TECHNISCHE UNIVERSITÄT DRESDEN

Fakultät Informatik Institut für Systemarchitektur, Professur für Betriebssysteme

OPERATING-SYSTEM CONSTRUCTION

Material based on slides by Olaf Spinczyk, Universität Osnabrück

Exercise 2: C++ (2), Keyboard, Interrupts

https://tud.de/inf/os/studium/vorlesungen/betriebssystembau

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Overview

- **C++ Crash Course (Part 2)**
- Lab Task #1: Keyboard
- Interrupts on x86: PIC
- Lab Task #2: Interrupt Handling

More C++ Concepts (Crash Course Part 2)

- Compiling and Linking
- Preprocessor
- Inheritance and Multiple Inheritance
- Virtual Functions

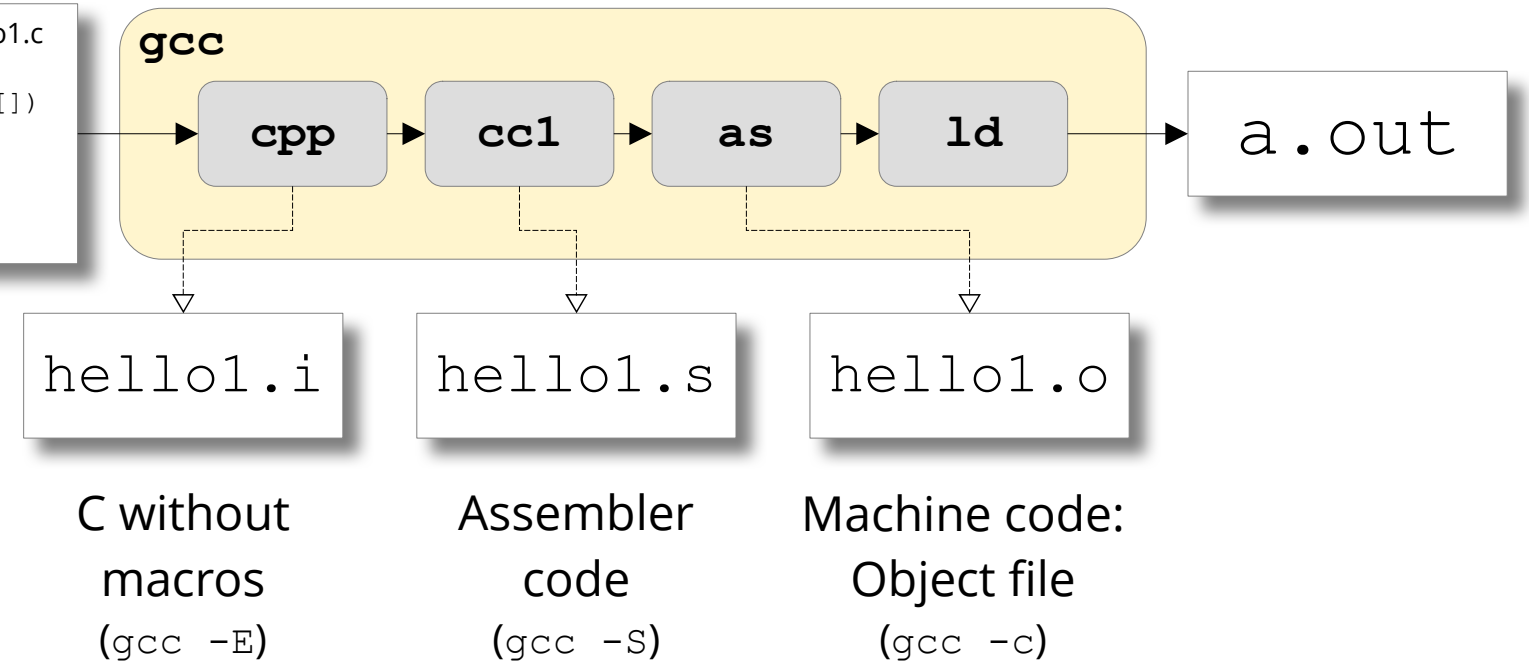
C/C++ Build Process

- Preprocessing, compilation, assembly and linkage in one step: **`gcc hello1.c`**
  - Generates file **`a.out`**
    (name can be changed with parameter `-o`)

hello1.c

```c
#include <stdio.h>

int main(int argc, char *argv[])
{
   printf("Hello World\n");
   return 0;
}
```



Source Code – Preprocessor

- Two file extensions:
  - .cc — C++ source code
  - .h — „Header Files“ with definitions of data types, constants, preprocessor macros etc.
- File extensions are only convention, variants:
  - .C, .cpp, .cxx, .hpp, .hh
- The preprocessor textually “integrates” header files in .cc files
  - #include directive:
    - #include <iostream> for system headers
    - #include "device.h" for own header files
  - Modern alternative: C++20 modules

Source Code – Preprocessor

- More preprocessor functionality:
  - Macros, e.g. for constants (*without* semicolon!)

```
#define pi 3.1415926
#define VGA_BASE 0xb8000
```

  - Conditional compilation:

```
#ifdef DEBUG
…
#endif
```

```
#ifndef VGA_BASE
#define VGA_BASE 0xb8000
#endif
```

- The preprocessor **expands macros**, integrates **header-file contents**, and generates a **new text file** (.i) as compiler input.

Source Code – Preprocessor

- Important use-case for #define and #ifndef:
  - Header files may include other header files → infinite recursion possible!
  - Preventing repeated inclusion of header files:

```
#ifndef __cgastr_include__
#define __cgastr_include__

#include "object/o_stream.h"
#include "machine/cgascr.h"

class CGA_Stream
/* Add your code here */
{
/* Add your code here */
};
#endif
```

Source Code – Compiler

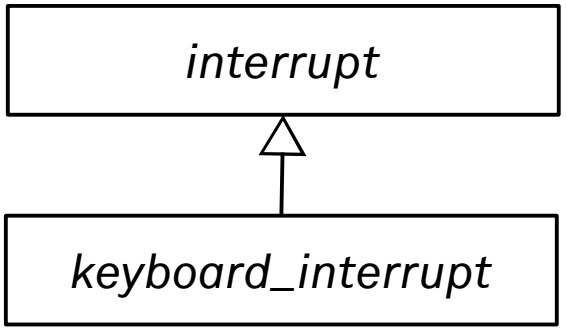
- Generates an object file (.o) from preprocessed source code
  - Generally **not directly executable**: unresolved references to functions or variables from other object files
- Checks code for syntactic and semantic correctness, may
  - … abort compilation and print an **error** message *(errors)*
  - … emit **warnings** that could be a sign of a problem
  - Warnings do not abort compilation, but do not ignore them!

