# Escape

Nils Asmussen

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## Outline

- Introduction
- 2 Tasks
- Memory
- 4 VFS
- IPC
- 6 Security
- 7 UI

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### Motivation

### Beginning

- Writing an OS alone? That's way too much work!
- Port of UNIX32V to ECO32 during my studies
- Started with Escape in October 2008

#### Goals

- Learn about operating systems and related topics
- Experiment: What works well and what doesn't?
- What problems occur and how can they be solved?

### Overview

### **Basic Properties**

- UNIX-like microkernel-based OS
- Open source, available on github.com/Nils-TUD/Escape
- Mostly written in C++, some parts in C
- Runs on x86, x86\_64, ECO32 and MMIX
- Only third-party code: libgcc, libsupc++, x86emu, inflate

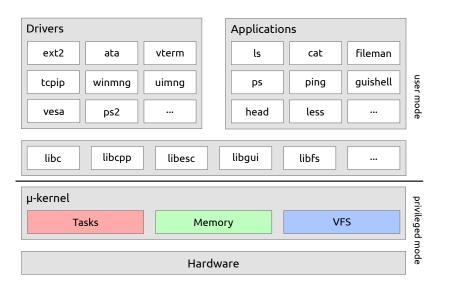
#### ECO32

MIPS-like, 32-bit big-endian RISC architecture, developed by Prof. Geisse for lectures and research

#### MMIX

64-bit big-endian RISC architecture of Donald Knuth as a successor for MIX (the abstract machine from TAOCP)

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 UI

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## Processes and Threads

#### **Process**

- Virtual address space
- File descriptors
- Mountspace
- Threads (at least one)
- . . .

#### Thread

- User and kernel stack
- State (running, ready, blocked, ...)
- Scheduled by a round-robin scheduler with priorities
- Signals
- . . .

### Processes and Threads

### Synchronization |

- Process-local semaphores (can also be created for interrupts)
- Global semaphores, named by a path to a file
- Userspace builds other synchronization primitives on top
  - Combination of atomic ops and process-local semaphores
  - Readers writer lock
  - . . .

### Priority Management

- Priorities are dynamically adjusted based on compute intensity
- High CPU usage  $\rightarrow$  downgrade, low CPU usage  $\rightarrow$  upgrade

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## Memory Management

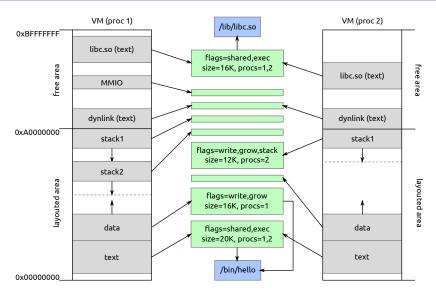
### Physical Memory

- Mostly, memory is managed by a stack (fast for single frames)
- A small part handled by a bitmap for contiguous phys. memory

### Virtual Memory

- Kernel part is shared among all processes
- User part is managed by a region-based concept
- mmap-like interface for the userspace

## Virtual Memory Management



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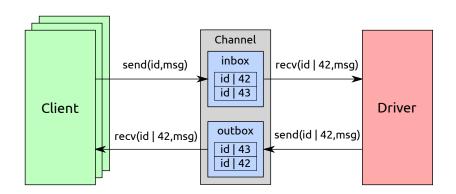
### **Basics**

- The kernel provides the virtual file system
- System-calls: open, read, mkdir, mount, ...
- It's used for:
  - Provide information about the state of the system
  - Access userspace filesystems
  - Access devices
  - Access interrupts

### **Drivers and Devices**

- Drivers are ordinary user programs
- They create devices via the system call createdev
- These are usually put into /dev
- Devices can also be used to implement on-demand-generated files (such as /sys/net/sockets)
- Communication is based on asynchronous message passing

# Message Passing



## Devices Can Behave Like Files

- As in UNIX: Devices should be accessable like files
- Messages: FILE\_OPEN, FILE\_READ, FILE\_WRITE, FILE\_CLOSE
- Devices may support a subset of these message
- Kernel handles communication for open/read/write/close
- Type of file transparent for applications

