# Impossibility Results for Distributed Transactional Memory

Paper Reading Group

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### Table of Contents

Introduction

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## Distributed transctional memory

- Distributed system
- Set of objects
- Gather all objects

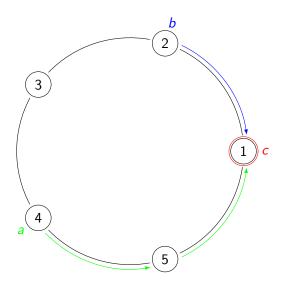
# Types of transactional memory

- Data-flow
- Control-flow
- Hybrid-flow

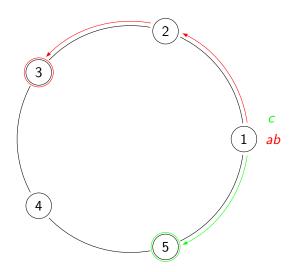
## System model

- Data-flow based implementation
- Network graph
- Instantaneous transaction
- Atomic receive-compute-send
- All delays are equal
- Single copies
- One transaction per node

# Transactions and objects



# Several transactions on the same objects



#### Evaluated network

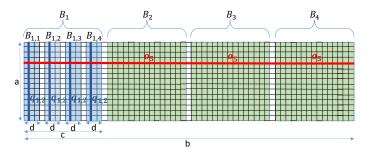


Figure 1: The graph G for the time-communication impossibility result, with  $a=c=16,\,b=64,\,d=4,$  and  $\gamma=\delta=4.$ 

## Transaction scheduling

In this schedule the transactions in G execute sequentially, one after another, in a column by column way starting from the leftmost column of G up to the rightmost column. All transactions in column j finish execution before the transactions in column j+1 start execution.

#### Communication costs

For a set of transactions  $\mathcal T$  in graph G, the communication cost of an execution  $\mathcal E$  is the sum of the traversed path lengths of all messages sent during  $\mathcal E$ . The communication cost of scheduling algorithm A is the maximum communication cost over all possible executions for  $\mathcal T$ 

#### Execution time

For a set of transactions  $\mathcal T$  in graph G, the time of an execution  $\mathcal E$  is the time elapsed until the last transaction finishes its execution in  $\mathcal E$ . The execution time of scheduling algorithm A is the maximum time over all possible executions for  $\mathcal T$ .

## Impossibility Result

in this instance it is impossible to simultaneously optimize execution time and communication cost

If one optimizes for lower communication costs, one pays with higher execution time. And vice versa.

#### Positive result

We give algorithms which minimize independently the communication cost or execution time in an arbitrary graph G.

#### Small communication costs

The problem of minimizing the communication cost is NP-hard, by a reduction from graph TSP.

Given a graph G, we can approximate the optimal communication cost using a universal TSP tour.

#### Small execution time

We will reduce the vertex coloring problem to this problem. The coloring problem aims at finding the chromatic number  $\chi(H)$  of a graph H, and it is an NP-hard problem.

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