Source Code – Linker

- Links a set of object files (.o) and possibly libraries (.a, .so) to an executable binary:
  - Resolve references
  - Sort/group object-file parts/sections in memory map of executable
- Two linking modes:
  - **dynamic:** Libraries are loaded when starting the program, reference resolution at start- or even at runtime (“lazy linkage”)
  - **static:** Libraries are linked at link/build time, yielding a completely linked “static” binary containing all external dependencies.

Single Inheritance

- Class *keyboard_interrupt* inherits from class *interrupt*
- Inheritance operator ":" (like "extends" in Java)



interrupt.h:

```
class interrupt {
  …
};
```

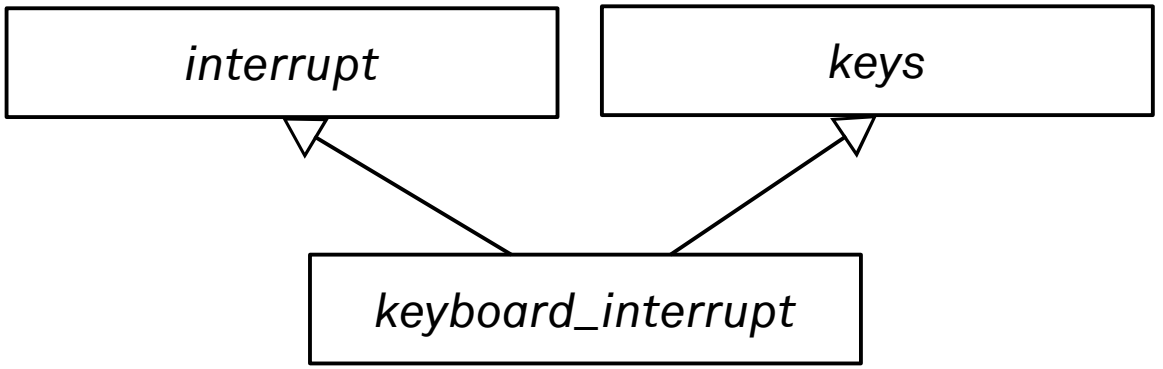
keyboard_interrupt.h:

```
#include "interrupt.h"

class keyboard_interrupt : public interrupt {
public:
  keyboard_interrupt();
  ~keyboard_interrupt();
};
```

Multiple Inheritance

- Class *keyboard_interrupt* inherits from classes *interrupt* **and** *keys*:



keyboard_interrupt.h:

```
#include "interrupt.h"

class keyboard_interrupt : public interrupt, public keys {
public:
  keyboard_interrupt();
  ~keyboard_interrupt();
};
```

Virtual Functions

- Specially “marked” function of a base class (keyword: `virtual`)
- Derived class may **override** it, thereby providing a **specialized implementation** for its instances
  (however, this also works with non-virtual functions)
- For classes with ≥1 virtual functions, each object “knows” from which class in the hierarchy it was instantiated
  → correct function gets called in polymorphic scenarios
- **Not every function is virtual** by default (unlike in Java)

Virtual Functions

- Output:

  ”Derived”

- without **virtual** in front of void base::display():

  ”Base”

```
#include <iostream>

class base {
public:
  virtual void display() {
    cout << "Base";
  }
};

class derived : public base {
public:
  void display() {
    cout << "Derived";
  }
};

void main() {
  base *ptr = new derived;
  ptr->display();
}
```

Virtual Destructors

- **Rule of thumb:** A class with a **virtual function** should also have a **virtual destructor**
  - A **non-virtual destructor** does not guarantee correct destruction of derived classes.
    (If one exists anyways, this can even be interpreted such that its author didn't intend (and doesn't recommend) deriving from this class.)

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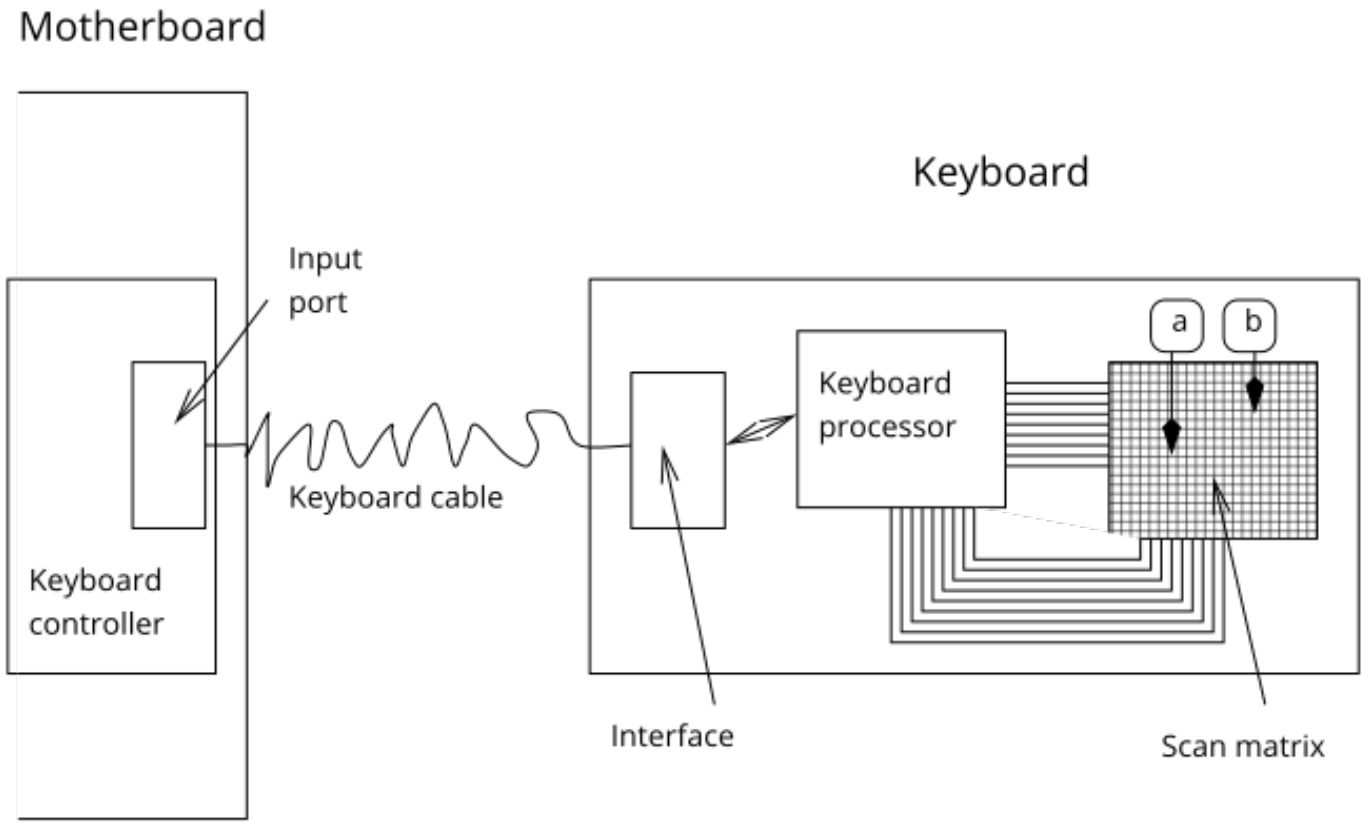
PC Keyboard