# Devices Can Behave Like Filesystems

- Messages: FS\_OPEN, FS\_READ, FS\_WRITE, FS\_CLOSE, FS\_STAT, FS\_SYNC, FS\_LINK, FS\_UNLINK, FS\_RENAME, FS\_MKDIR, FS\_RMDIR, FS\_CHMOD, FS\_CHOWN
- Kernel handles communication, if syscall refers to userspace fs
- Filesystems are mounted using the mount system call

# Achieving Higher Throughput

- Copying everything twice hurts for large amounts of data
- sharebuf establishes shmem between client and driver
- Easy to use: just call sharebuf once and use this as the buffer
- Clients don't need to care whether a driver supports it or not
- Drivers need to handle DEV\_SHFILE to support it
- In read/write, they check if SHM should be used

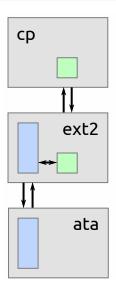
# Achieving Higher Throughput - Code Example

```
int fd = open("/dev/zero",O_READ);
static char buf[SIZE];
while(read(fd,buf,SIZE)) > 0) {
    // ...
}
close(fd);
```

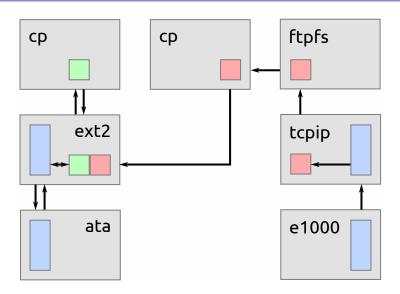
# Achieving Higher Throughput – Code Example

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# Achieving Higher Throughput – Usage Example



# Achieving Higher Throughput – Usage Example



# File Exchange

- Files (=capabilities) can be exchanged via channel
- Client can delegate/obtain files from driver:
  - int delegate(int chan, int fd, uint perm, int arg)
  - int obtain(int chan, int arg)
- Used for:
  - Establishing shared memory
  - Connecting control and event channel of uimng
  - Accepting incoming network connections (accept)
  - . . .

## File Descriptors For Everything

#### Interrupts

- Escape uses semaphores for interrupts
- For each interrupt, Escape creates a file /sys/irq/\$irq
- Syscall semirgert expects fd for IRQ file
- On an IRQ, all semaphores in the list are up'ed

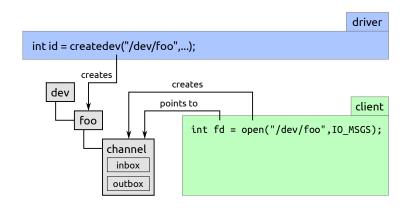
#### Signals

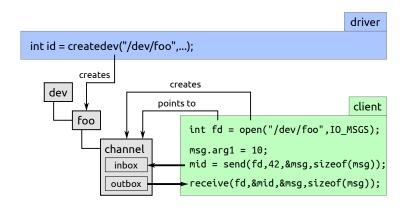
- The kill syscall expects fd for process directory
- Only if it has write permission, the signal can be sent

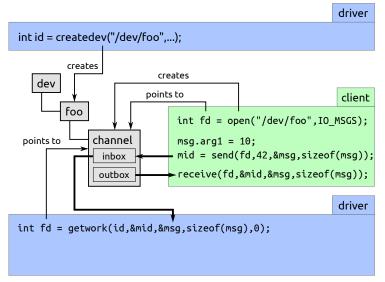
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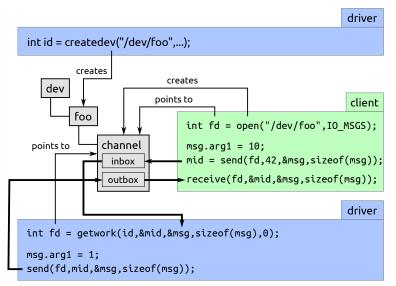
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## Driver Example: /dev/zero

```
struct ZeroDevice : public ClientDevice <> {
    explicit ZeroDevice(const char *name, mode_t mode)
        : Client Device (name . mode . DEV_TYPE_BLOCK . DEV_OPEN | DEV_DELEGATE |
              DEV_READ | DEV_CLOSE) {
        set (MSG_FILE_READ, std:: make_memfun(this,&ZeroDevice:: read));
    void read(IPCStream &is) {
        static char zeros[BUF_SIZE];
        Client *c = get(is.fd());
        FileRead::Request r;
        is \gg r;
        if (r.shmemoff != -1)
            memset(c->shm() + r.shmemoff,0,r.count);
        is << FileRead::Response(r.count) << Reply();
        if (r.shmemoff == -1 \&\& r.count)
            is << ReplyData(zeros, r.count);
};
int main() {
    ZeroDevice dev("/dev/zero",0400);
    dev.loop();
    return EXIT_SUCCESS;
```

