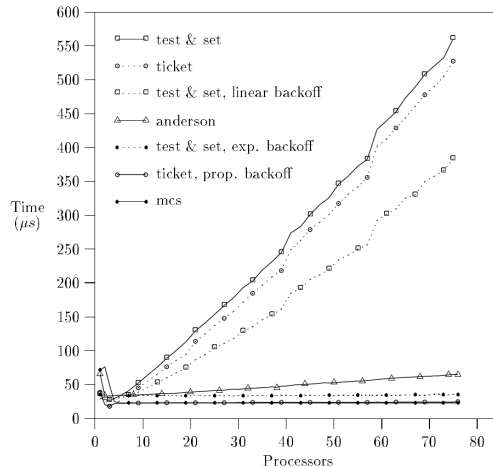
 T_2

 T_3

 queue

MCS Lock

Performance



MCS Lock

Performance