- classic:



- modern PC: USB keyboard
  - *USB Legacy Support*: Programming still also works via keyboard controller (backwards compatibility)

Key Encoding

- Each key has unique code (“Scan code”)
  - 7-bit number (max. 128 keys)

Representation in applications (and in CGA video memory!): Character codes (ASCII)

Character	ASCII code
(	40
0	48
1	49
2	50
A	65
B	66
a	97

Representation in keyboard hardware: Key codes

Key	Scancode
A	30
S	31
D	32
Cursor up	72
Cursor down	80

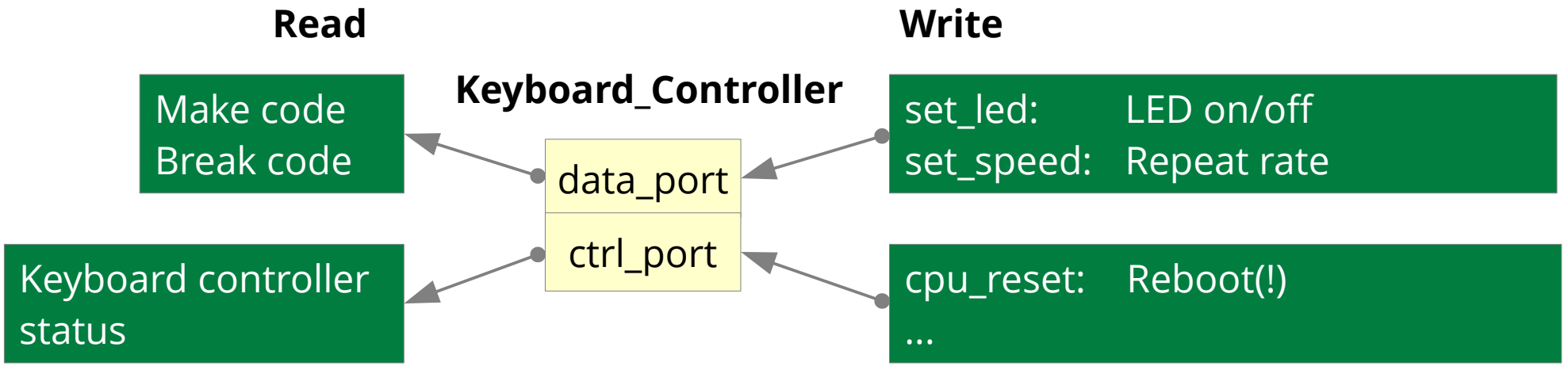
- Keyboard sends additional information
  - *Make Code* when pressing / while holding a key
  - *Break Code* when releasing a key

Make and Break Codes

- General system:
  - Make code (key pressed) = Scan code
  - Break code (key released) = Scan code + 128 (Bit 7)
- Some keys send **more than one code**
  - e.g. function keys (F1–F12)
  - … for historic reasons (XT keyboard)
  - up to 3 make/break codes per key
- Built-in **repeat** functionality
  - Hardware sends additional make codes while holding a key
- ➔ Decoding is cumbersome
  - already implemented in OOStuBS template: **bool** *key_decoded*()

Communication with Keyboard

- Keyboard controller: two I/O ports
  - Input/output register (data_port) **0x60**
  - Control register (ctrl_port) **0x64**



Keyboard-Controller Status

- Status register:

Bit	Mask	Name	Meaning
0	0x01	outb	Set to 1 when a character is ready to be read from the output buffer of the keyboard controller
1	0x02	inpb	Set to 1 as long as the keyboard controller has not yet fetched a character written by the CPU
5	0x20	auxb	Source of the value in the output buffer (0 = keyboard, 1 = mouse)

Keyboard-Controller Status – Usage

Bit	Mask	Name	Meaning
0	0x01	outb	Set to 1 when a character is ready to be read from the output buffer of the keyboard controller
1	0x02	inpb	Set to 1 as long as the keyboard controller has not yet fetched a character written by the CPU
5	0x20	auxb	Source of the value in the output buffer (0 = keyboard, 1 = mouse)

- Active keyboard polling (without interrupts):
  - Wait until **outb** in ctrl_port is set (1)
  - Read *Make/Break* code from data_port (clears ctrl_port.**outb**)
- Program keyboard (set_led, set_speed)
  - Write **command byte** to data_port
  - Keyboard replies with **ACK** (0xfa), need to wait for this reply (see above)
  - Write **data byte** to data_port (LED codes, repeat rate)
  - Keyboard replies with **ACK**, need to wait for this reply