## Client Example: vterm

```
// get console-size
ipc::VTerm vterm(std::env::get("TERM").c.str());
ipc::Screen::Mode mode = vterm.getMode();

// implementation of vterm.getMode():
Mode getMode() {
    Mode mode;
    int res;
        is << SendReceive(MSG_SCR_GETMODE) >> res >> mode;
    if(res < 0)
        VTHROWE("getMode()",res);
    return mode;
}</pre>
```

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#### General Idea

### Goals

- Keep the powerful and convenient UNIX concepts
- Improve the security, reliability and maintainability

### Approach

- Structure it as a microkernel-based system
- Permissions can only be downgraded (e.g., no setuid)
- Mountspace as a first layer: control entire subtrees
- ACL as a second layer: control at file-level

# Mountspaces

- Every process has a mountspace, inherited to childs
- Mountspace is represented as a directory
- Child mountspaces become child directories
- Changing a mountspace requires write permission
- ullet Mountspace translates: path o (FS, perm, subpath)
- perm defines upperbound for files in subpath
- Can be done by unprivileged users
  - Filesystems and drivers run in userspace
  - ... with the user+group of the mounter
  - Overmounting system directories is no security issue

## Mounting for the User

#### Tools

- mount creates a new FS for a device and makes it visible
  - \$ mount /dev/hda1 /mnt /sbin/ext2
- bind makes an existing FS visible at a different place
  - \$ bind /dev/ext2-hda1 /home/me/mnt

#### What does bind do?

```
int fs = open("/dev/ext2-hda1", ...);
int ms = open("/sys/pid/self/ms", O_WRITE);
mount(ms, fs, "/home/me/mnt");
// open("/home/me/mnt/a/b", ...) -> FS_OPEN("/a/b")
```

### Sandbox

### Reasoning

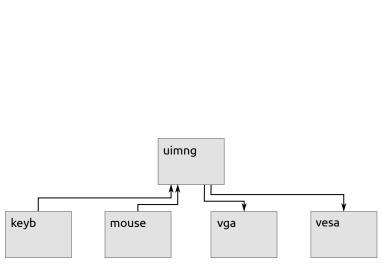
- Some applications are not trusted
- Running them as a different user is inconvenient
- Instead: run with same user, but less permissions

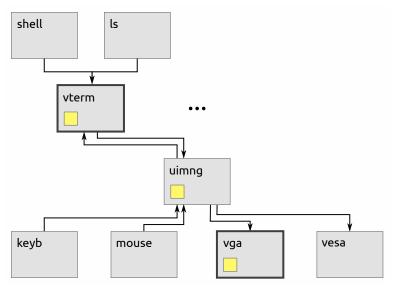
#### The sandbox tool

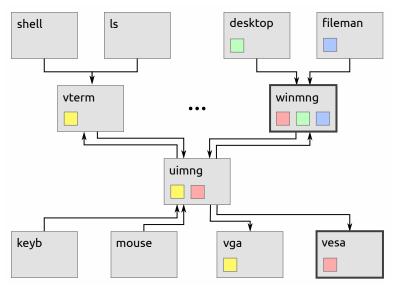
- Allows to leave groups
- Allows to reduce permissions to entire subtrees
- Example: sandbox -g netuser -m /home:r app
- Sandboxes can be nested and used by unprivileged users

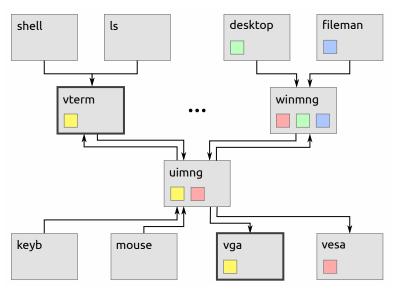
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## Questions

Get the code, ISO images, etc. on: https://github.com/Nils-TUD/Escape

Questions?