Keyboard Programming

- set_led **0xed**, <led_mask> in data_port
- set_speed **0xf3**, <config_byte> in data_port

Parameter for **set_led** command: (led_mask)

MSB							LSB
Always 0	Always 0	Always 0	Always 0	Always 0	Caps Lock	Num Lock	Scroll Lock

Parameter for **set_speed** command: (config_byte)

Bits 5 and 6 (hex)	Delay (in seconds)
0x00	0.25
0x01	0.5
0x02	0.75
0x03	1.0

Bits 0–4 (hex)	Repeat rate (characters per second)
0x00	30
0x02	25
0x04	20
0x08	15
0x0c	10
0x10	7
0x14	5

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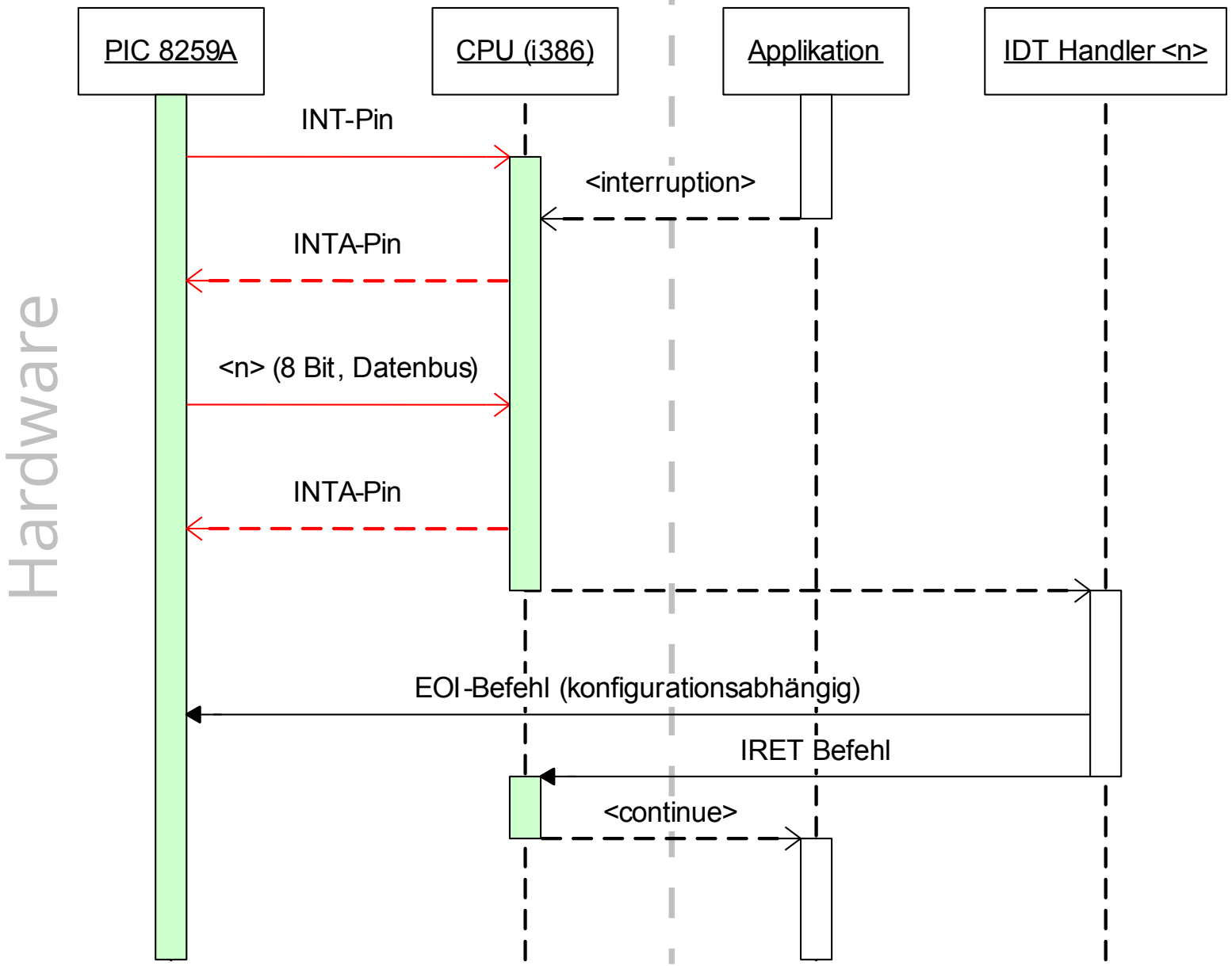
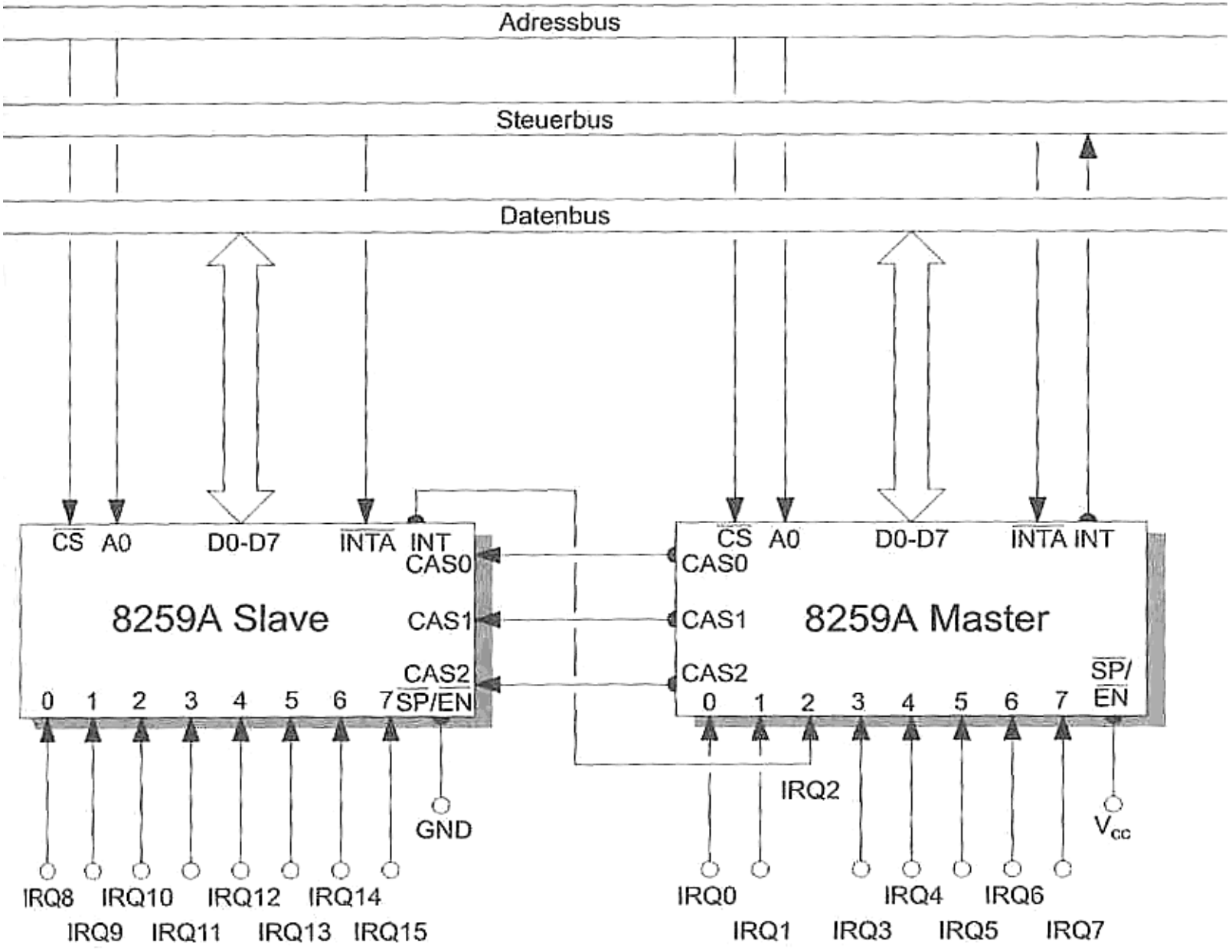
Hardware IRQs on x86 CPUs

- x86 CPUs up to and including i486:
  only one interrupt line (INT) + one NMI line
  - INT can be masked with IE bit in EFLAGS register
    - `cli` instruction (clear interrupt enable flag) – **disable interrupt handling**
    - `sti` instruction (set interrupt enable flag) – **enable interrupt handling**
  - NMI cannot be masked in the CPU (“non-maskable interrupt”)
    - … PC still allows this via CPU-external hardware …
- External controller puts IRQ number on memory bus
  - PC: **Programmable Interrupt Controller** (PIC) 8259A
  - Communication protocol between CPU and PIC 8259A

Hardware IRQ Sequence (with PIC)

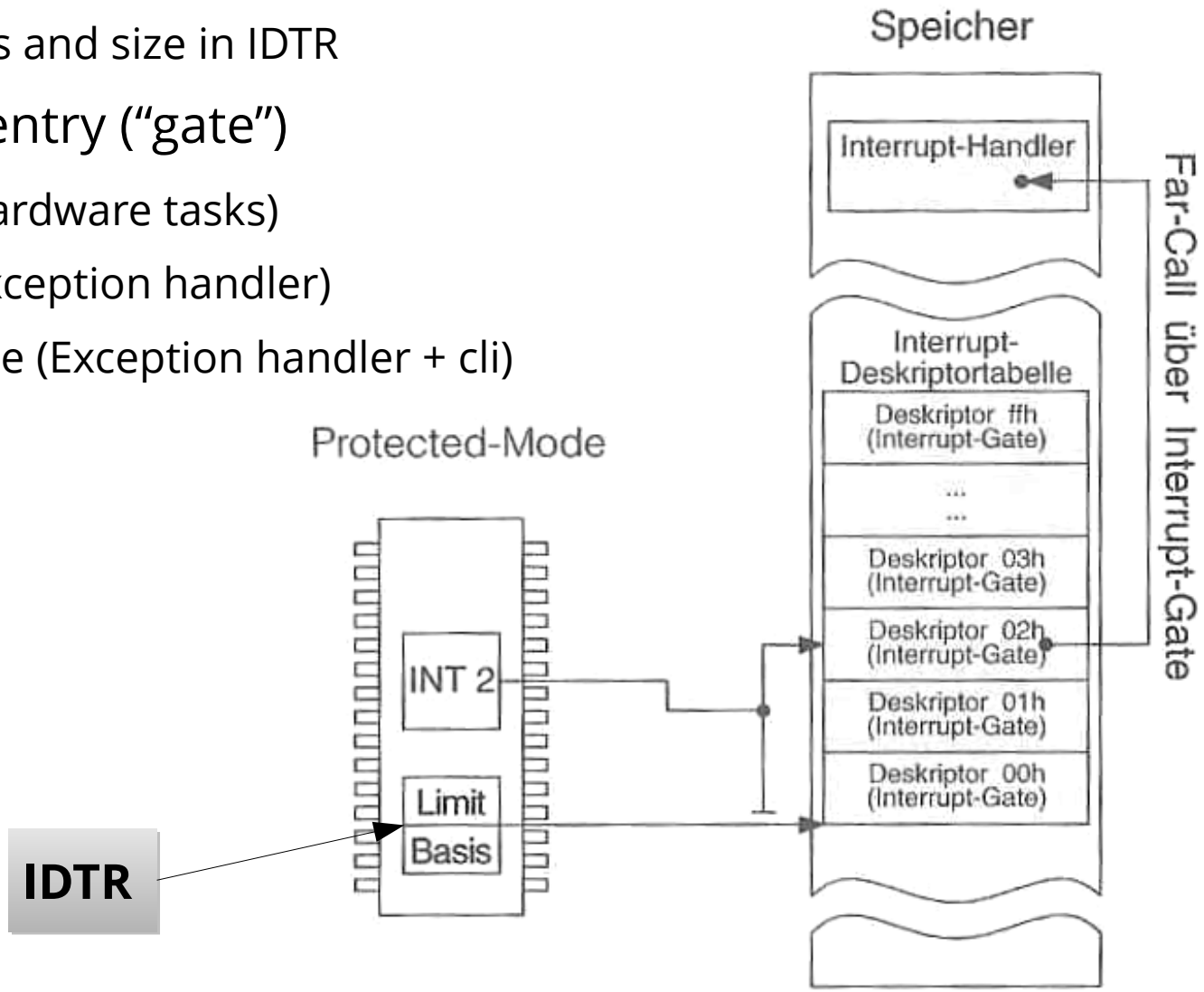


PIC Cascading in the PC (15 Interrupts)

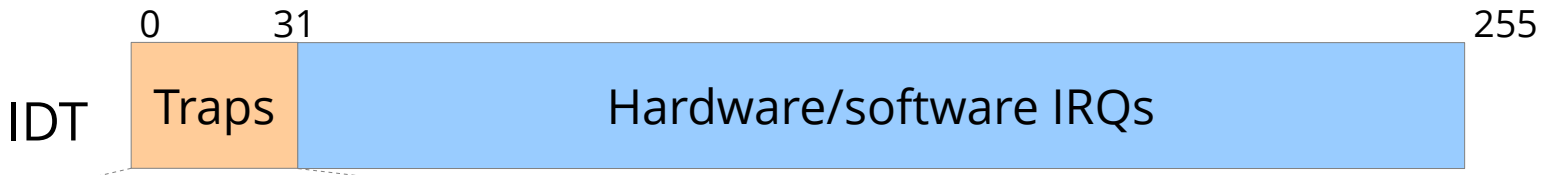


x86-64 Interrupt Descriptor Table

- max. 256 entries
  - Base address and size in IDTR
- 16 bytes per entry (“gate”)
  - Task gate (Hardware tasks)
  - Trap gate (Exception handler)
  - Interrupt gate (Exception handler + cli)



x86 IDT: Structure

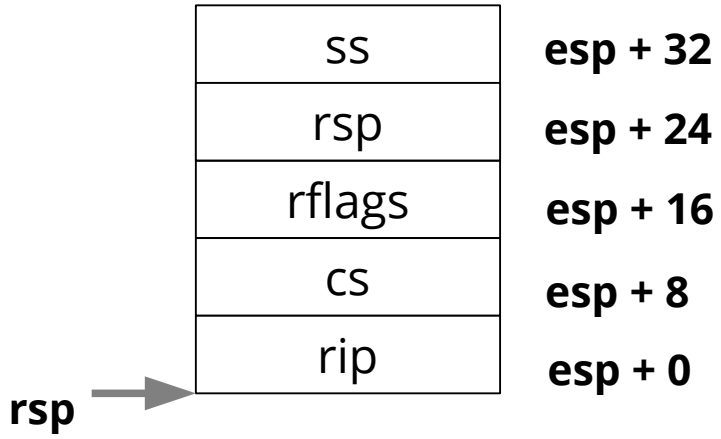


Number	Description
0	Divide-by-zero
1	Debug exception
2	Non-Maskable Interrupt (NMI)
3	Breakpoint (INT 3)
4	Overflow
5	Bound exception
6	Invalid Opcode
7	FPU not available
8	Double Fault
9	Coprocessor Segment Overrun
10	Invalid TSS
11	Segment not present
12	Stack exception
13	General Protection
14	Page fault
15	Reserved
16	Floating-point error
17	Alignment Check
18	Machine Check
19-31	Reserved By Intel

- Entries 0–31 for traps (fixed)
- Trap = Exception that occurs synchronously to control flow
  - Division by 0
  - Page fault
  - Breakpoint
  - …
- Entries 32–255 for IRQs (configurable)
  - Software (`INT` <number>)
  - Hardware (CPU's INT pin to HIGH, #number on data bus)

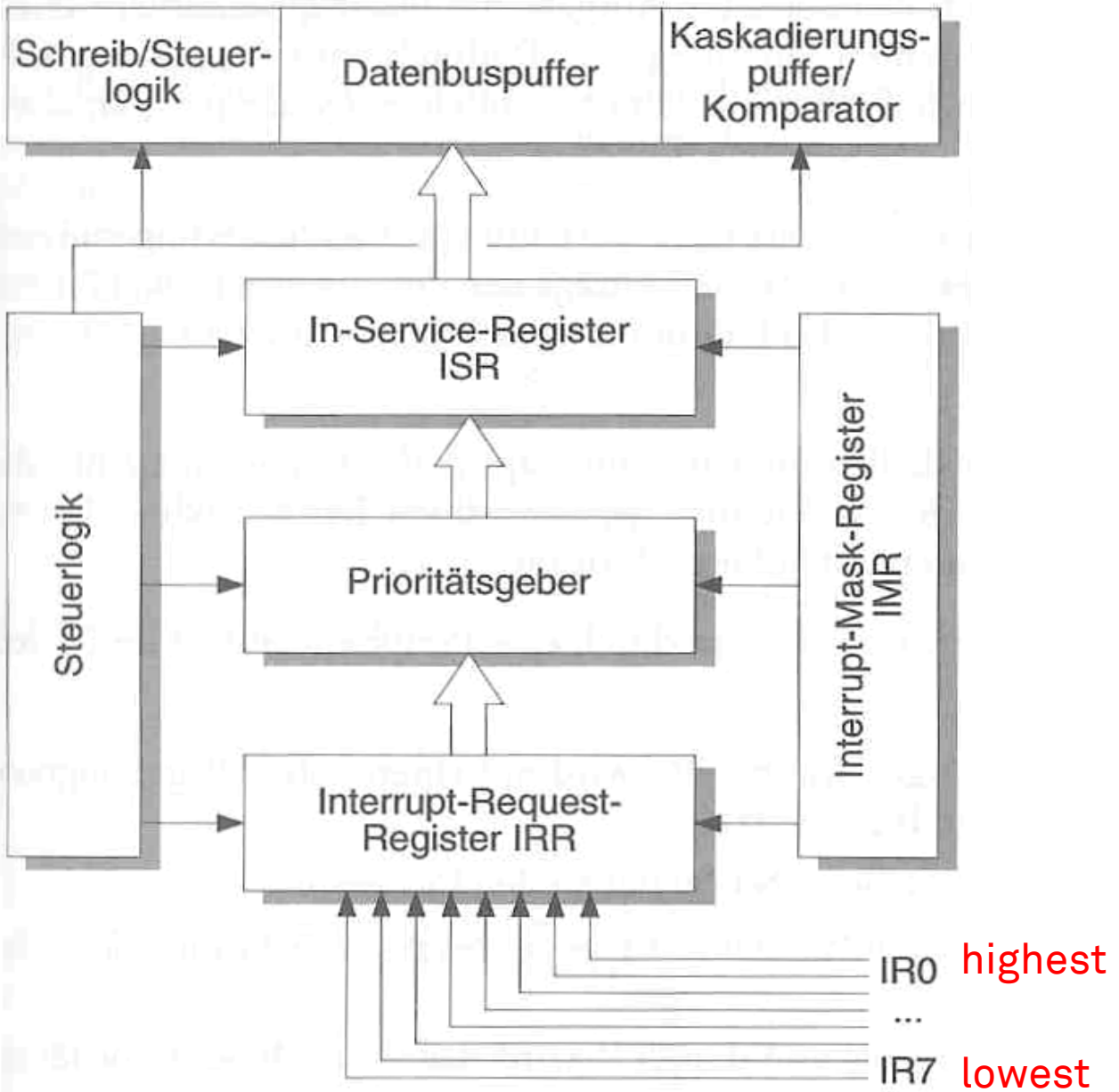
State Saving

- When an interrupt occurs, the CPU **automatically saves a part of its state** on the stack
  - Active stack segment (ss)
  - Stack pointer (rsp)
  - Condition codes (rflags)
  - Active code segment (cs)
  - Return address (rip)
  - For some exceptions (="traps"): additionally an error code (8 bytes)



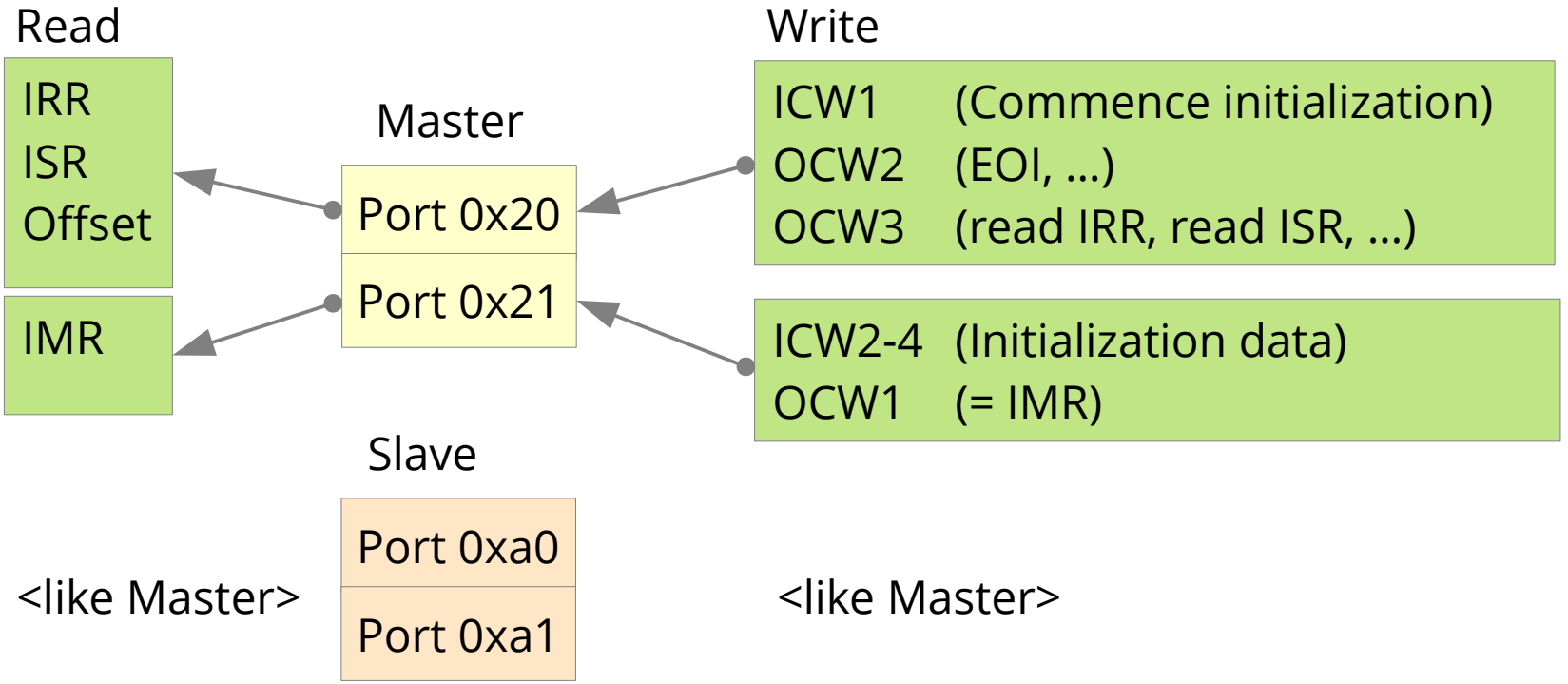
- Automatically saved state is restored by `iretq` instruction
  - If handler uses other registers, it **must save/restore them by itself**!

PIC 8259A – Internal Structure



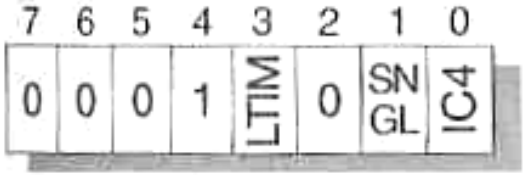
Accessing PICs via I/O Ports

- Each PIC has 2 ports that can be read/written
- Data that can be written: ICW1–4, OCW1–3
  - ICW = **Initialization Control Word** – PIC initialization
  - OCW = **Operation Control Word** – Commands during operation
- Read data depends on command



PIC Initialization – Part 1

ICW1

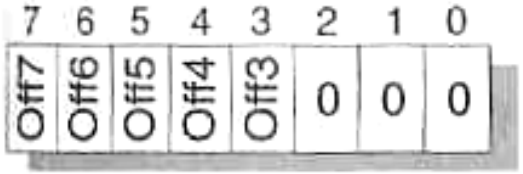


LTIM: 0=Flankentriggerug 1=Pegeltriggerung
SNGL: 0=kaskadierte PICs 1=nur Master
IC4: 0=kein ICW4 1=ICW4 notwendig

OOStuBS setting:

Master	Slave
00010001	00010001

ICW2



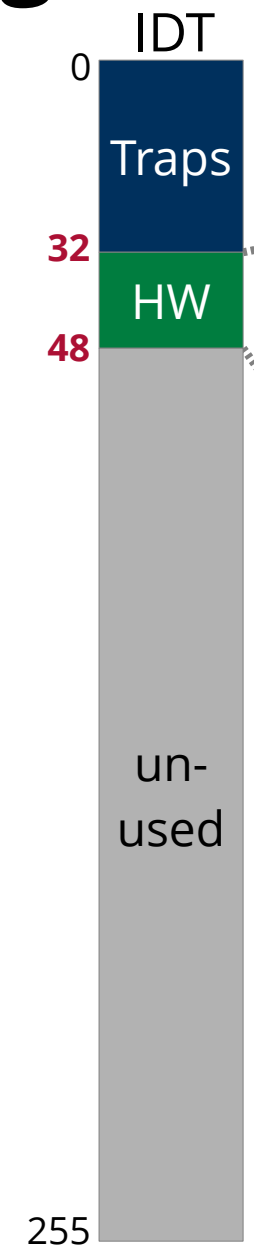
Off7..Off3: programmierbarer Offset des Interrupt-Vektors

OOStuBS setting:

Master	Slave
00100000	00101000
=32	=40

Mapping of HW IRQs (OOStuBS)

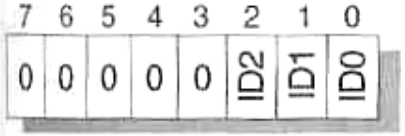
Standard AT IRQ mapping



IRQ	Description
0	Programmable Interrupt Timer (PIT)
1	Keyboard
2	(PIC Cascade)
3	COM2
4	COM1
5	LPT2
6	Floppy-Disk Drive
7	LPT1 / spurious interrupt
8	CMOS Real-Time Clock
9	
10	
11	
12	PS/2 Mouse
13	FPU / Coprocessor / Inter-Processor
14	Primary ATA HDD
15	Secondary ATA HDD

PIC Initialization – Part 2

ICW3 (Slave)



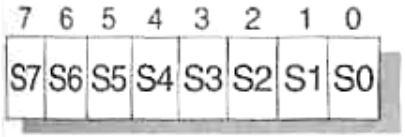
ID2..ID0: Identifizierungsnummer des Slave-PIC

OOStuBS setting:

Master	Slave
00000100	0000010

IRQ 2 → Slave **ID 2**

ICW3 (Master)

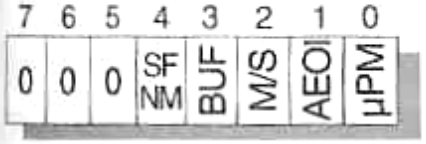


S7..S0: 0=zugehörige IR-Leitung ist mit Peripheriegerät verbunden oder frei
1=zugehörige IR-Leitung ist mit Slave-PIC verbunden

OOStuBS setting:

Master	Slave
00000011	00000011

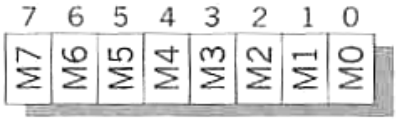
ICW4



SFNM:	0=kein Special-Fully-Nested-Modus	1=Special-Fully-Nested-Modus
BUF:	0=kein gepufferter Modus	1=gepufferter Modus
M/S:	0=Slave-PIC	1=Master-PIC
AEOI:	0=manueller EOI	1=automatischer EOI
µPM:	0=Betrieb im MCS-80/85-Modus	1=Betrieb im 8086/88-Modus

PIC Programming

OCW1



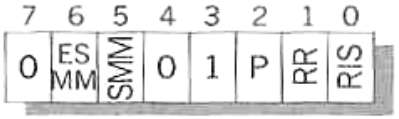
M7..M0: 0=zugehörige IRQ-Leitung ist nicht maskiert
1=zugehörige IRQ-Leitung ist maskiert

Interrupt mask (IMR)
- read and write via Port 0x21 / 0xa1

OCW2

000: im AEOI-Modus rotieren
001: nicht-spezifischer EOI-Befehl
010: kein Vorgang (NOP)
011: spezifischer EOI-Befehl (mit L2..L0)
100: im AEOI-Set-Modus rotieren
101: bei nicht-spezifischem EOI-Befehl rotieren
110: Prioritätsbefehl setzn
111: bei spezifischem EOI-Befehl rotieren

OCW3



ESMM, SMM:	00=kein Vorgang (NOP)	01=kein Vorgang (NOP)
	10=spez. Maske löschen	11=spez. Maske setzen
RR, RIS:	00=kein Vorgang (NOP)	01=kein Vorgang (NOP)
	10=IRR lesen	11=ISR lesen
P:	Polling: 0=kein Polling	1=Polling-Modus

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Interrupt Handler in OOStuBS

- Interrupt handling starts in **`guardian()`** function
  - Parameter **`slot`**: IRQ number

```
void guardian( unsigned int slot ) {
  ... // call IRQ handler (Gate object)
}
```

  - During interrupt handling, interrupts are disabled
    - Can be manually re-enabled via **`sti`** (wrapped in **`CPU::enable_int()`**)
    - Automatically re-enabled when **`guardian()`** returns
- Actual (IRQ-specific) IRQ handlers
  - are instances of class Gate
  - are registered/unregistered in class Plugbox

Interrupt Handler in OOStuBS